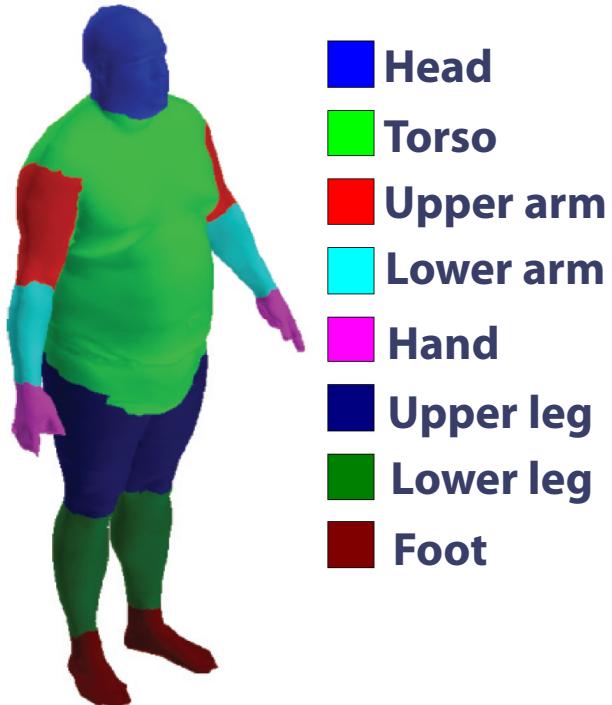
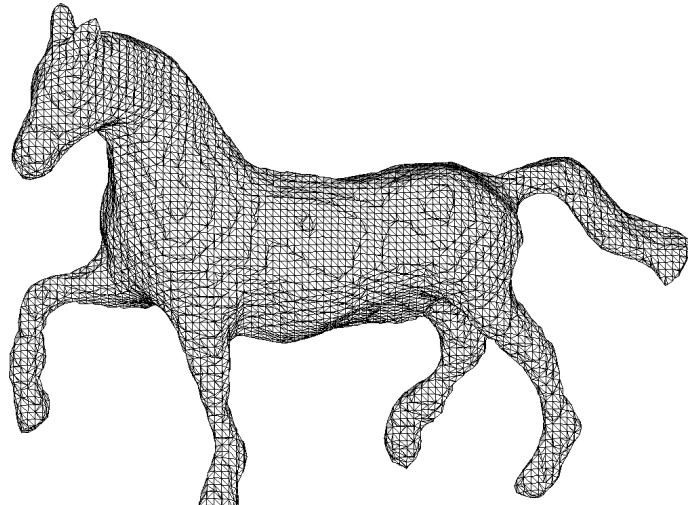


Learning 3D mesh segmentation and labeling



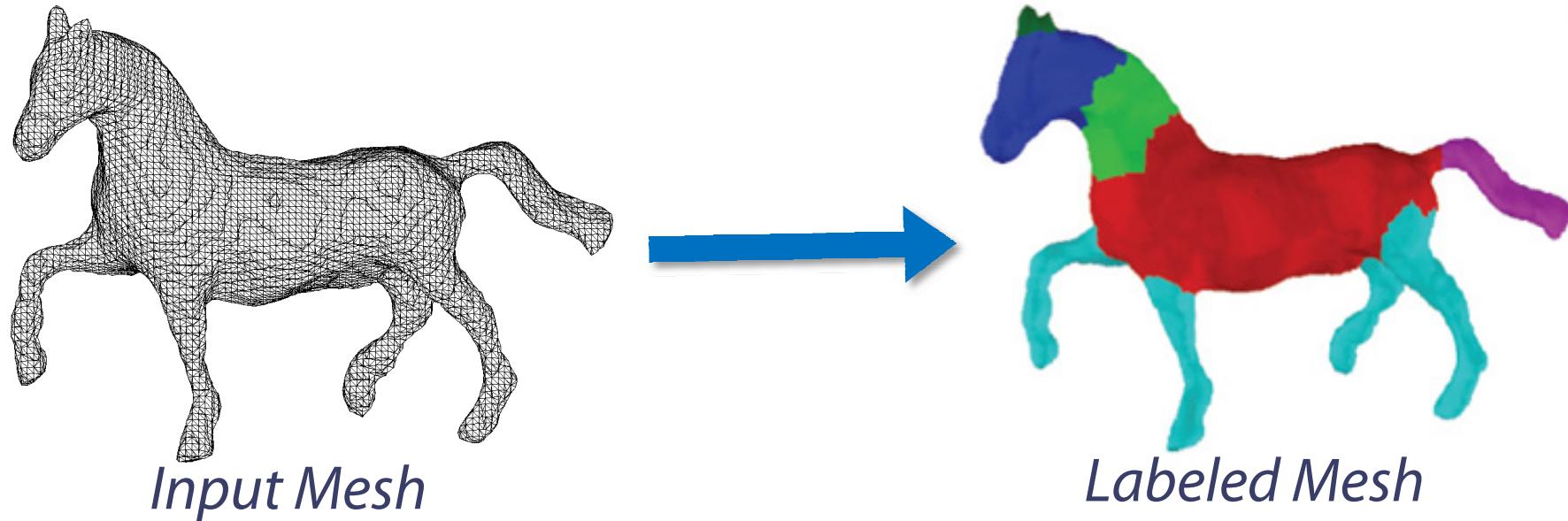
Evangelos Kalogerakis, Aaron Hertzmann, Karan Singh
University of Toronto

Goal: mesh segmentation and labeling



Input Mesh

Goal: mesh segmentation and labeling



■ Head

■ Neck

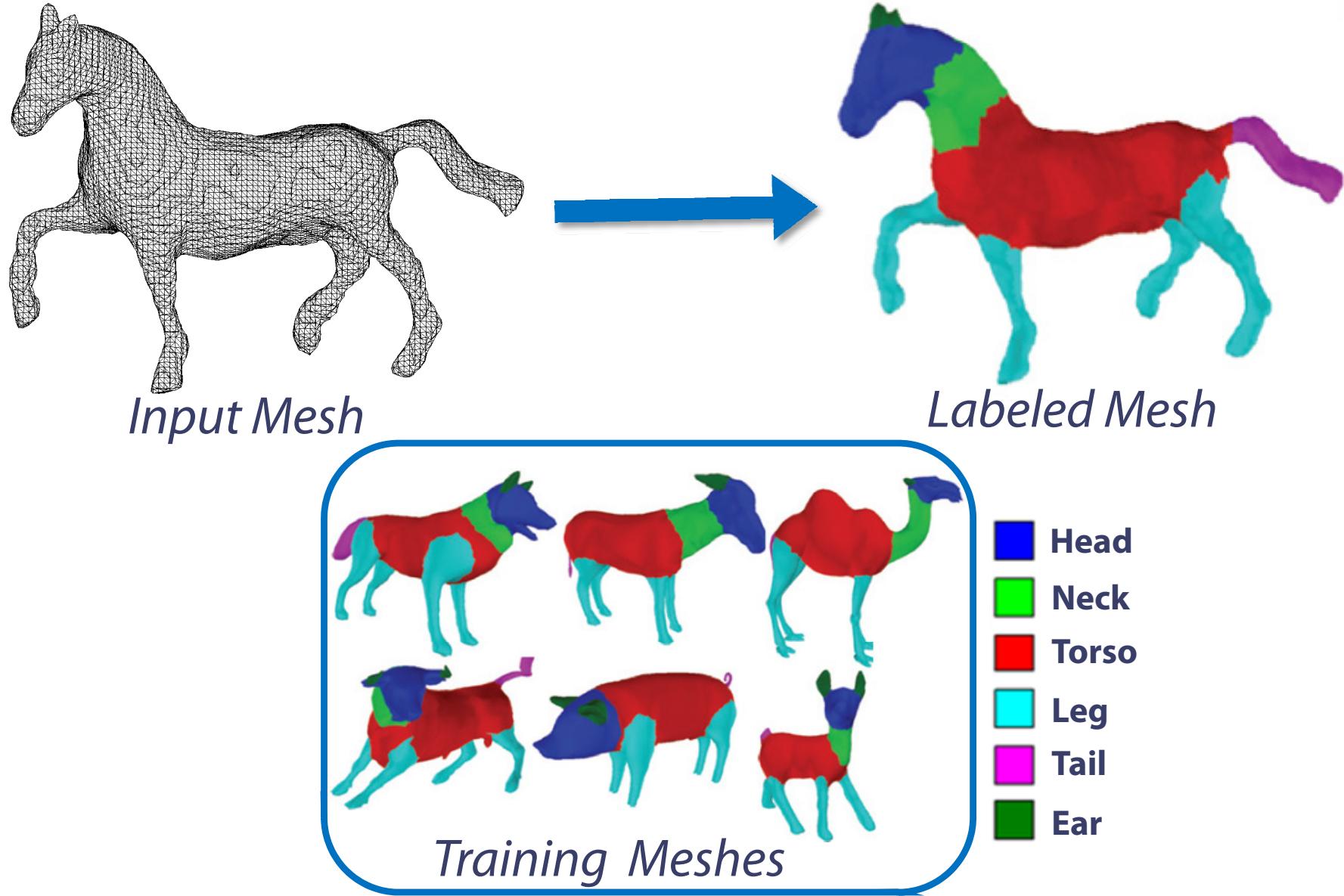
■ Torso

■ Leg

■ Tail

■ Ear

Goal: mesh segmentation and labeling



Related work: mesh segmentation

[**Mangan and Whitaker 1999, Shlafman *et al.* 2002,**
Katz and Tal 2003, Liu and Zhang 2004, Katz *et al.* 2005,
Simari *et al.* 2006, Attene *et al.* 2006, Lin *et al.* 2007,
Kraevoy *et al.* 2007, Pekelny and Gotsman 2008,
Golovinskiy and Funkhouser 2008, Li *et al.* 2008,
Lai *et al.* 2008, Lavoue and Wolf 2008, Huang *et al.* 2009,
Shapira *et al.* 2010]

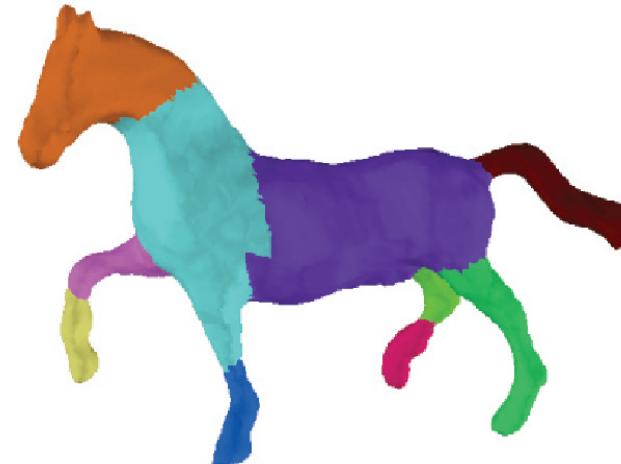
Surveys:

[**Attene *et al.* 2006, Shamir 2008, Chen *et al.* 2009**]

