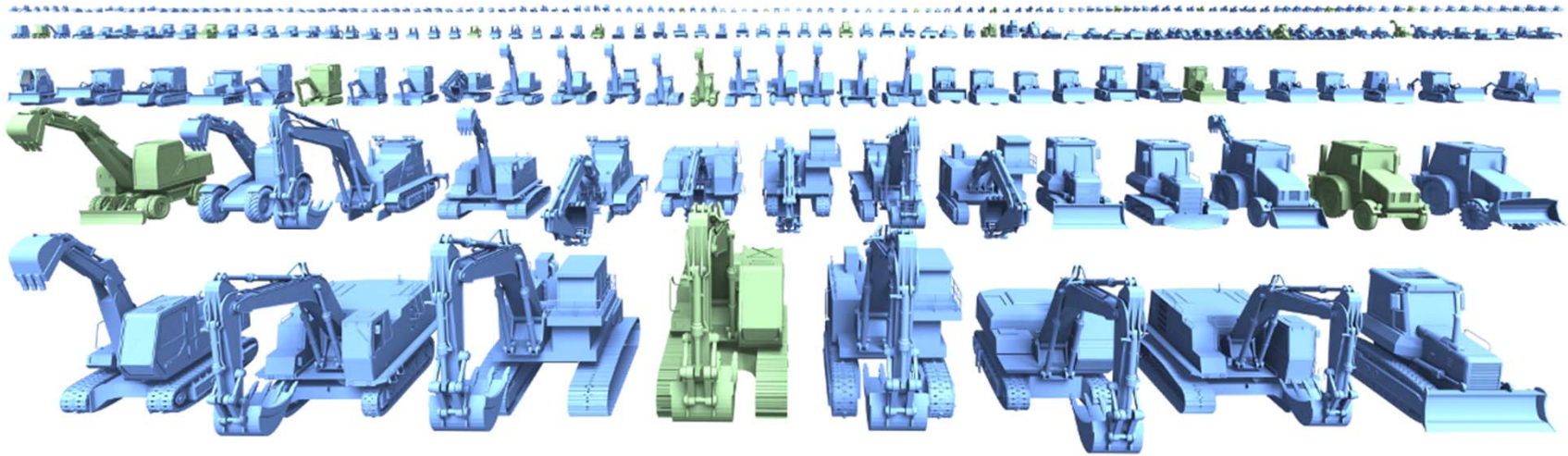


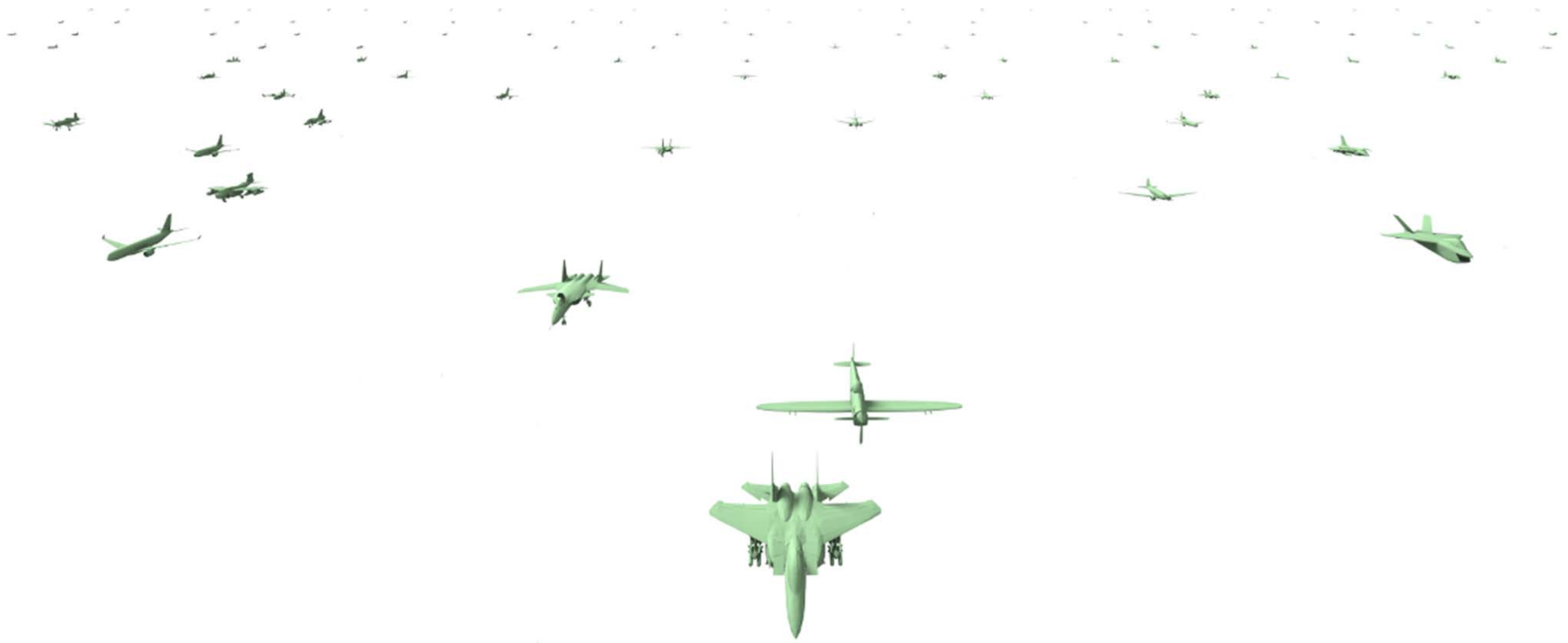
# A Probabilistic Model for Component-Based Shape Synthesis



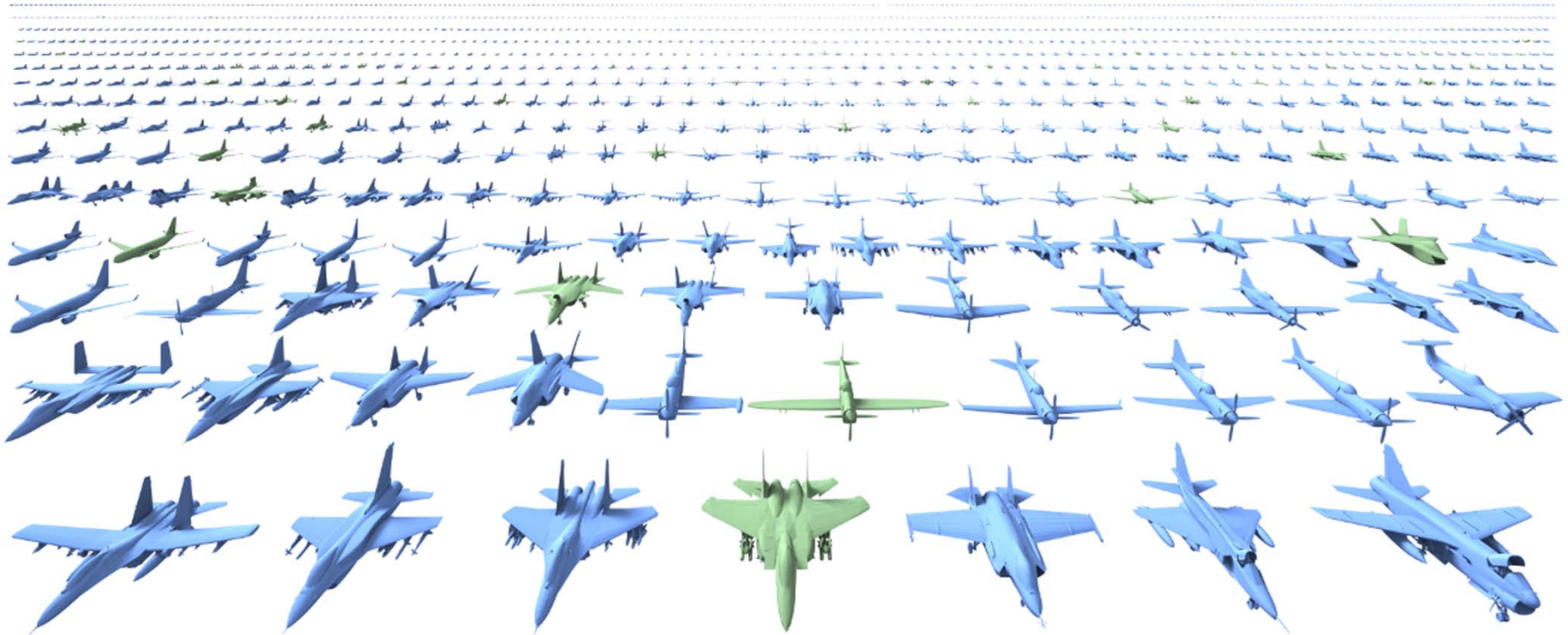
Evangelos Kalogerakis, Siddhartha Chaudhuri,  
Daphne Koller, Vladlen Koltun