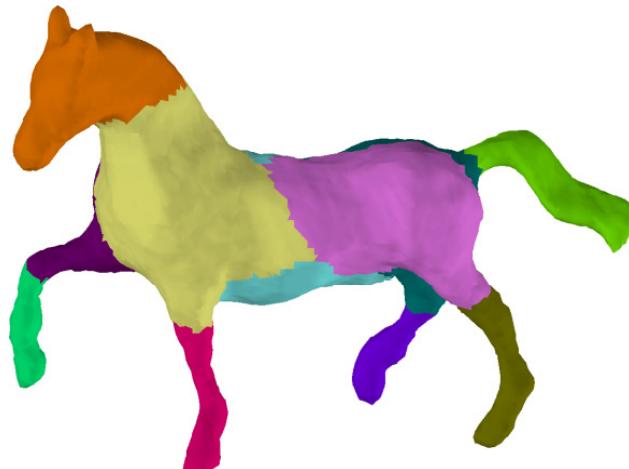
Related work: mesh segmentation



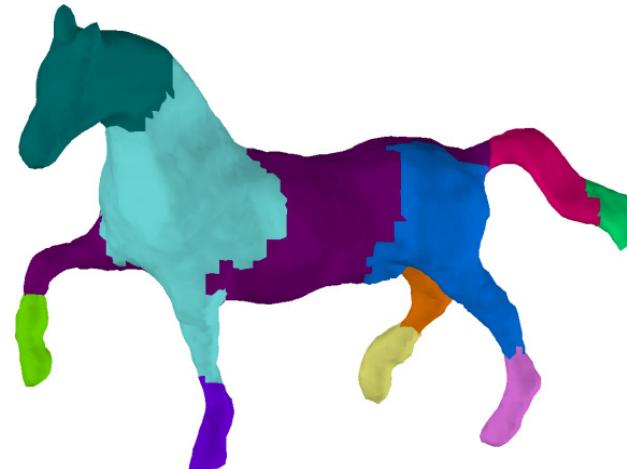
Shape Diameter
[Shapira et al. 10]



Randomized Cuts
[Golovinskiy and Funkhouser 08]

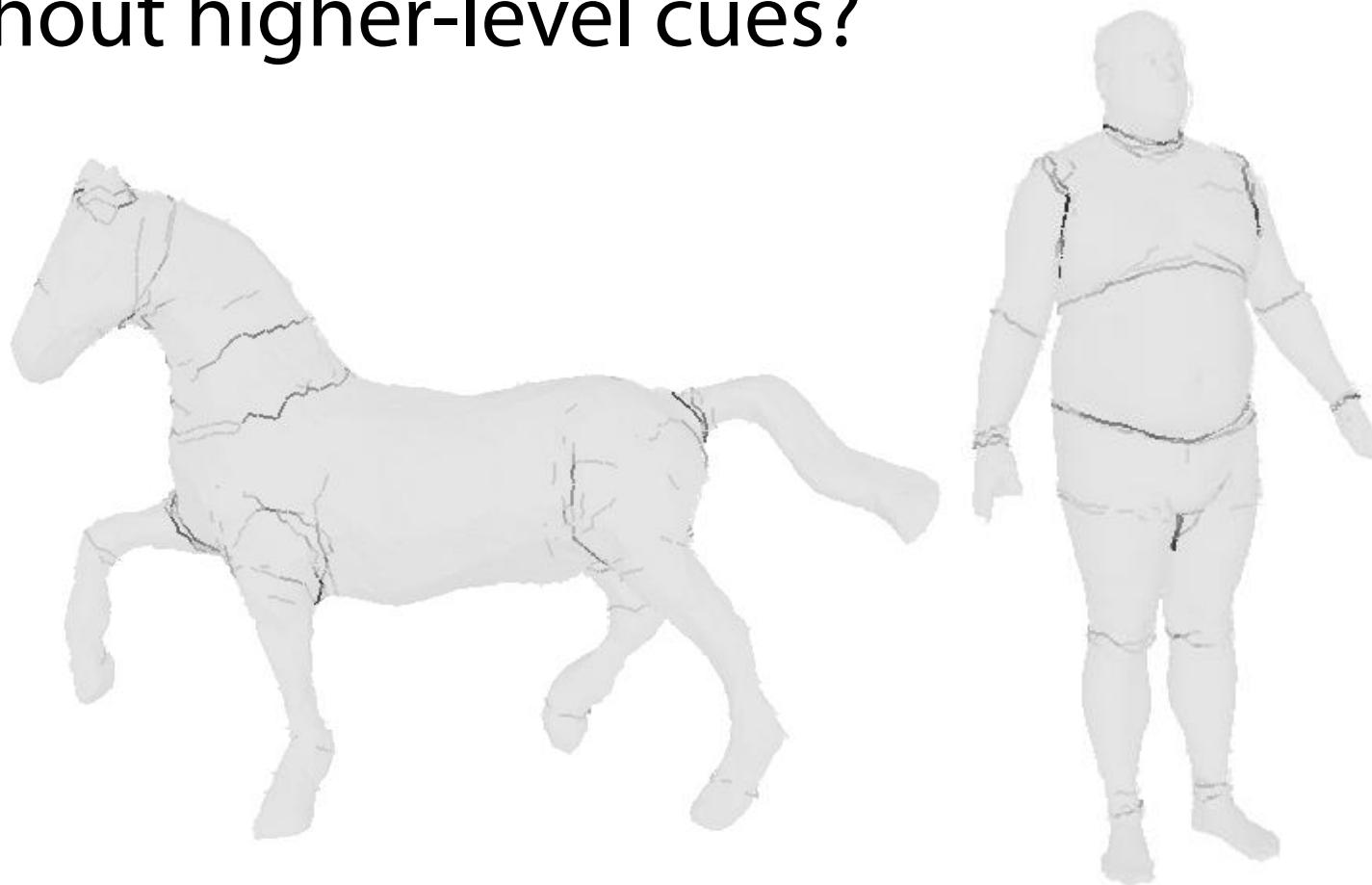


Random Walks
[Lai et al. 08]



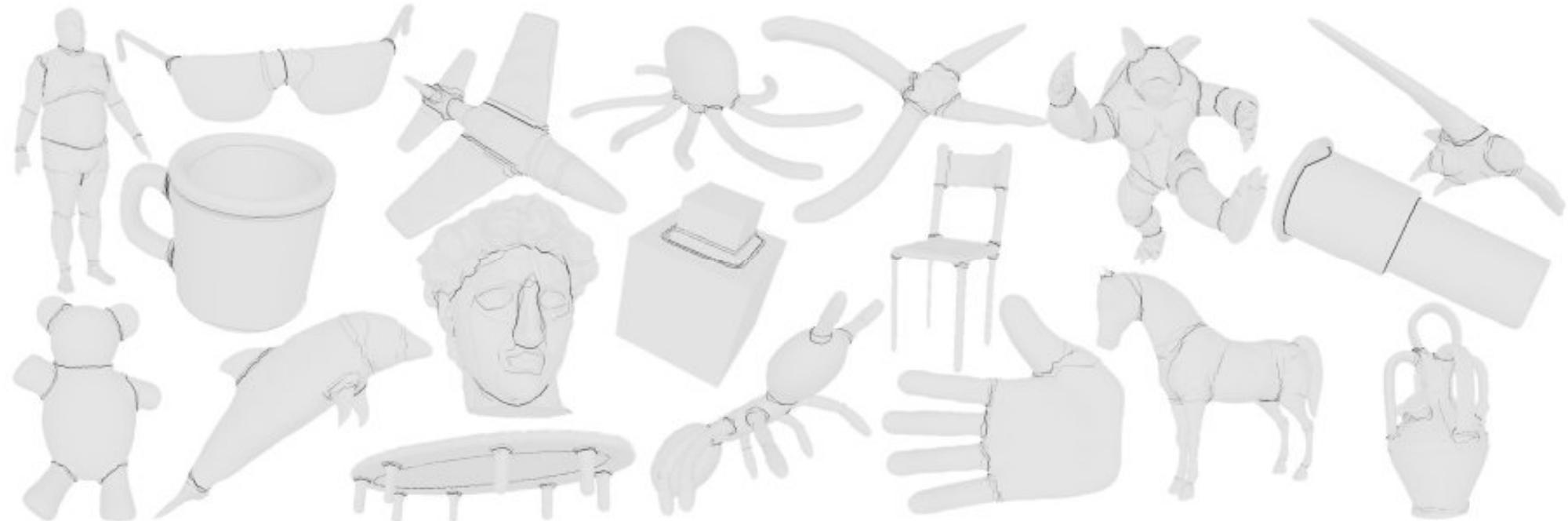
Normalized Cuts
[Golovinskiy and Funkhouser 08]

Is human-level segmentation even possible
without higher-level cues?



[X. Chen et al. SIGGRAPH 09]

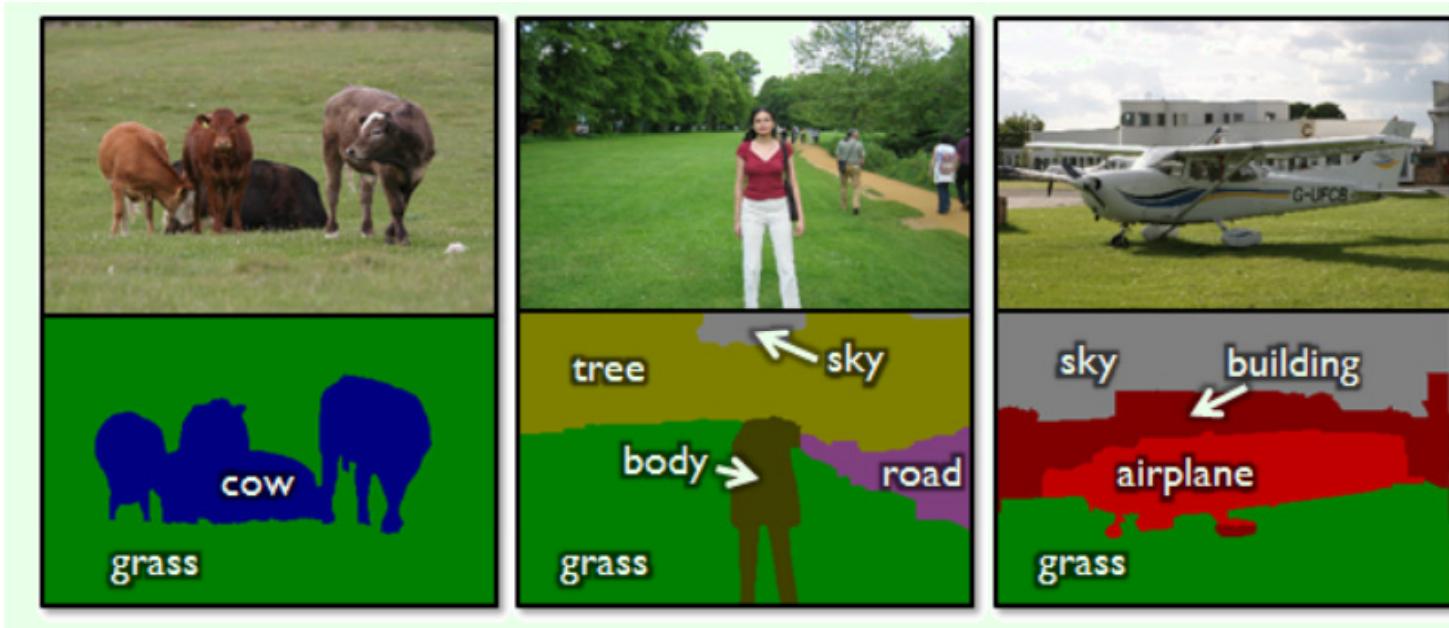
Is human-level segmentation even possible
without higher-level cues?