Stanford University

Goal: generative model of shape

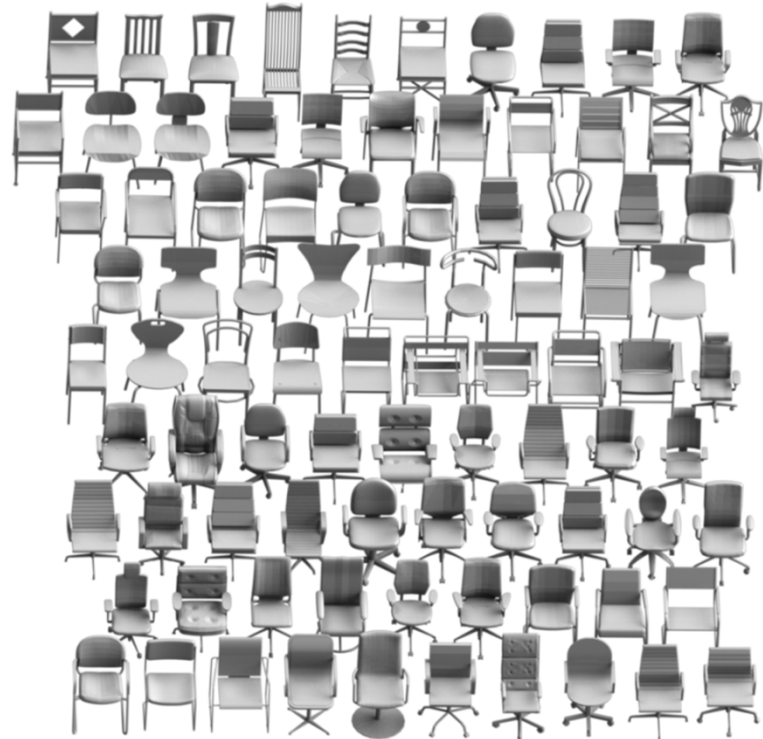


Goal: generative model of shape



# Challenge: understand shape variability

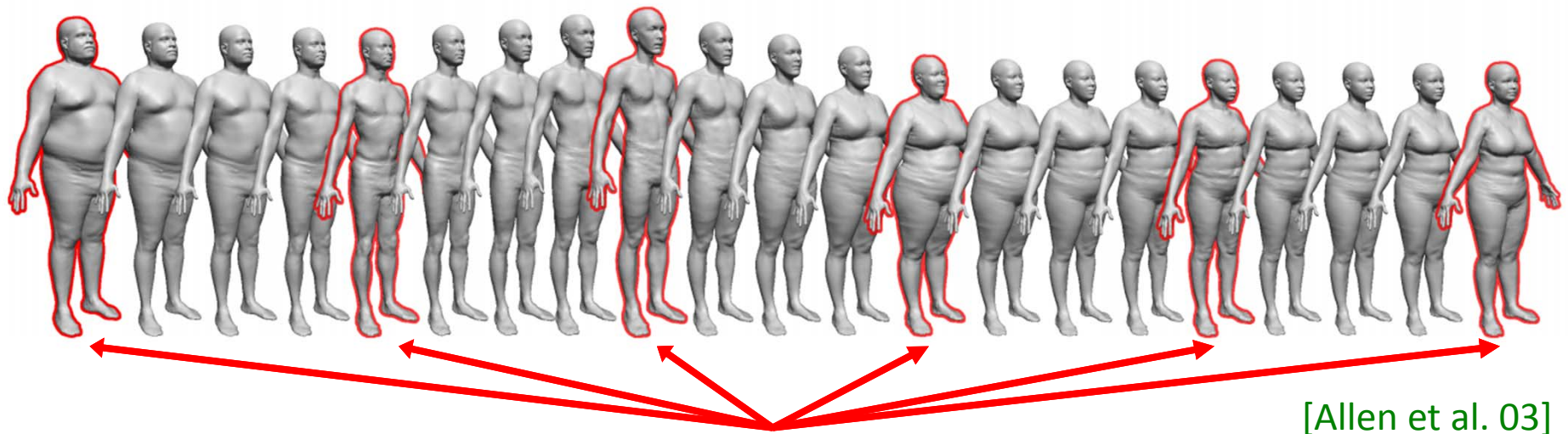
- Structural variability
- Geometric variability
- Stylistic variability



**Our chair dataset**

## Related work: variability in human body and face

- A morphable model for the synthesis of 3D faces [Blanz & Vetter 99]
- The space of human body shapes [Allen et al. 03]
- Shape completion and animation of people [Anguelov et al. 05]



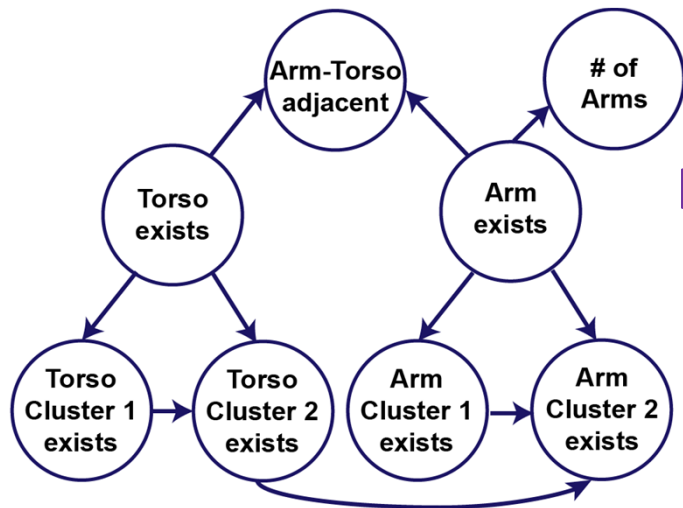
Scanned bodies

[Allen et al. 03]



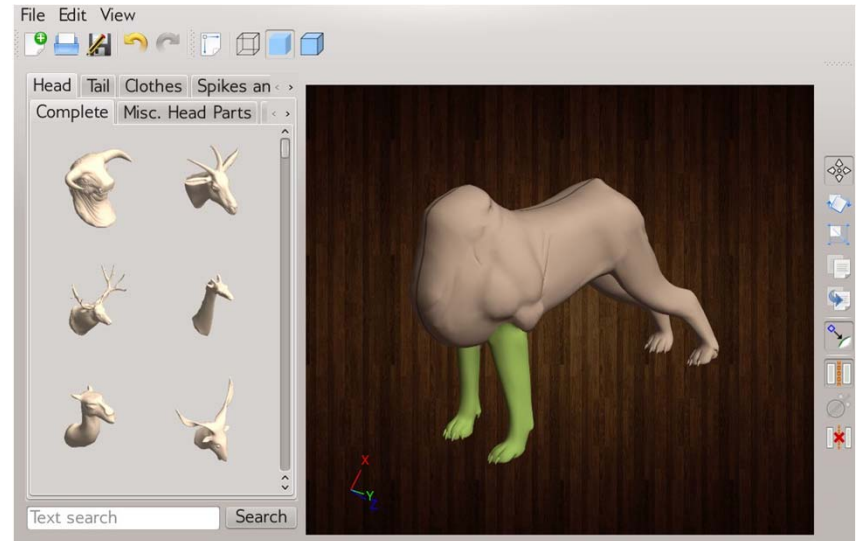
# Related work: probabilistic reasoning for assembly-based modeling

[Chaudhuri et al. 2011]



Probabilistic model

Inference

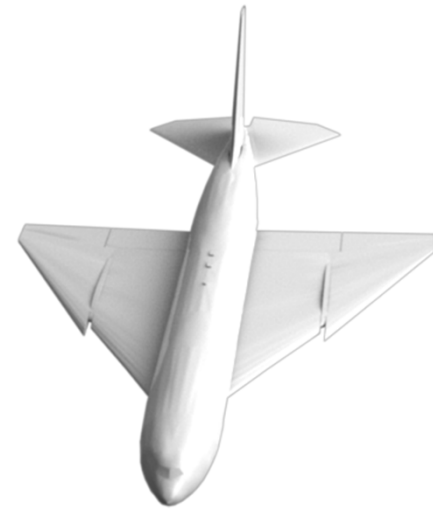
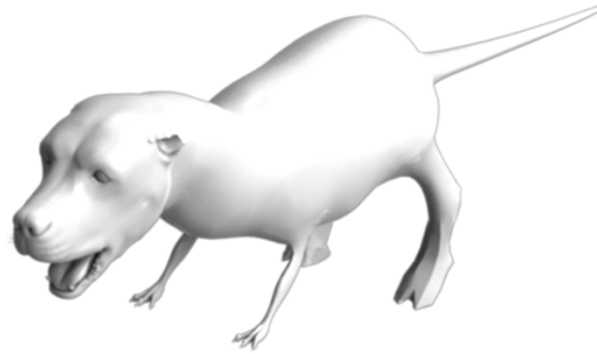
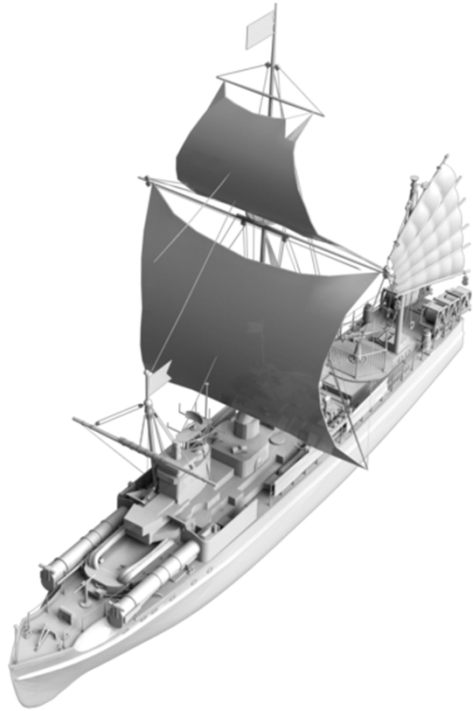


Modeling interface

## Related work: probabilistic reasoning for assembly-based modeling



Randomly shuffling components of the same category





## Our probabilistic model

- Synthesizes **plausible and complete shapes automatically**

## Our probabilistic model

- Synthesizes **plausible and complete shapes automatically**
- Represents shape variability at **hierarchical levels of abstraction**

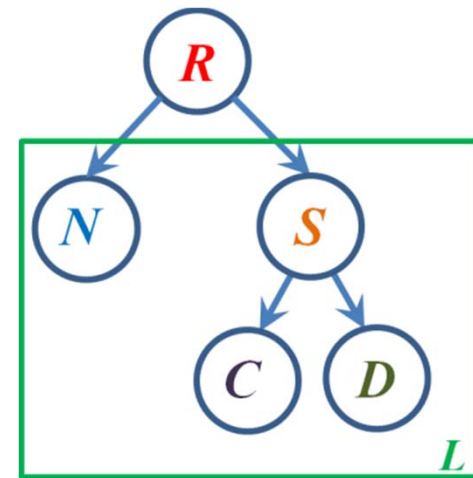
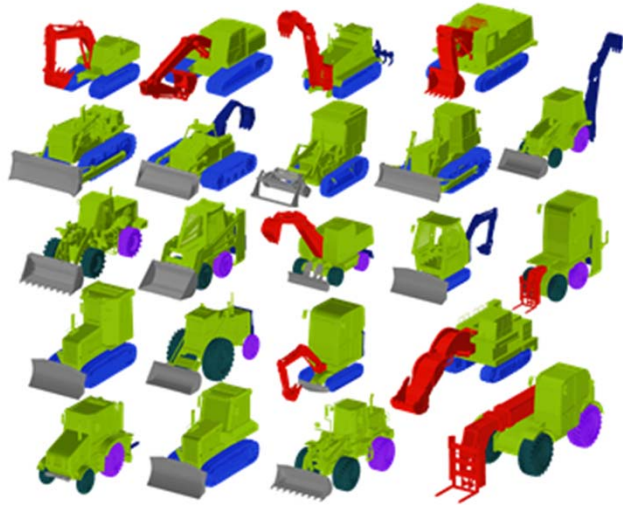
## Our probabilistic model

- Synthesizes **plausible and complete shapes automatically**
- Represents shape variability at **hierarchical levels of abstraction**
- Understands **latent causes of structural and geometric variability**

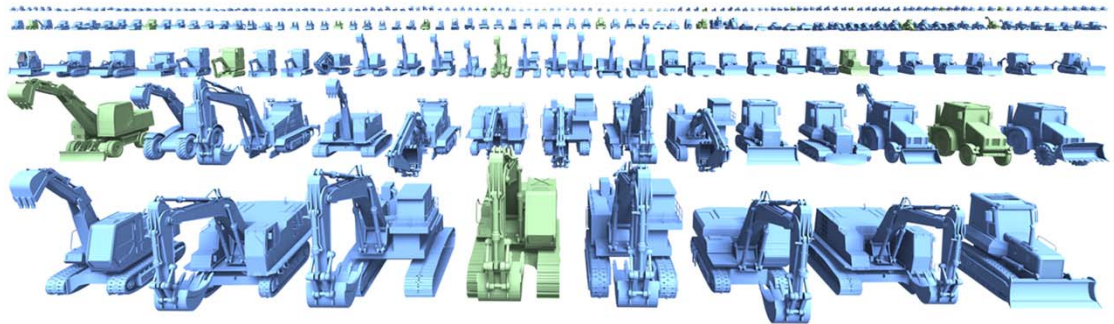
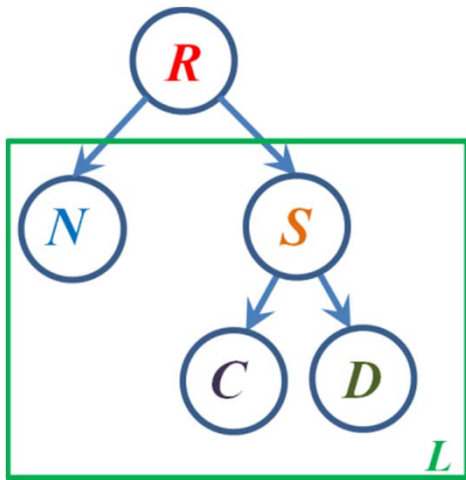
## Our probabilistic model

- Synthesizes **plausible and complete shapes automatically**
- Represents shape variability at **hierarchical levels of abstraction**
- Understands **latent causes of structural and geometric variability**
- Learned **without supervision** from a set of segmented shapes

# Learning stage

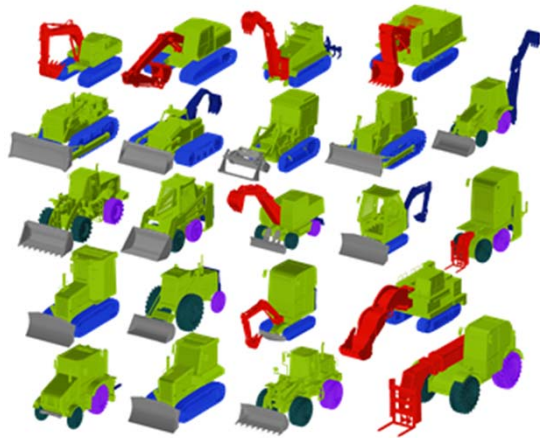


# Synthesis stage



# Learning shape variability

We model attributes related to **shape structure**:

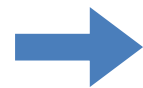


**Shape type**

**Component types**

**Number of components**

**Component geometry**



$P( R, S, N, G )$

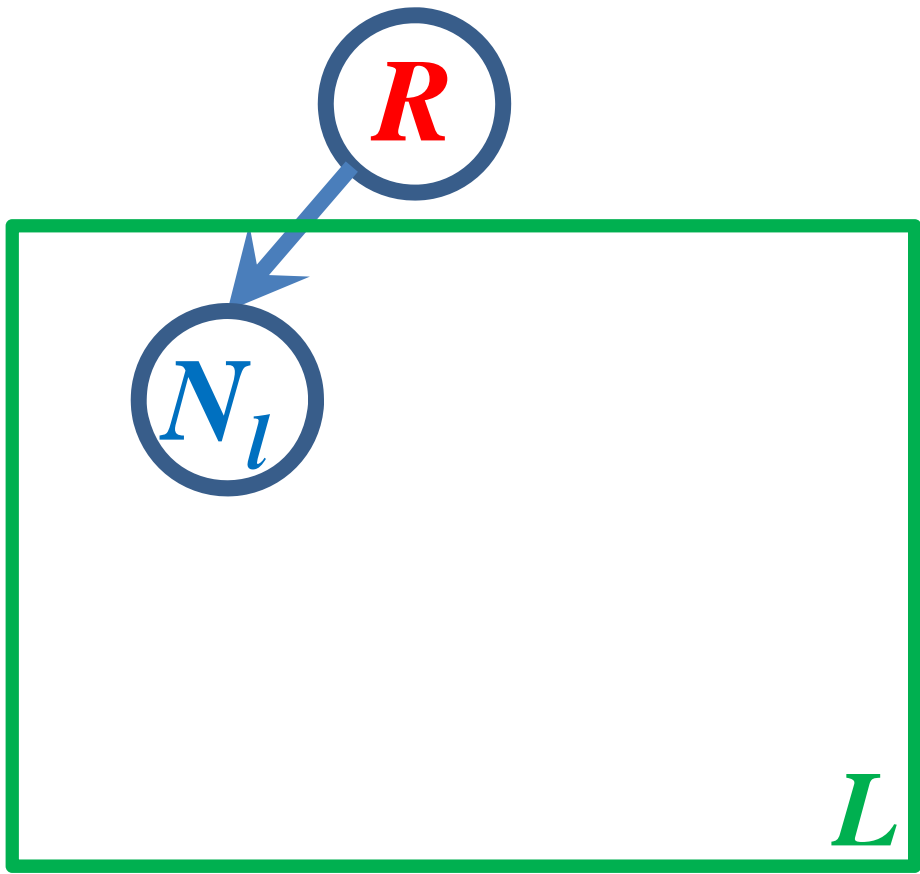




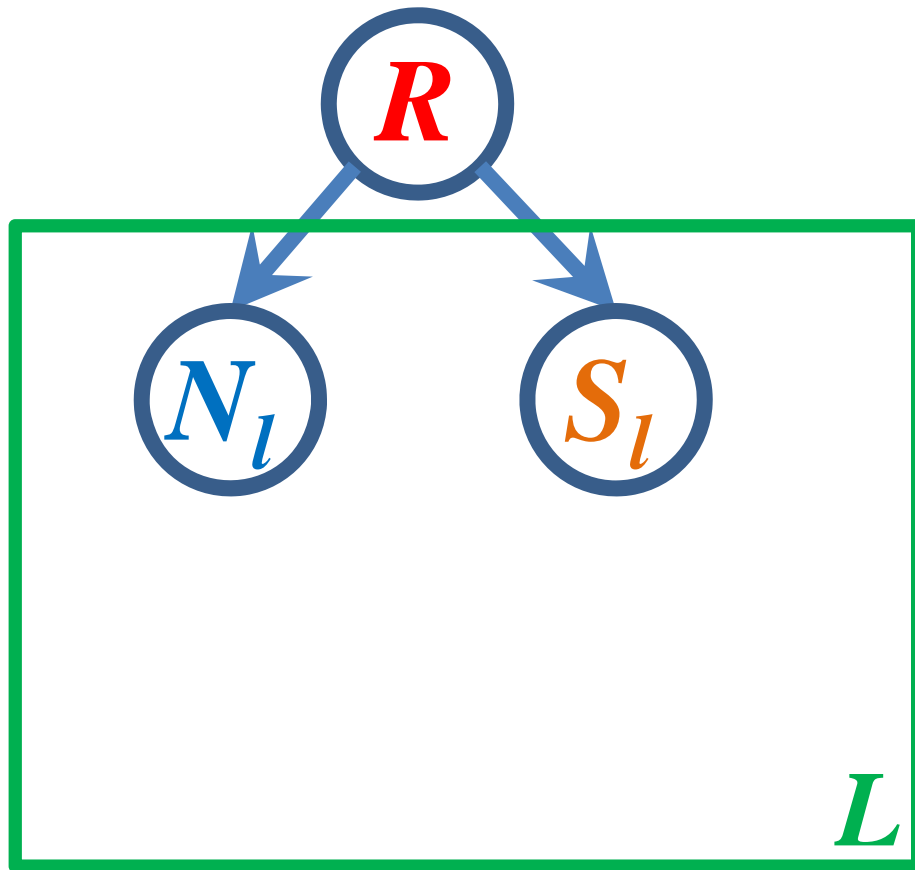
$P(R)$



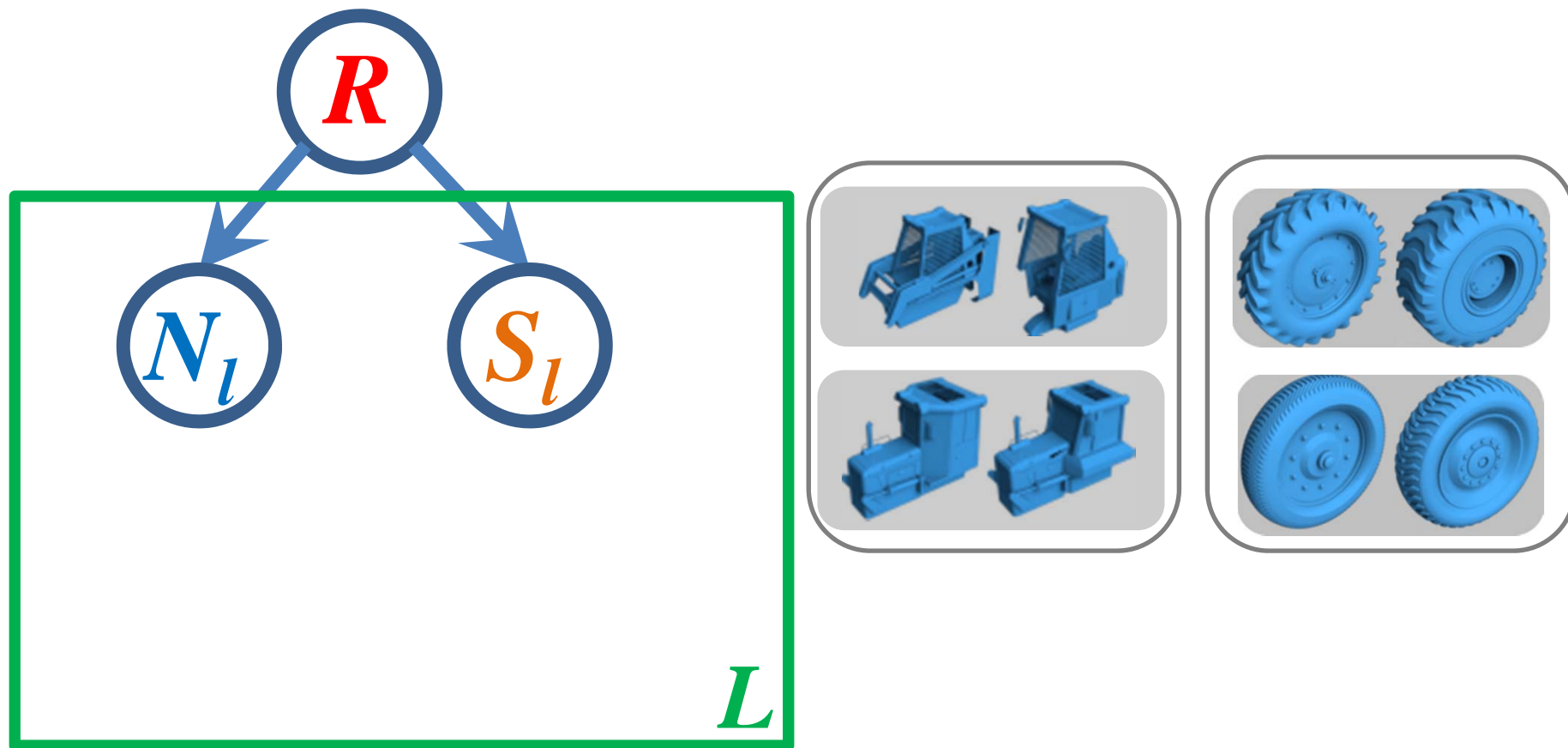
$P(R)$



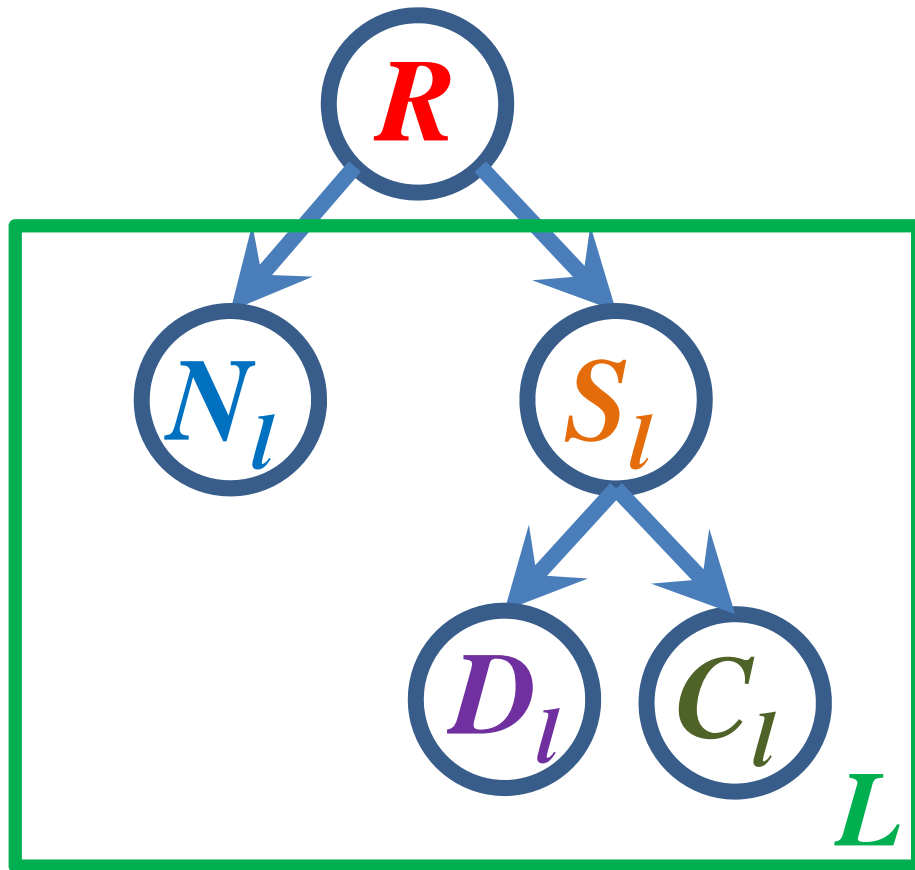
$$P(R) \prod_{l \in L} [P(N_l / R)]$$



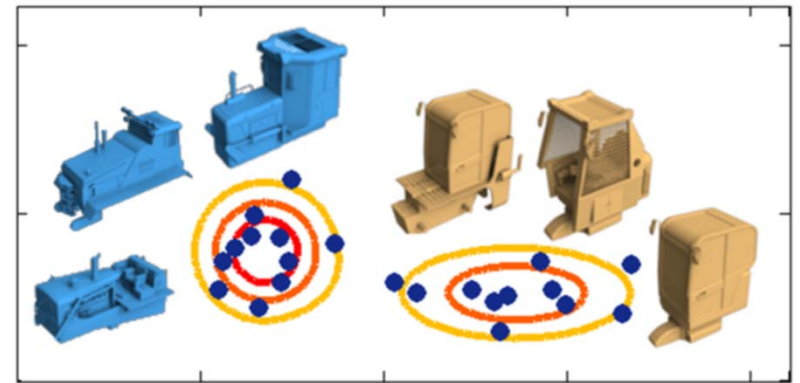
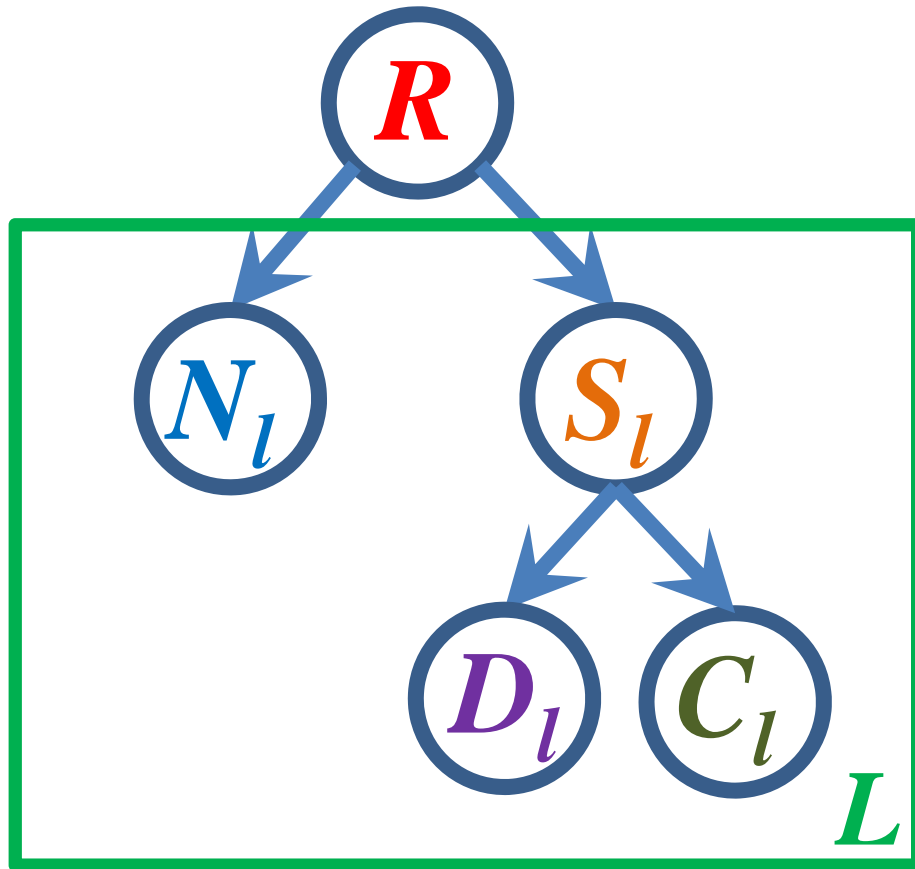
$$P(R) \prod_{l \in L} [P(N_l / R) P(S_l / R)]$$