[X. Chen et al. SIGGRAPH 09]

Image segmentation and labeling

[Konishi and Yuille 00, Duygulu et al. 02, He et al. 04, Kumar and Hebert 03, Anguelov et al. 05, Tu et al. 05, Schnitman et al. 06, Lim and Suter 07, Munoz et al. 08,...]

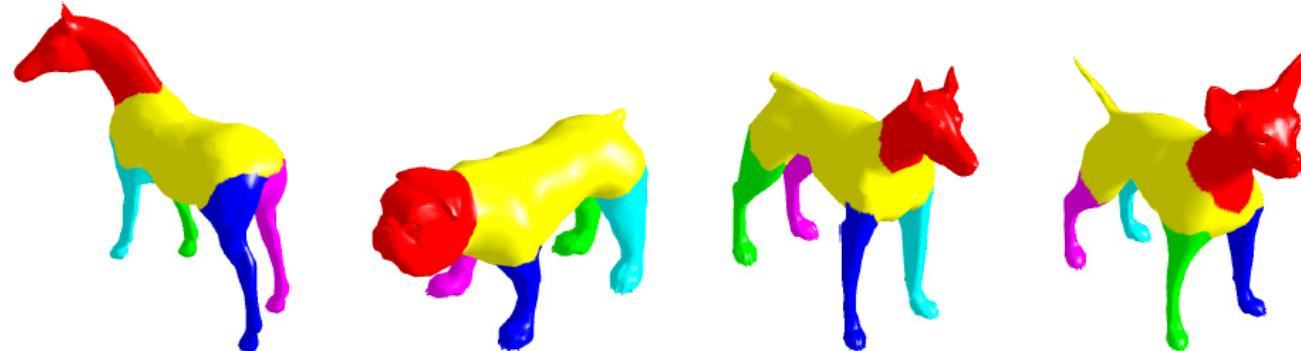


Textronboost
[Shotton et al. ECCV 06]

Related work: mesh segmentation & labeling



Consistent segmentation of 3D meshes
[Golovinskiy and Funkhouser 09]



Multi-objective segmentation and labeling
[Simari et al. 09]

Learning mesh segmentation and labeling

Learn from examples

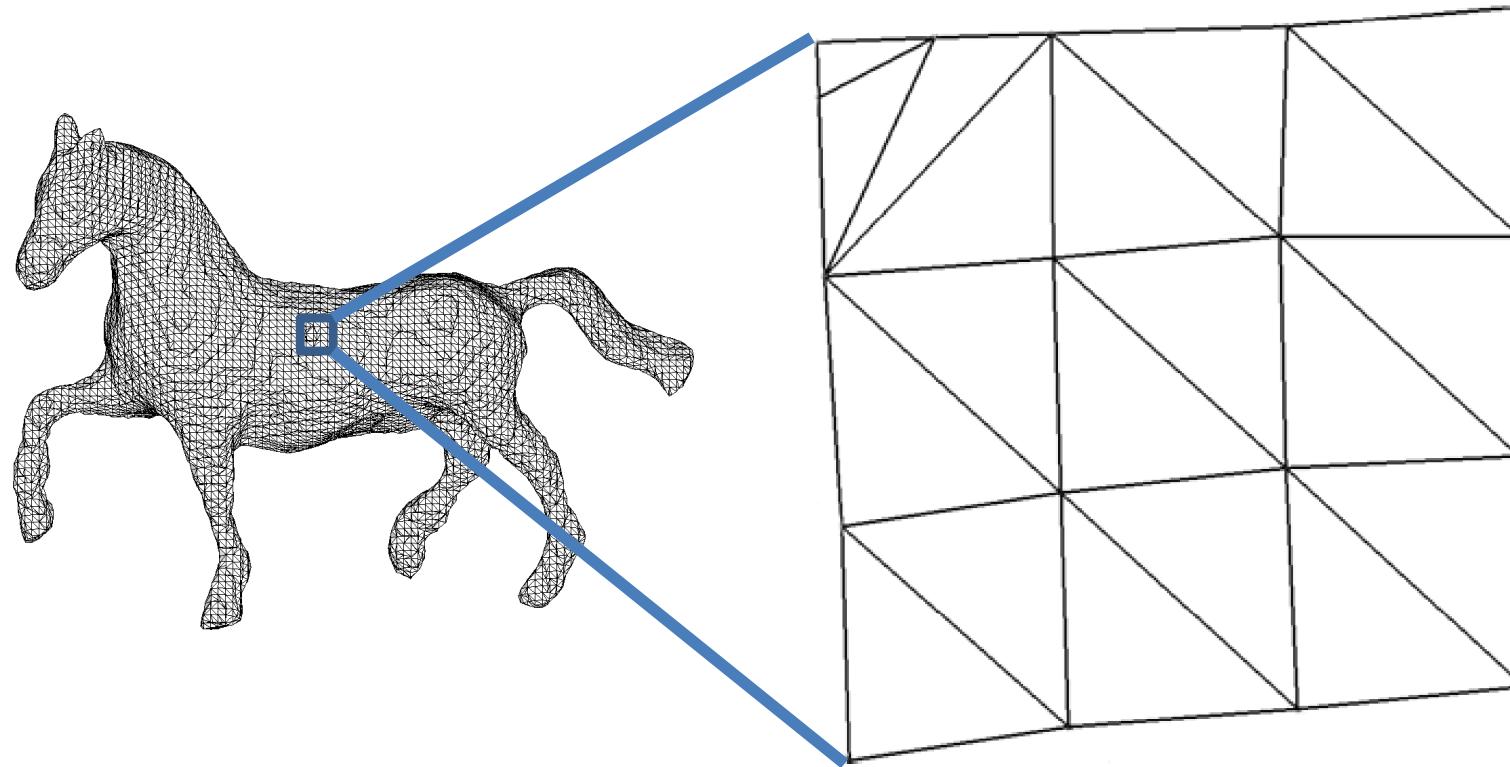
Significantly better results than state-of-the-art

No manual parameter tuning

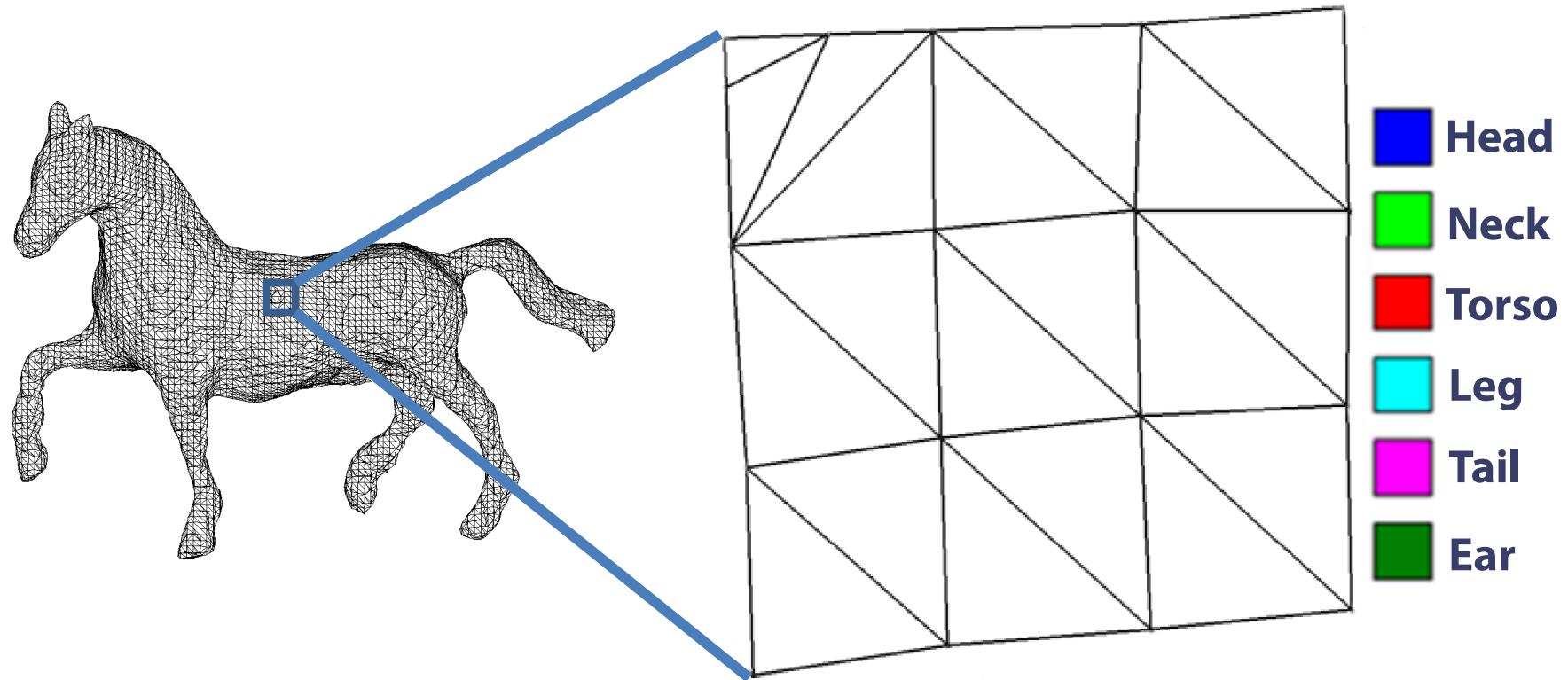
Can learn different styles of segmentation