$$P(R) \prod_{l \in L} [P(N_l / R) P(S_l / R)]$$

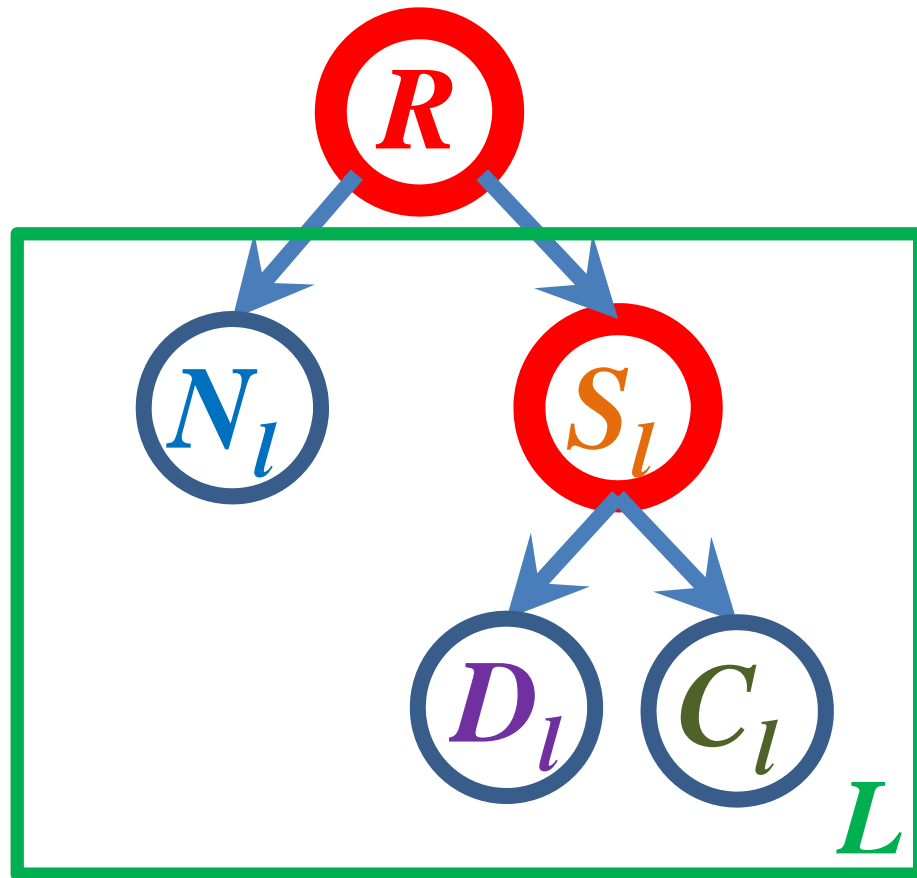


$$P(R) \prod_{l \in L} [P(N_l / R) P(S_l / R) P(D_l / S_l) P(C_l / S_l)]$$



$$P(R) \prod_{l \in L} [P(N_l / R) P(S_l / R) P(D_l / S_l) P(C_l / S_l)]$$

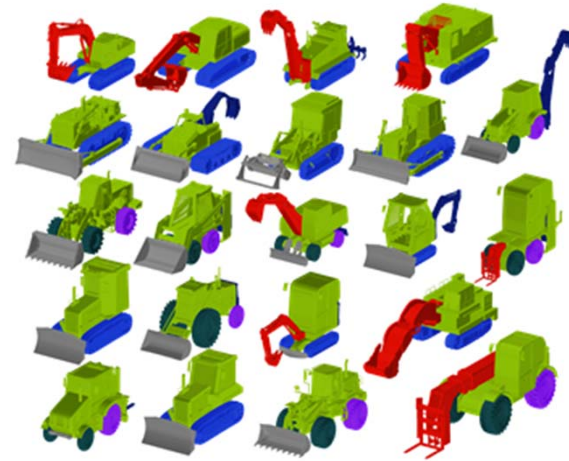
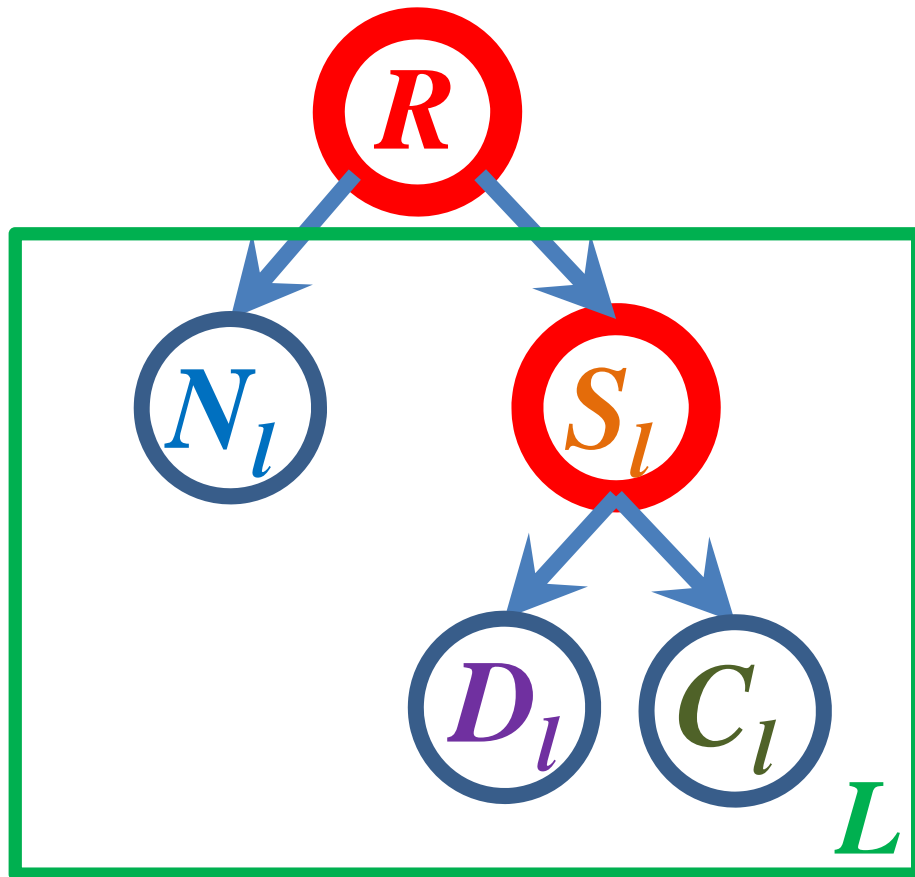




Latent object style

Latent component style

$$P(R) \prod_{l \in L} [P(N_l / R) P(S_l / R) P(D_l / S_l) P(C_l / S_l)]$$



Learn from training data:

latent styles

lateral edges

parameters of CPDs

# Learning

Given observed data  $\mathbf{O}$ , find structure  $\mathbf{G}$  that maximizes:

$$P(\mathbf{G} | \mathbf{O}) = \frac{P(\mathbf{O} | \mathbf{G})P(\mathbf{G})}{P(\mathbf{O})}$$

# Learning

Given observed data  $\mathbf{O}$ , find structure  $\mathbf{G}$  that maximizes:

$$P(\mathbf{G} | \mathbf{O}) = \frac{P(\mathbf{O} | \mathbf{G})P(\mathbf{G})}{P(\mathbf{O})}$$

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# Learning

Given observed data  $\mathbf{O}$ , find structure  $G$  that maximizes:

$$P(G | \mathbf{O}) = \frac{P(\mathbf{O} | G)P(G)}{P(\mathbf{O})}$$

Assuming uniform prior over structures, maximize **marginal likelihood**:

$$P(\mathbf{O} | G) = \sum_{R, S} \int_{\Theta} P(\mathbf{O}, R, S | \Theta, G) P(\Theta | G) d\Theta$$



# Learning

Given observed data  $\mathbf{O}$ , find structure  $G$  that maximizes:

$$P(G | \mathbf{O}) = \frac{P(\mathbf{O} | G)P(G)}{P(\mathbf{O})}$$

Assuming uniform prior over structures, maximize **marginal likelihood**:

$$P(\mathbf{O} | G) = \sum_{R, S} \int_{\Theta} P(\mathbf{O}, R, S | \Theta, G) P(\Theta | G) d\Theta$$

**Complete likelihood**

# Learning

Given observed data  $\mathbf{O}$ , find structure  $G$  that maximizes:

$$P(G | \mathbf{O}) = \frac{P(\mathbf{O} | G)P(G)}{P(\mathbf{O})}$$

Assuming uniform prior over structures, maximize **marginal likelihood**:

$$P(\mathbf{O} | G) = \sum_{R, S} \int_{\Theta} P(\mathbf{O}, R, S | \Theta, G) P(\Theta | G) d\Theta$$

Parameter priors

# Learning

Given observed data  $\mathbf{O}$ , find structure  $G$  that maximizes:

$$P(G | \mathbf{O}) = \frac{P(\mathbf{O} | G)P(G)}{P(\mathbf{O})}$$

Assuming uniform prior over structures, maximize **marginal likelihood**:

$$P(\mathbf{O} | G) = \sum_{R, S} \int_{\Theta} P(\mathbf{O}, R, S | \Theta, G) P(\Theta | G) d\Theta$$

# Learning

Given observed data  $\mathbf{O}$ , find structure  $G$  that maximizes:

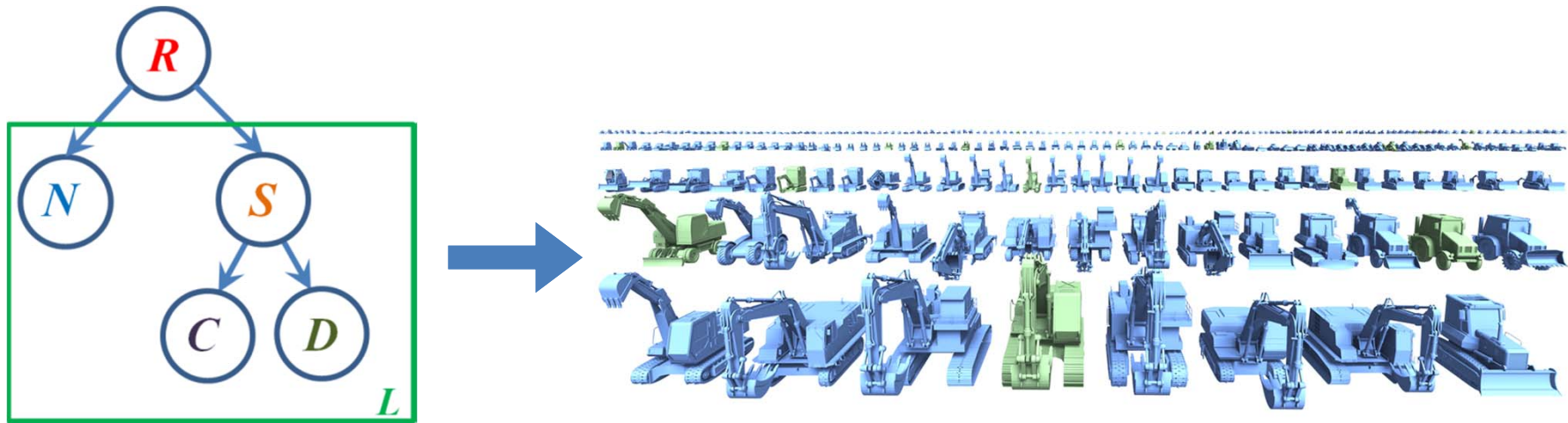
$$P(G | \mathbf{O}) = \frac{P(\mathbf{O} | G)P(G)}{P(\mathbf{O})}$$

Assuming uniform prior over structures, maximize **marginal likelihood**:

$$P(\mathbf{O} | G) = \sum_{R, S} \int_{\Theta} P(\mathbf{O}, R, S | \Theta, G) P(\Theta | G) d\Theta$$

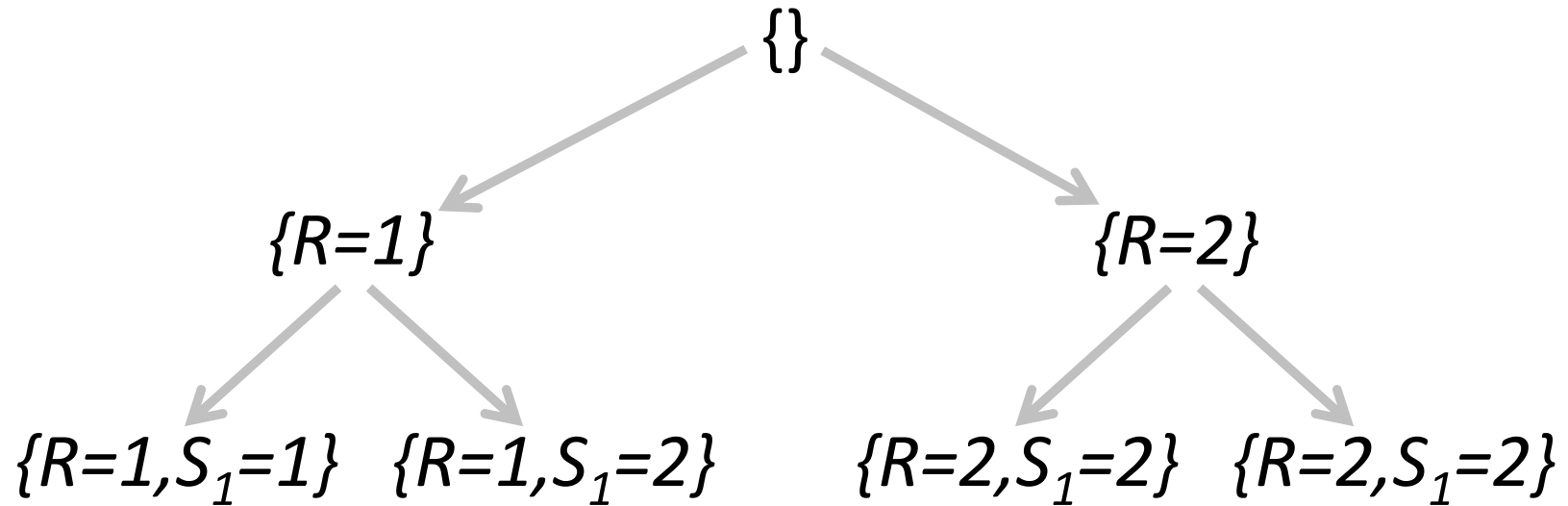
➡ ***Cheeseman-Stutz approximation***

# Our probabilistic model: **synthesis stage**



# Shape Synthesis

Enumerate high-probability instantiations of the model



# Component placement



**Source shapes**

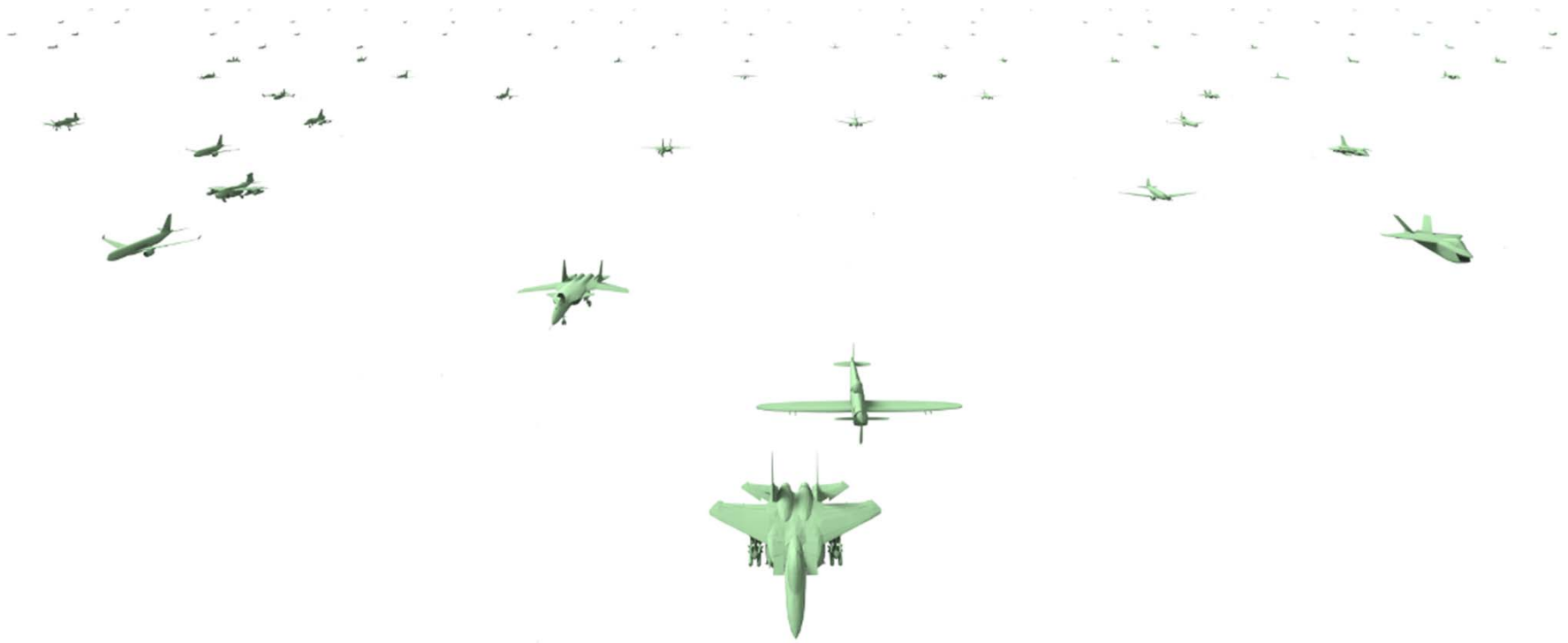


**Unoptimized new shape**



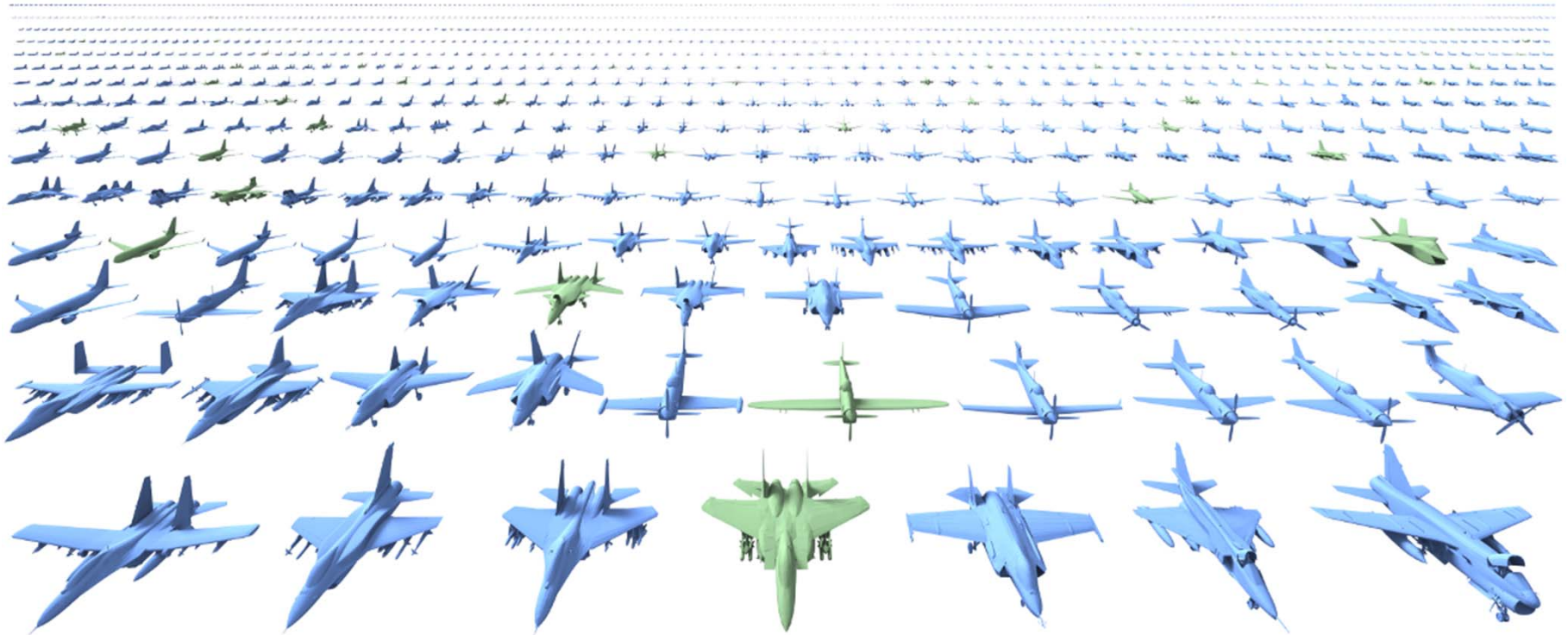
**Optimized new shape**

# Database Amplification - Airplanes





# Database Amplification - Airplanes



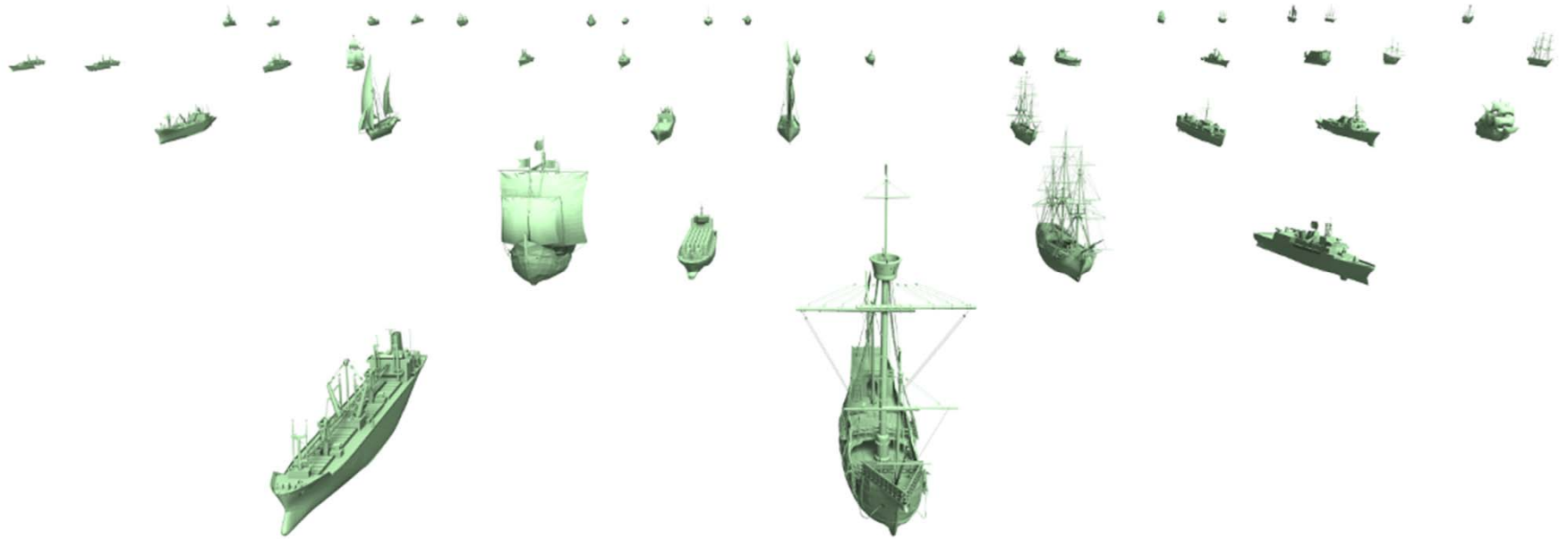
# Database Amplification - Chairs



# Database Amplification - Chairs

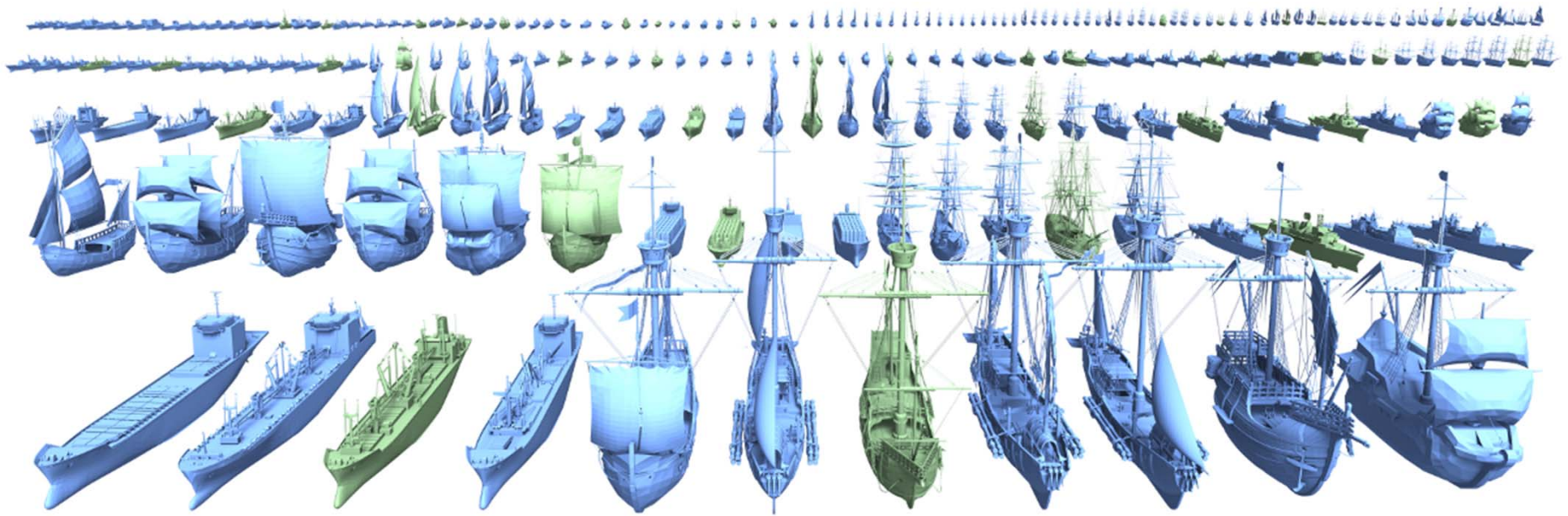


# Database Amplification - Ships

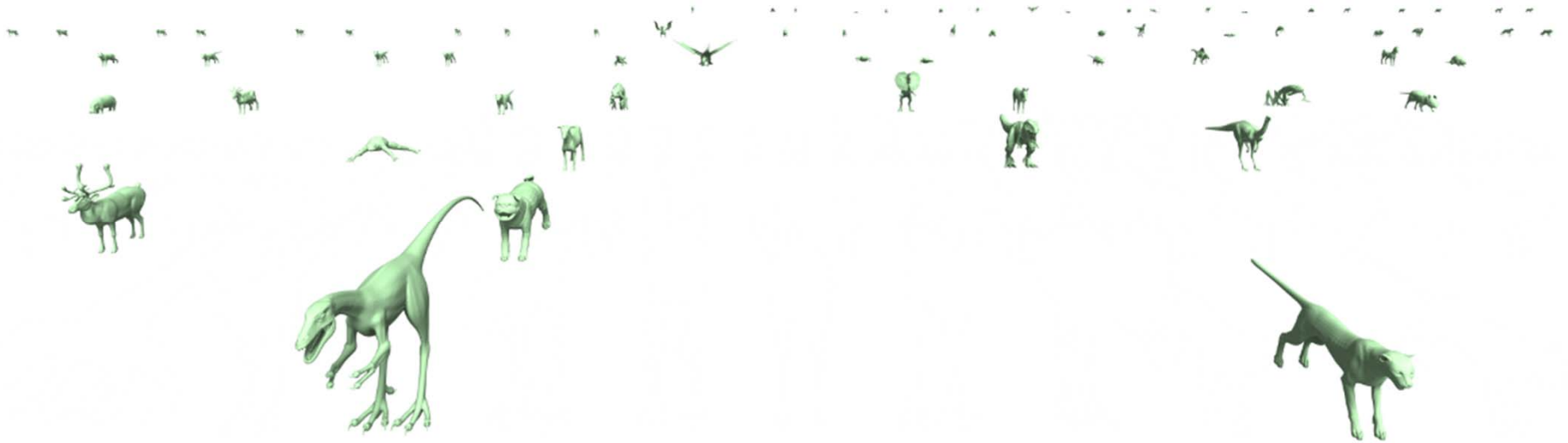




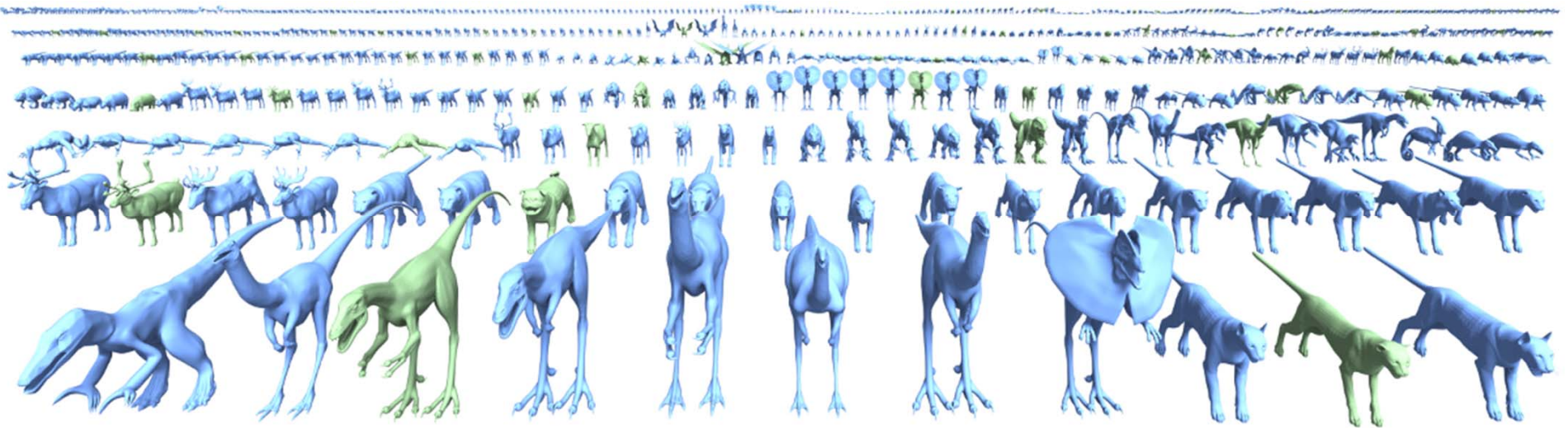