Several applications of part labeling

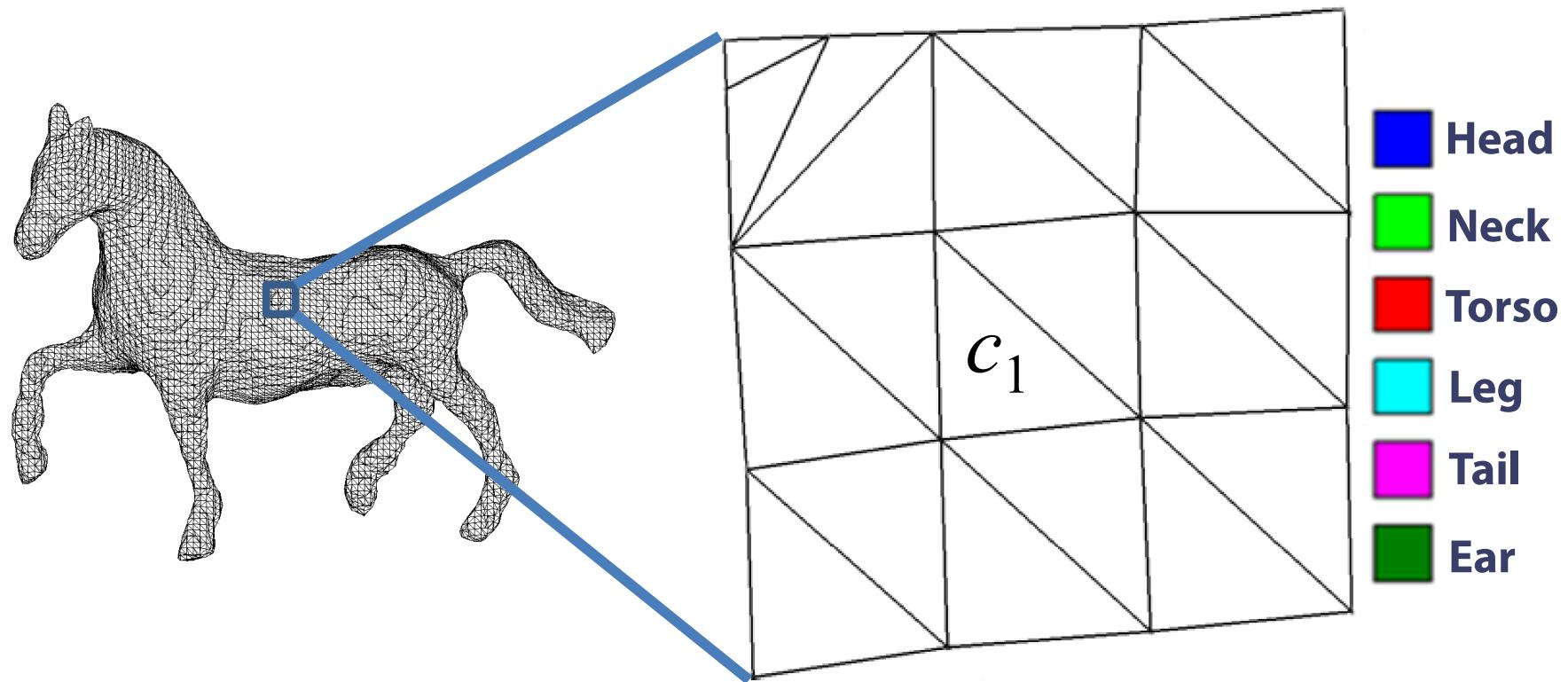
Labeling problem statement



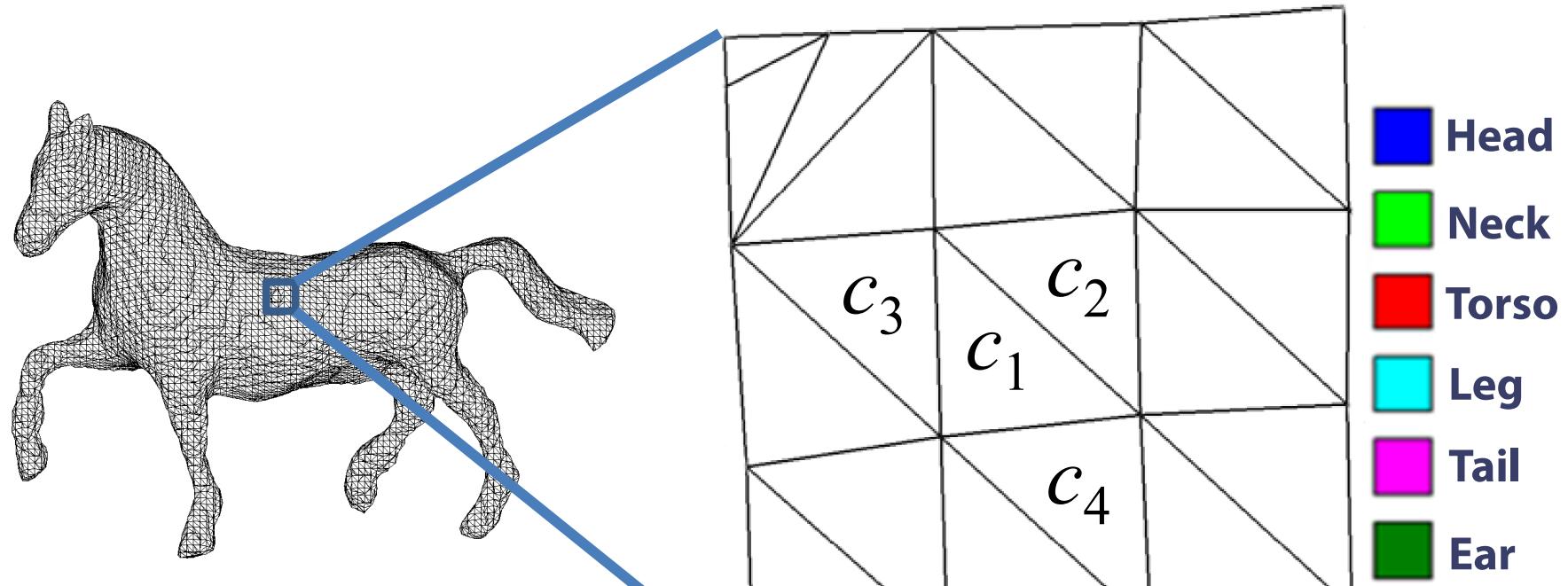
Labeling problem statement



Labeling problem statement



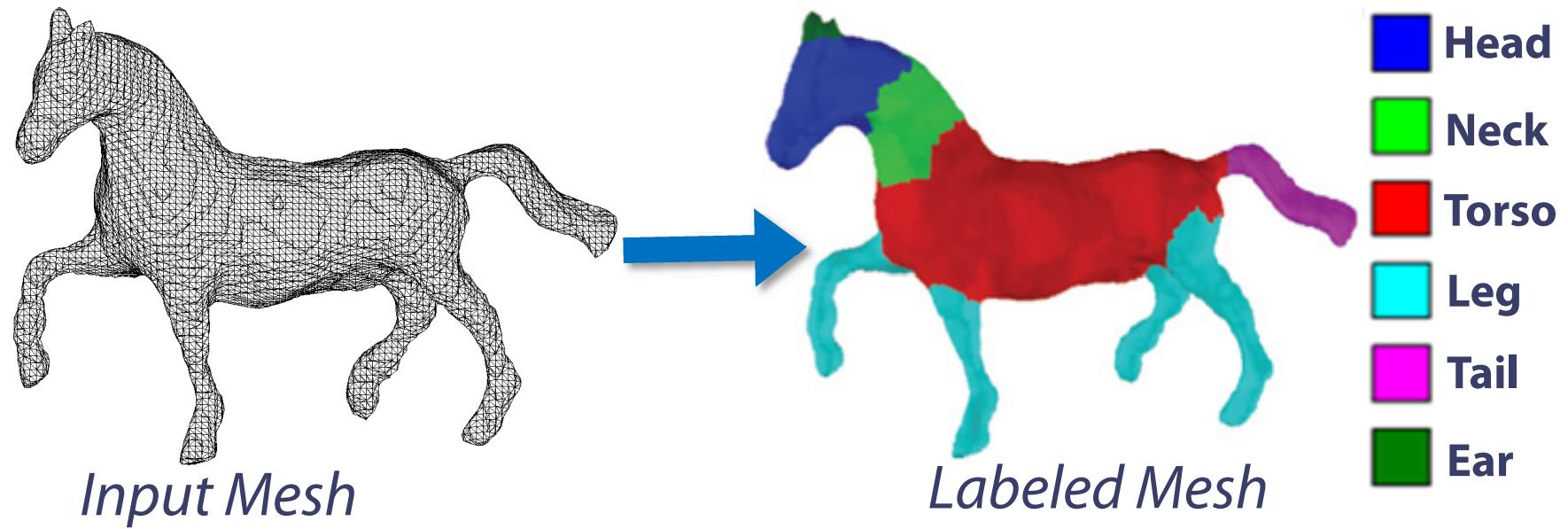
Labeling problem statement



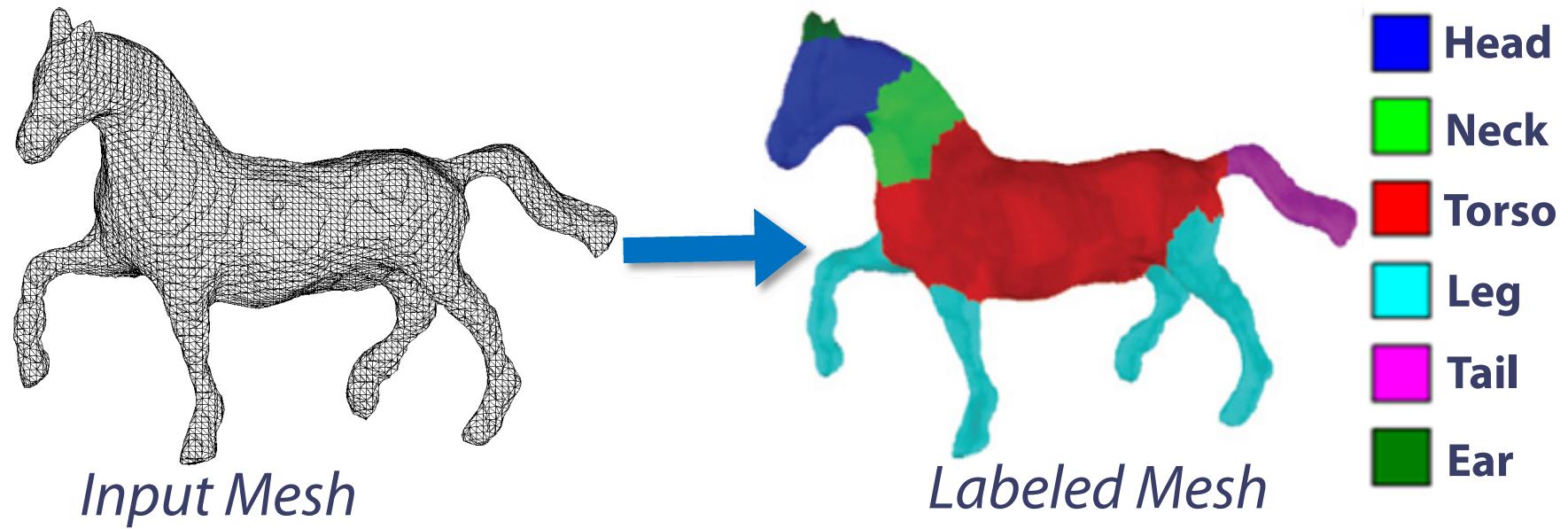
$$c_1, c_2, c_3 \in C$$

$$C = \{ \textit{head}, \textit{neck}, \textit{torso}, \textit{leg}, \textit{tail}, \textit{ear} \}$$

Conditional Random Field for Labeling

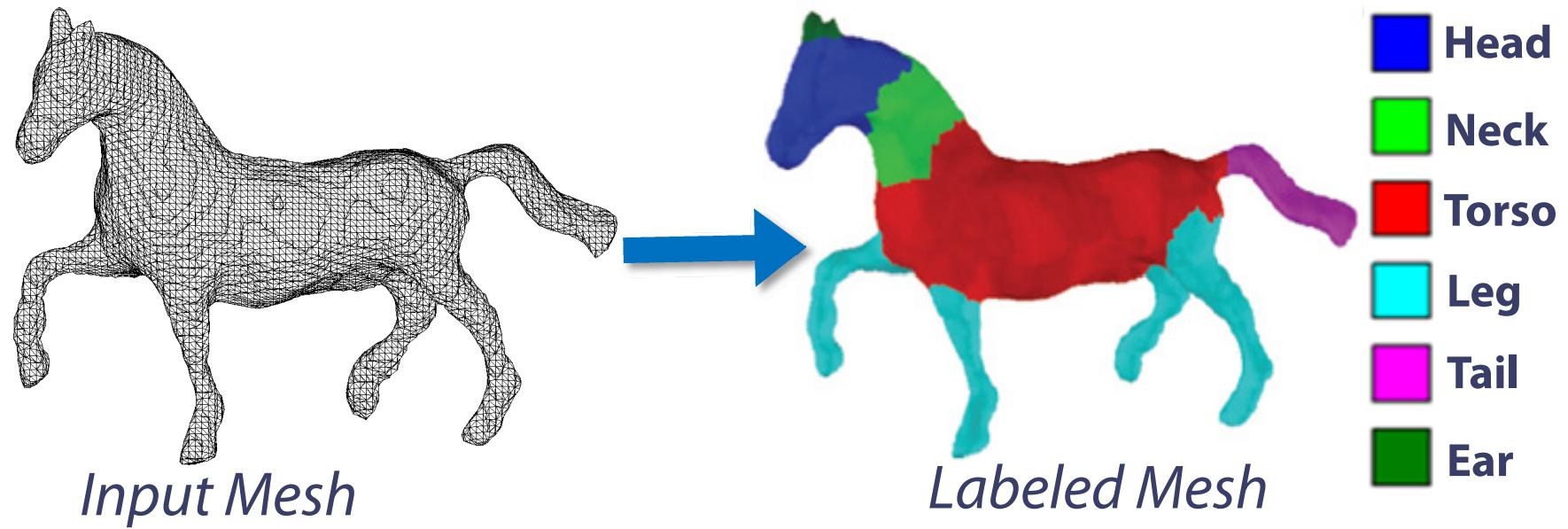


Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

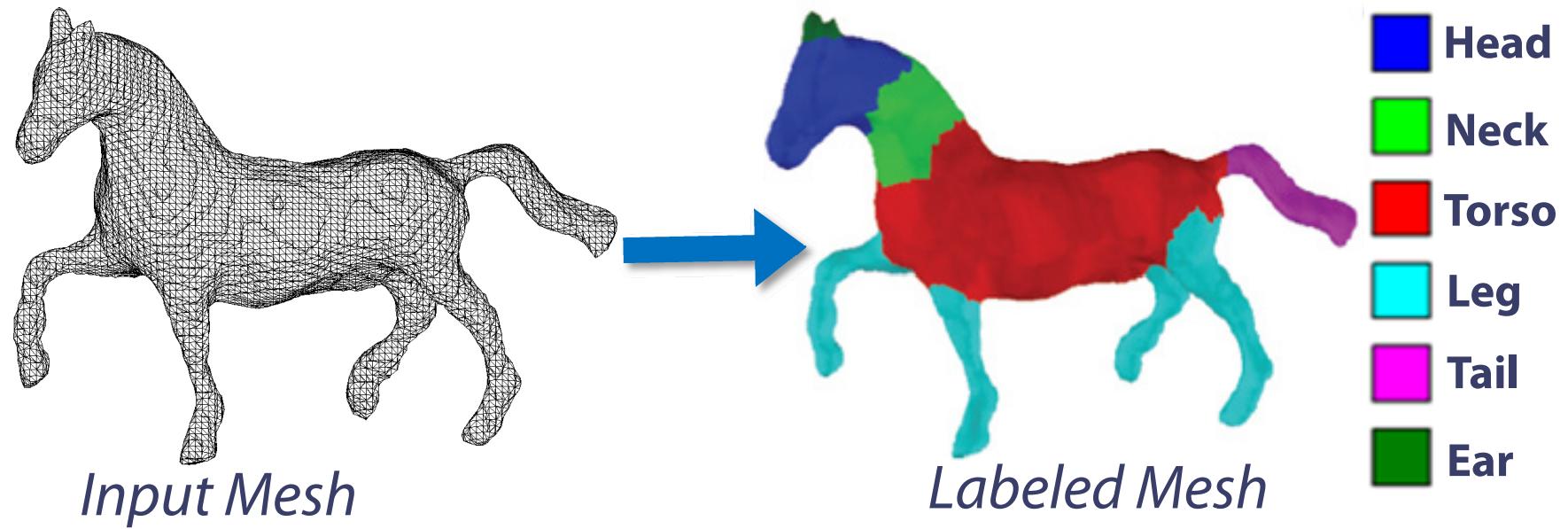
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Unary term

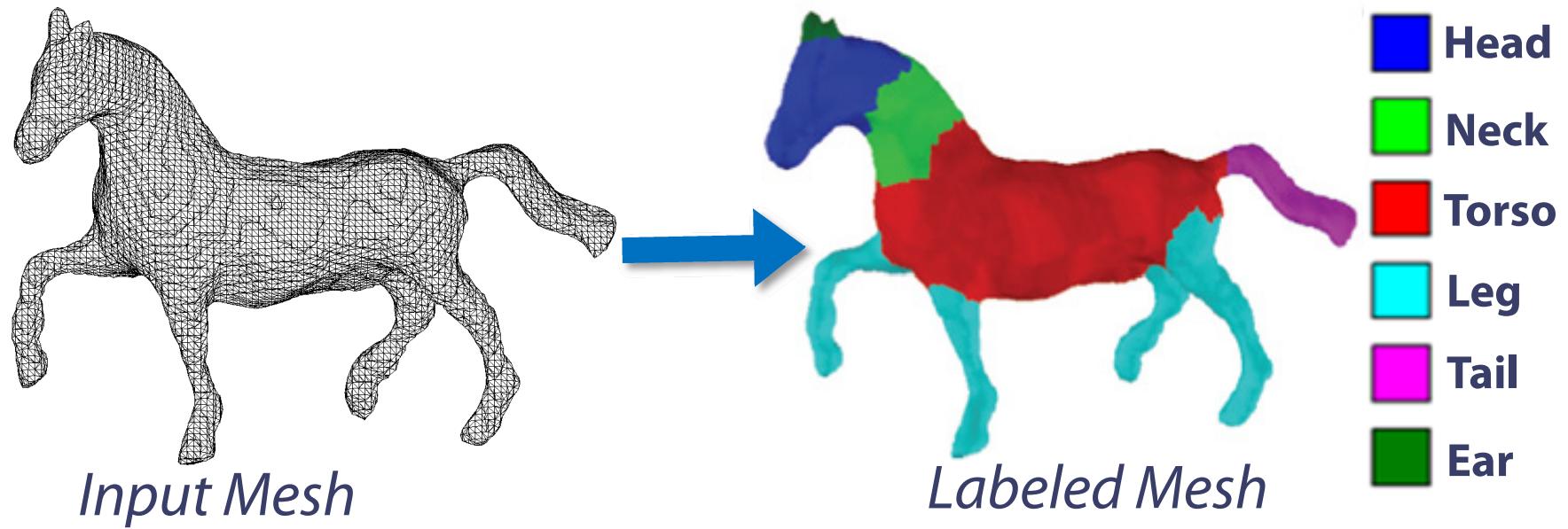
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Face features

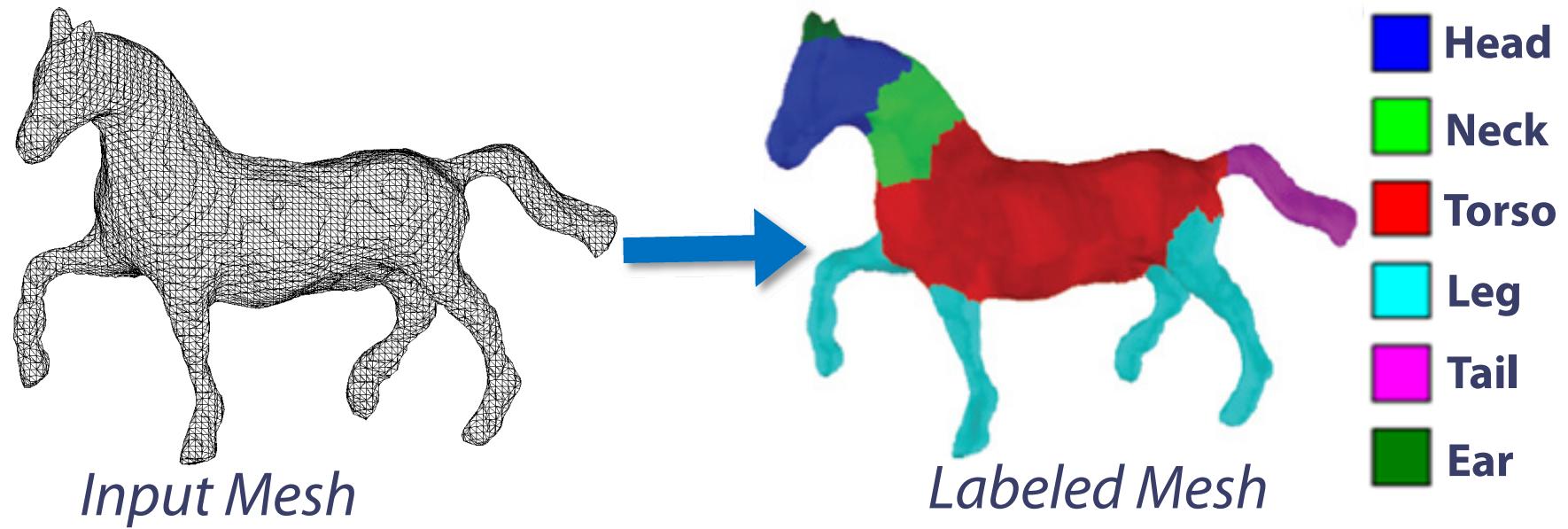
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Face Area