# Database Amplification - Ships



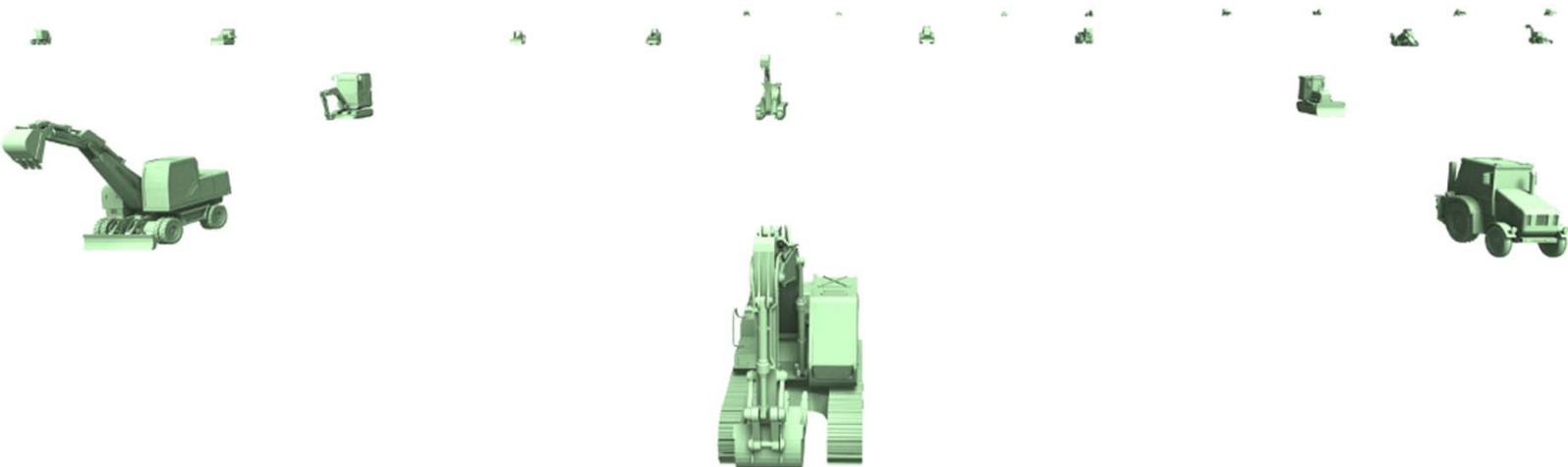
# Database Amplification - Animals



# Database Amplification - Animals

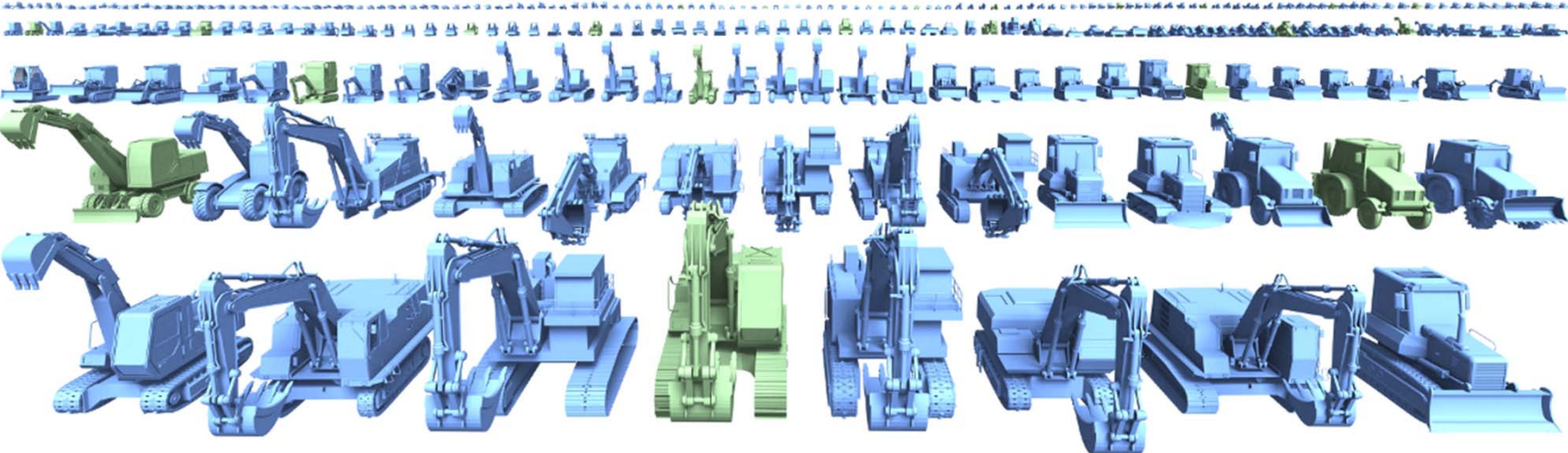


# Database Amplification – Construction vehicles





# Database Amplification – Construction vehicles



# Interactive Shape Synthesis

File

Shape Styles



Shape Style 1   Shape Style 2   Shape Style 3   Shape Style 4   Shape Style 5

Component Categories



Hull   Deck   Radar   Funnel   Propeller   Front Cannon I   Antenna

Component Styles

Components of the Selected Style

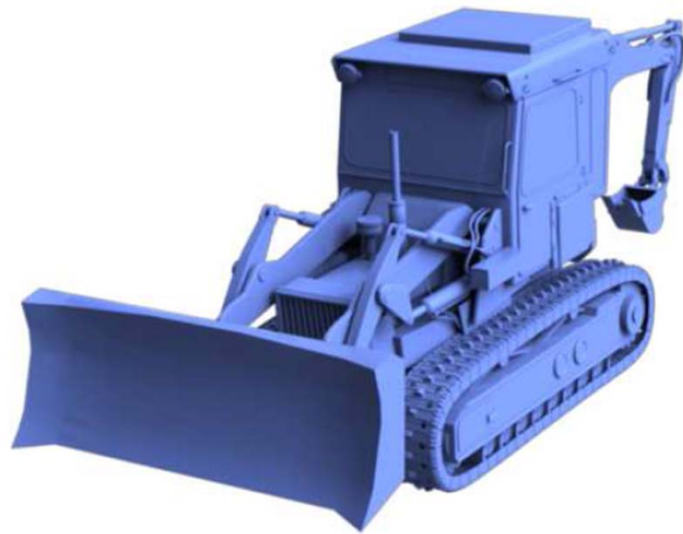
Clear   Generate

# User Survey



prefer left undecided prefer right

# Results



**New shape**

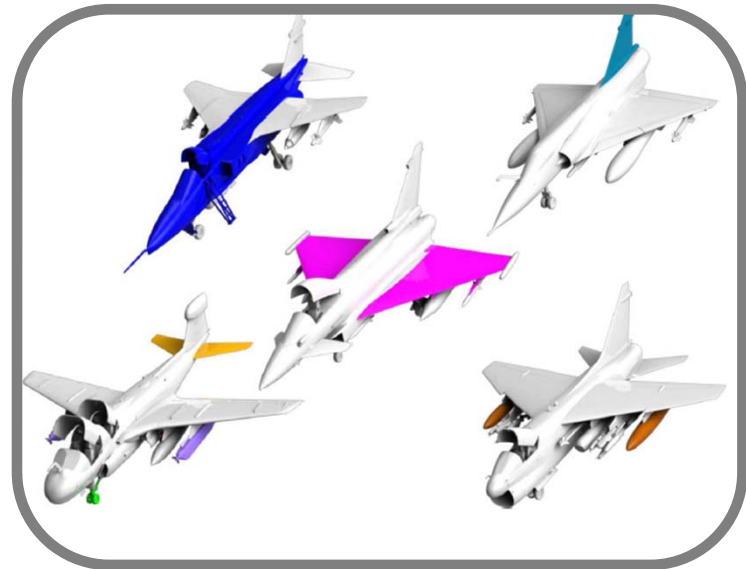


**Source shapes  
(colored parts are selected for  
the new shape)**

# Results

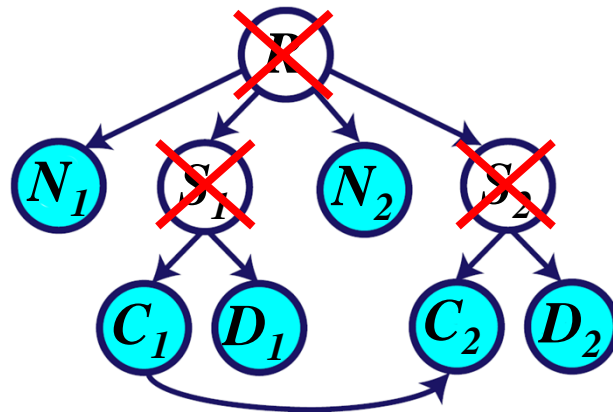


**New shape**

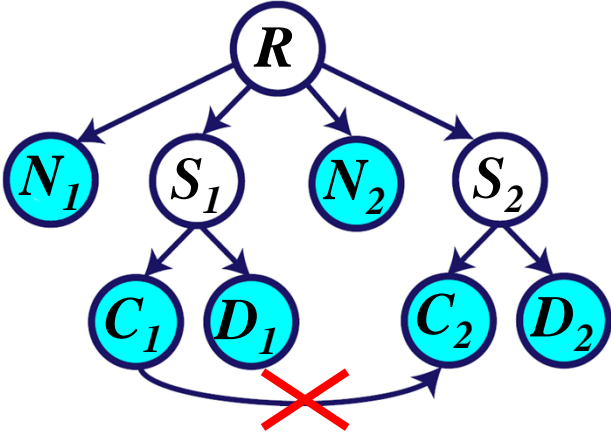


**Source shapes**  
(colored parts are selected for the new shape)

Results of alternative models: no latent variables



Results of alternative models: no part correlations



## Summary

- **Generative model** of component-based shape synthesis
- **Automatically synthesizes new shapes** from a domain demonstrated by a set of example shapes
- **Enables shape database amplification** or interactive synthesis with **high-level user constraints**



## Future Work

- Our model can be used as a shape prior - applications to **reconstruction** and **interactive modeling**
- Synthesis of shapes with **new geometry** for parts
- Model **locations** and **spatial relationships** of parts

Thank you!

**Acknowledgements:** *Aaron Hertzmann, Sergey Levine,  
Philipp Krähenbühl, Tom Funkhouser*

Our project web page:

<http://graphics.stanford.edu/~kalo/papers/ShapeSynthesis/>