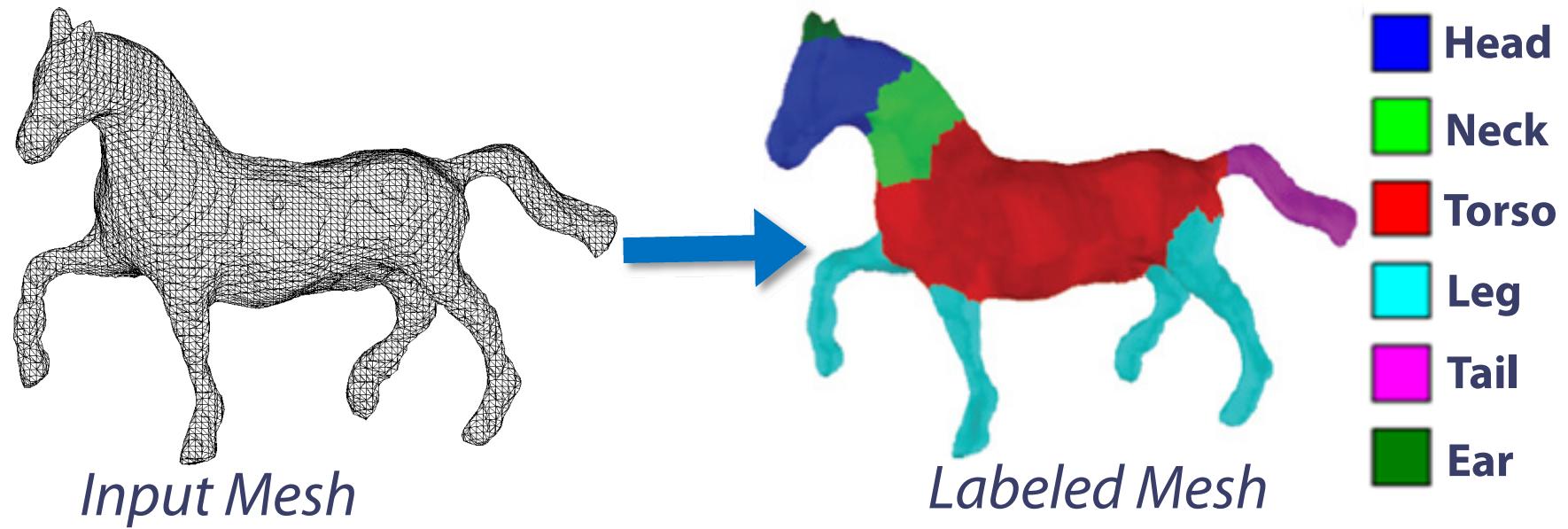
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Pairwise Term

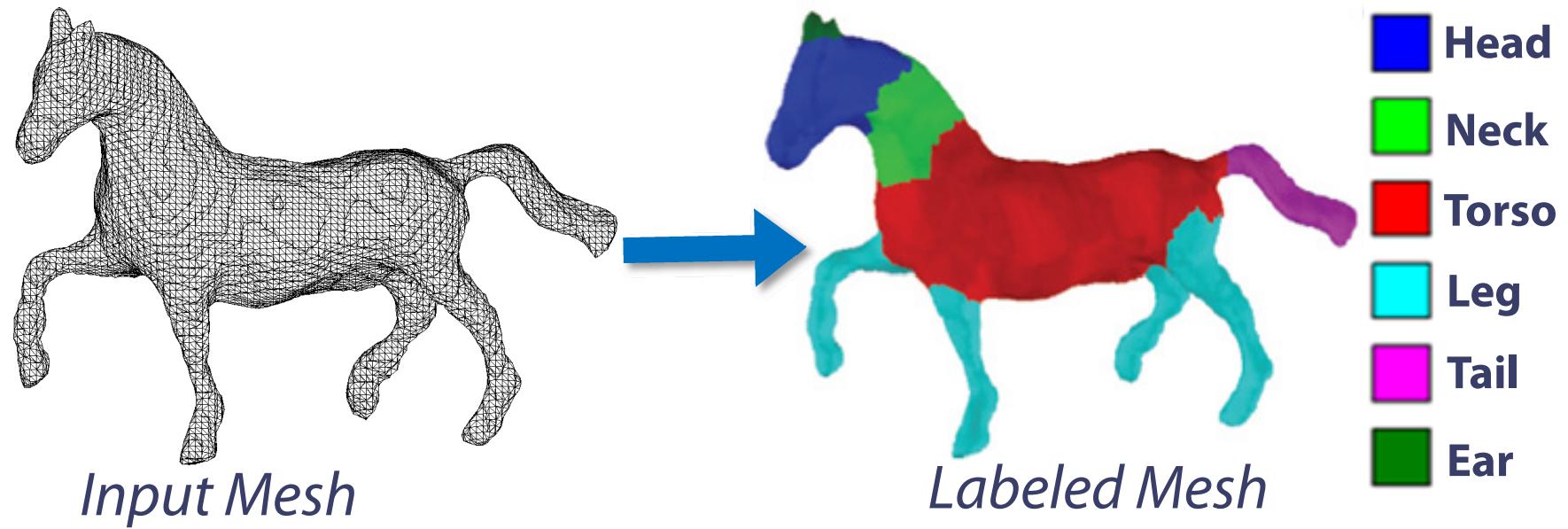
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Edge Features

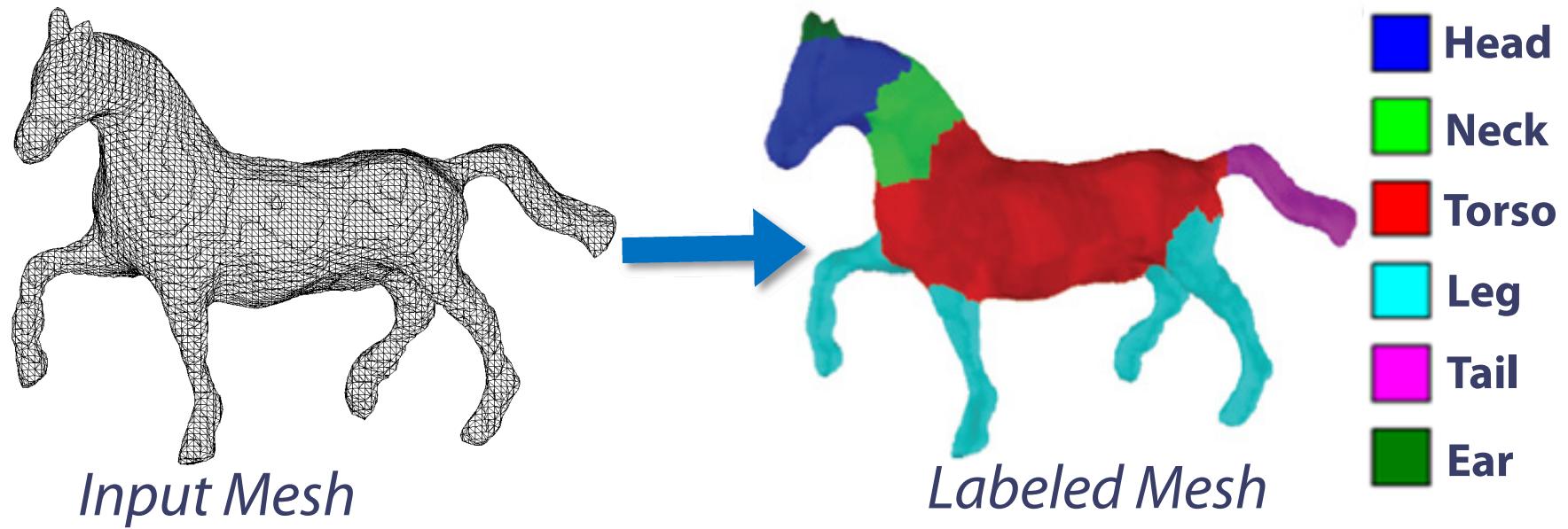
Conditional Random Field for Labeling



$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Edge Length

Conditional Random Field for Labeling

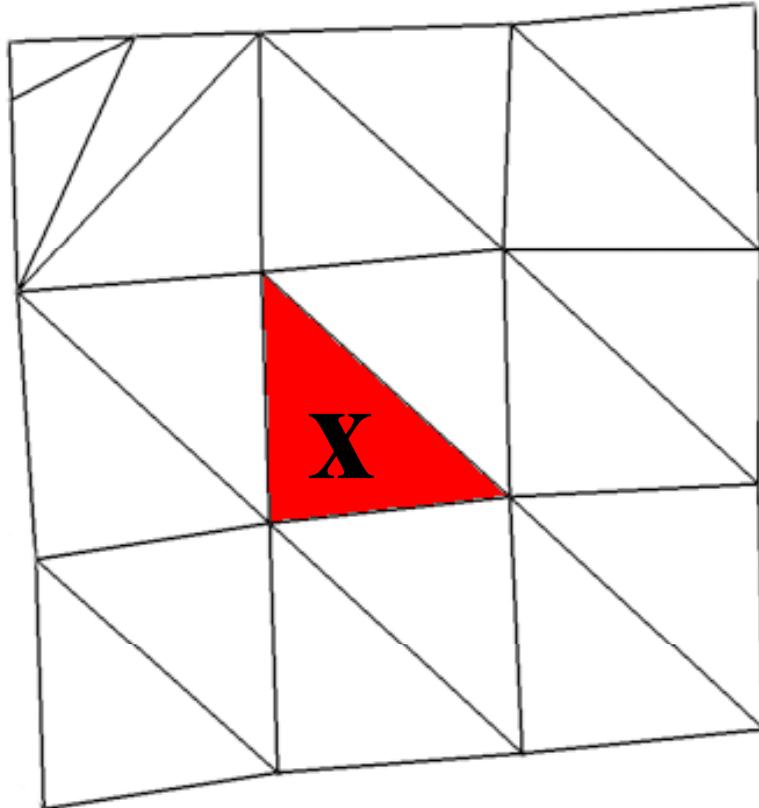


$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Unary term

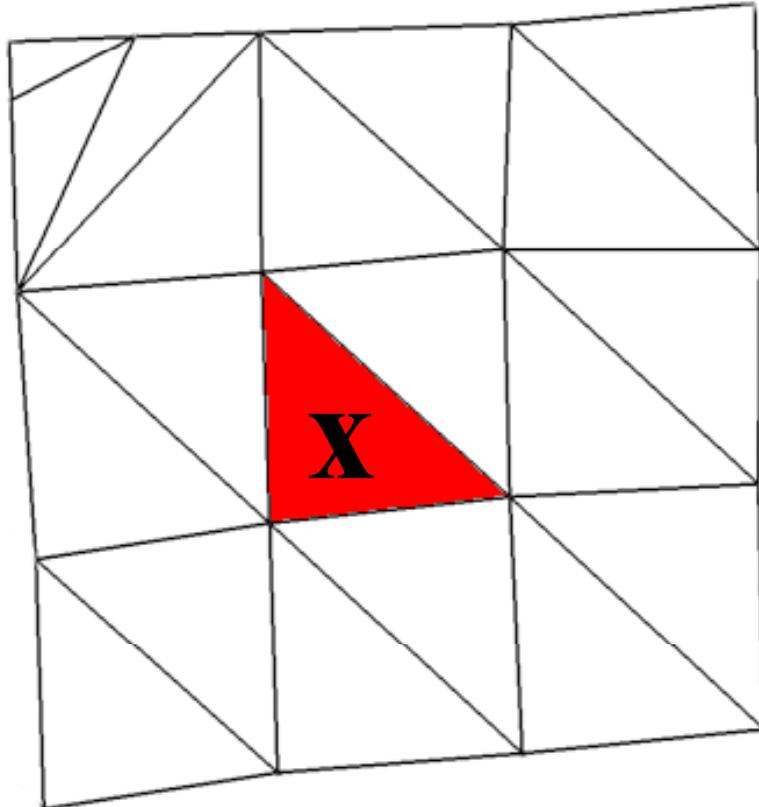
Feature vector

$$\mathbf{x} \in \Re^{375+35|C|} \rightarrow P(c \mid \mathbf{x})$$



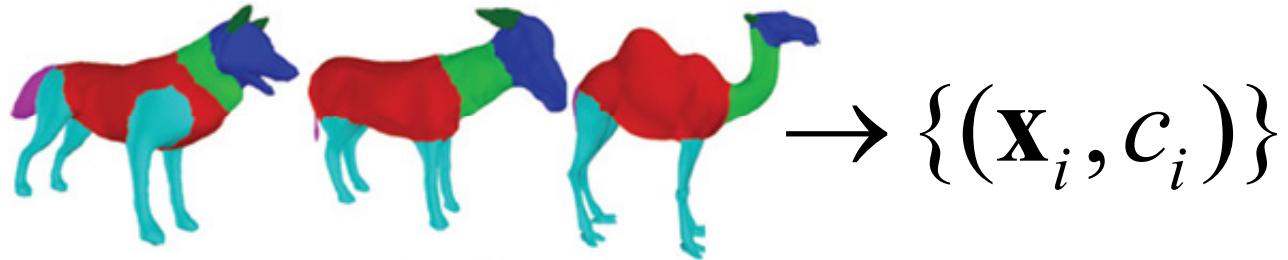
Feature vector

$$\mathbf{x} \in \Re^{375+35|C|} \rightarrow P(c \mid \mathbf{x})$$

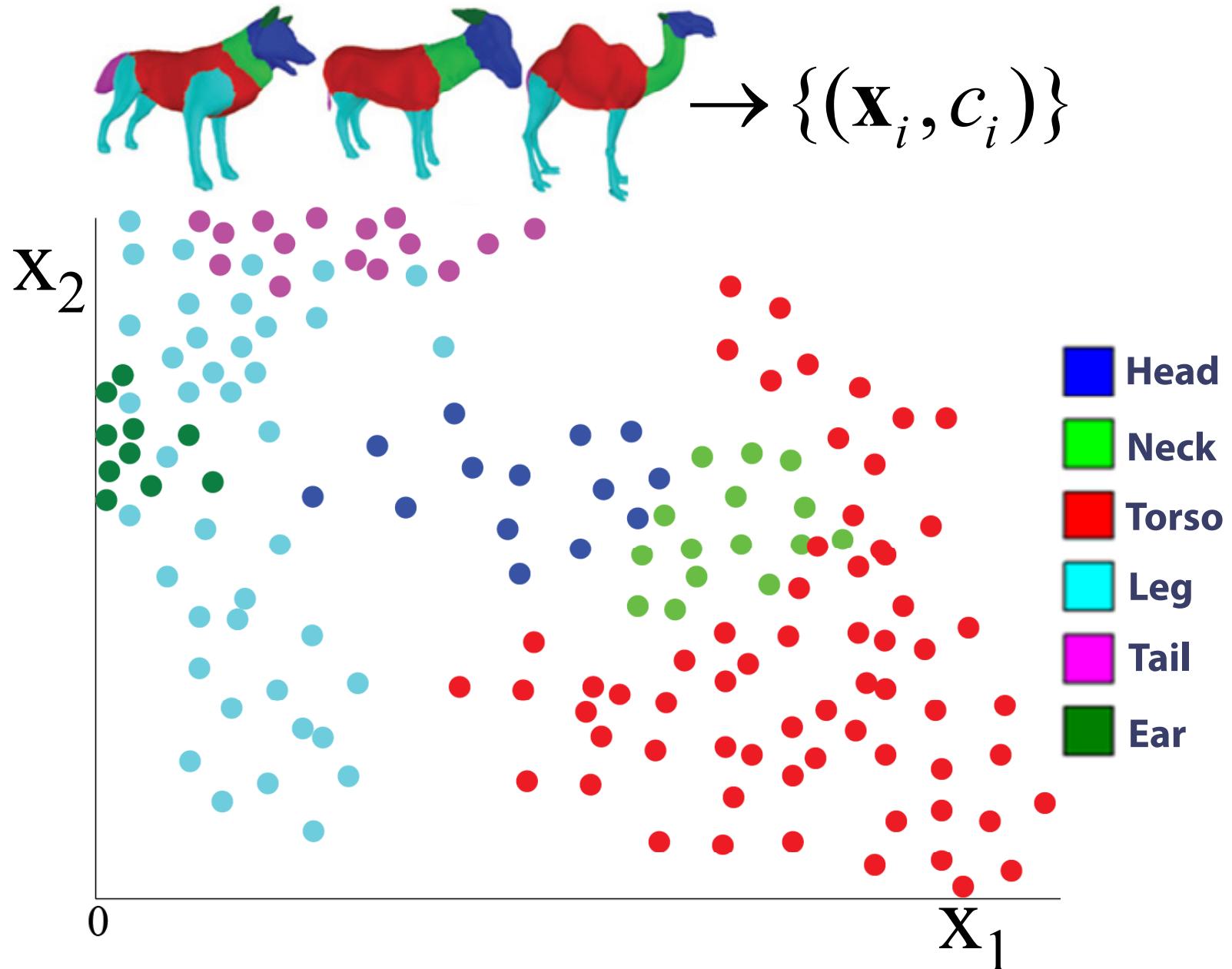


surface curvature
singular values from PCA
shape diameter
distances from medial surface
average geodesic distances
shape contexts
spin images
contextual label features

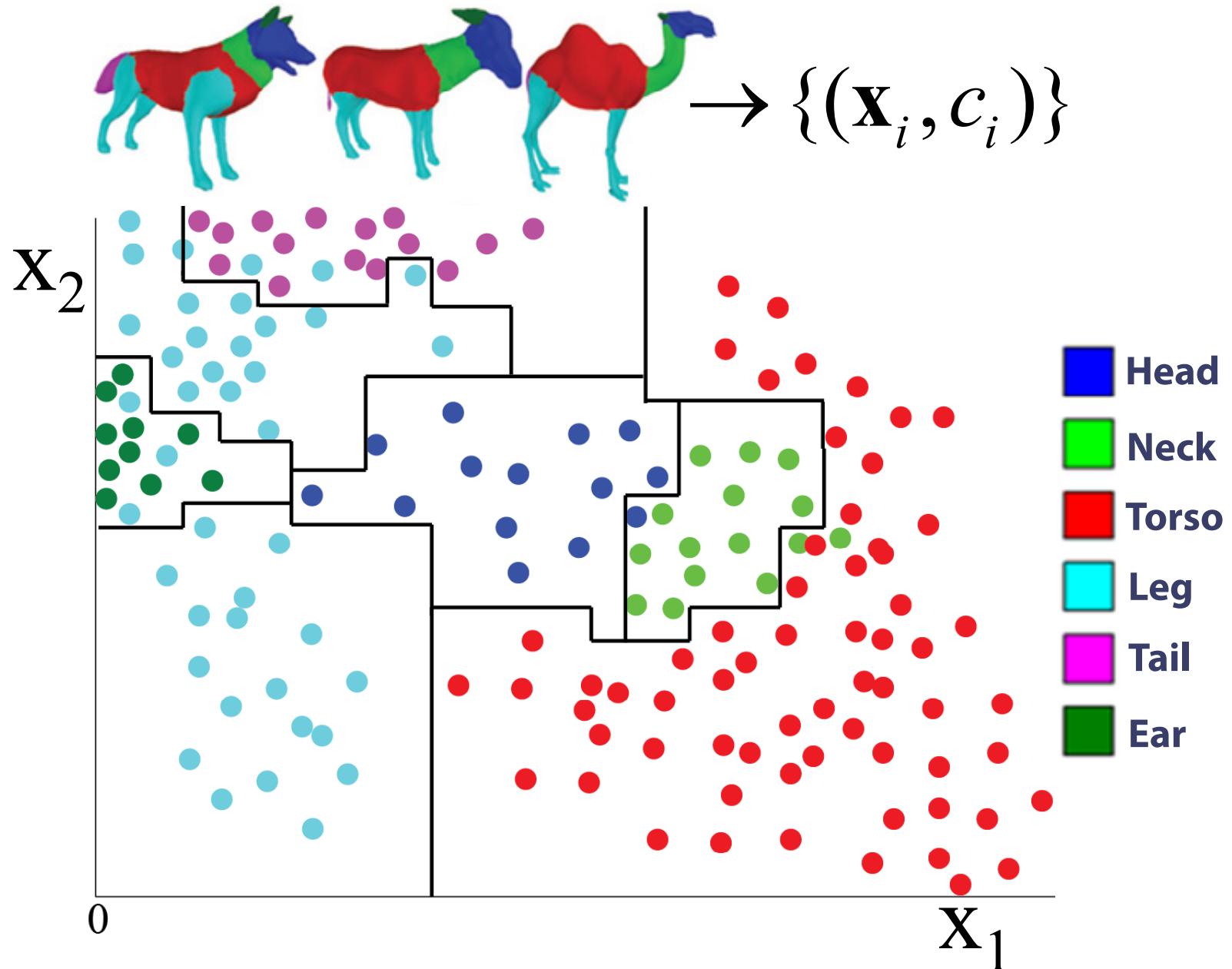
Learning a classifier



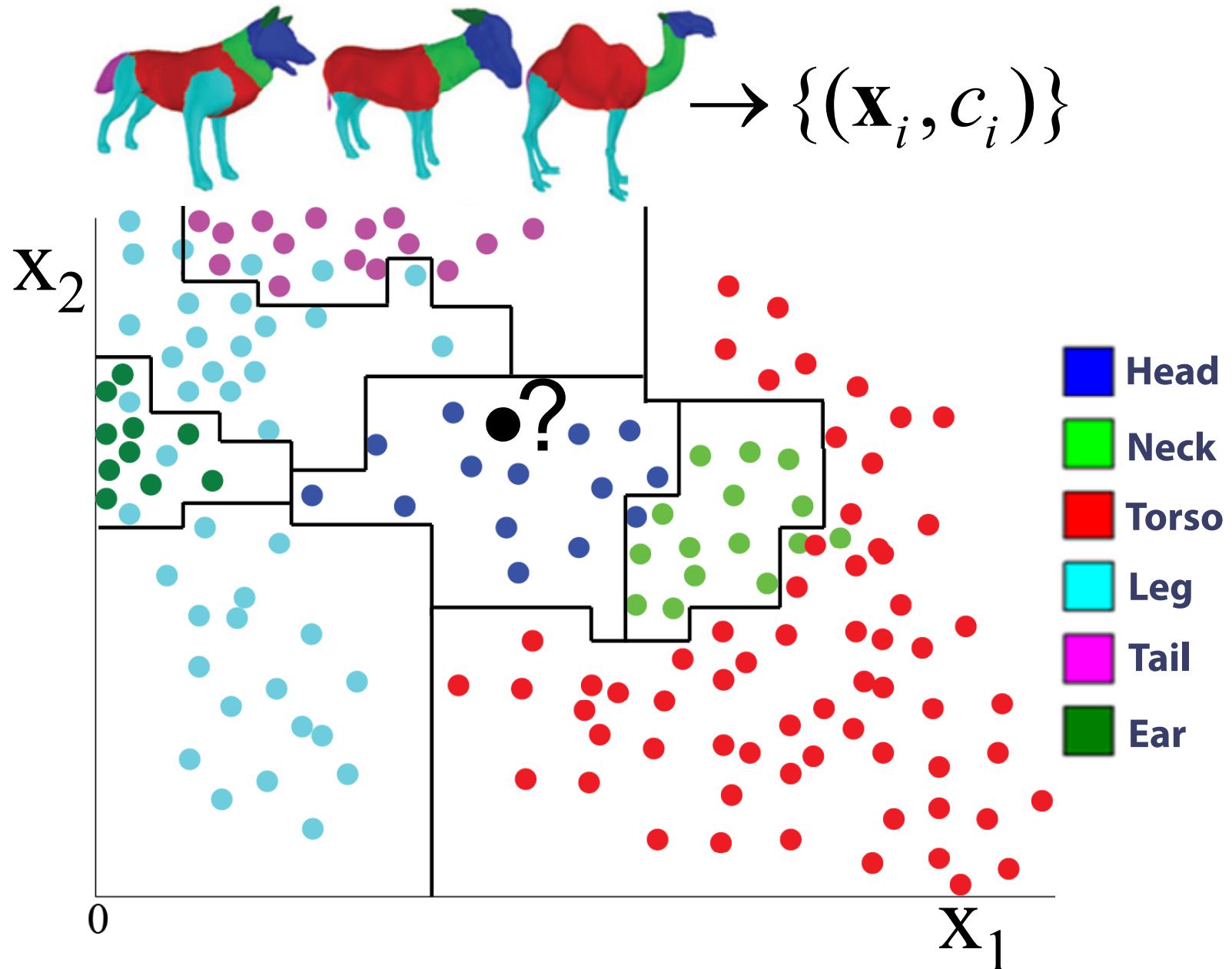
Learning a classifier



Learning a classifier

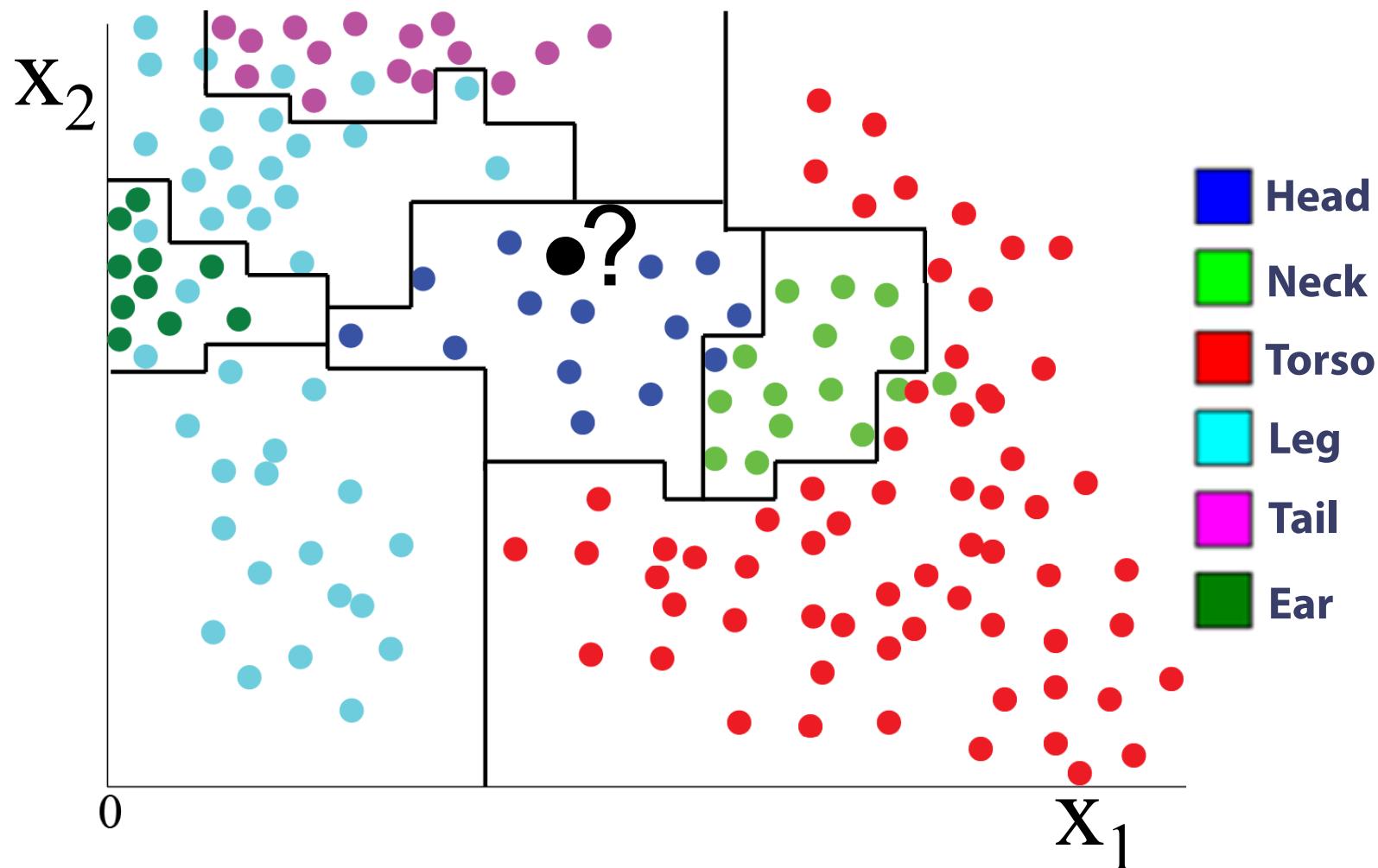


Learning a classifier

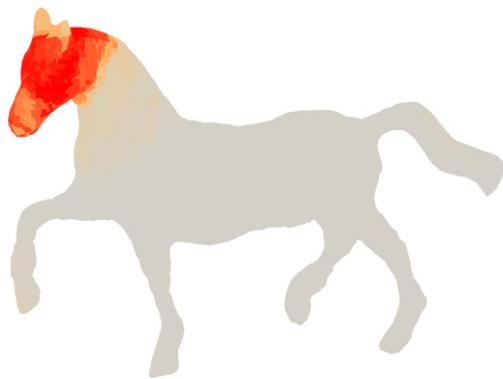


Learning a classifier

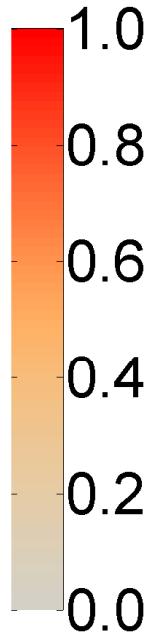
We use the Jointboost classifier [Torralba et al. 2007]



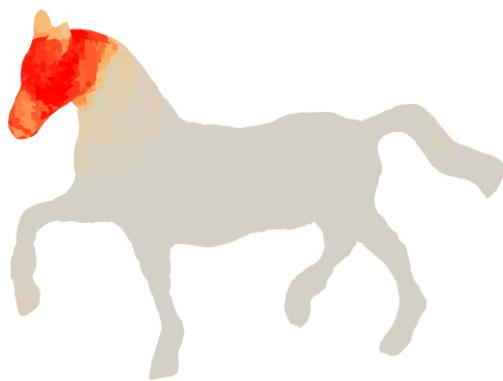
Unary term



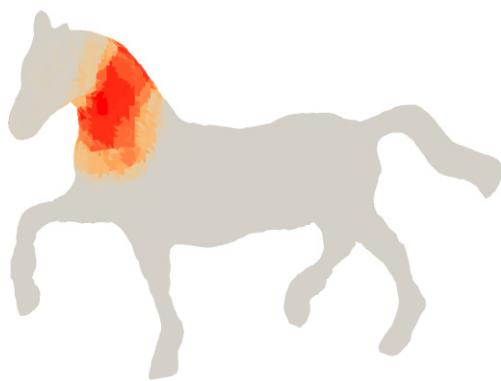
$P(\text{head} \mid \mathbf{x})$



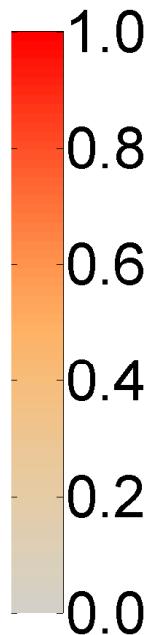
Unary term



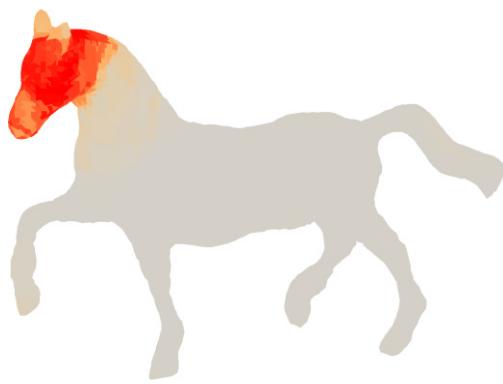
$P(\text{head} \mid \mathbf{x})$



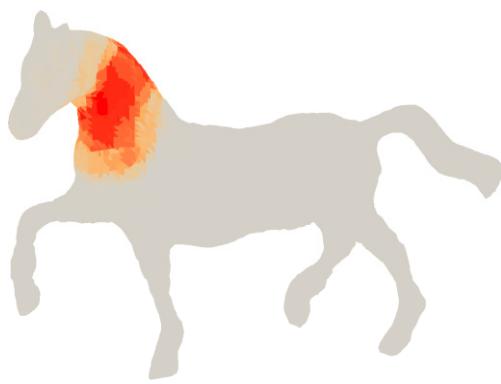
$P(\text{neck} \mid \mathbf{x})$



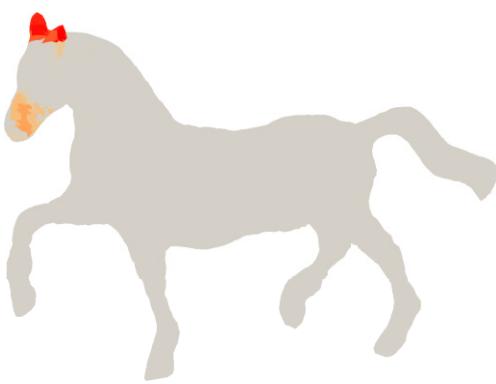
Unary term



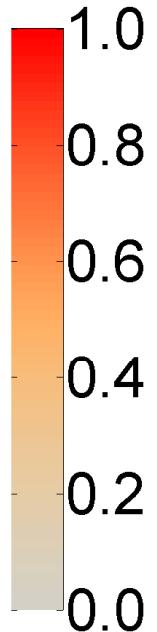
$P(\text{head} \mid \mathbf{x})$



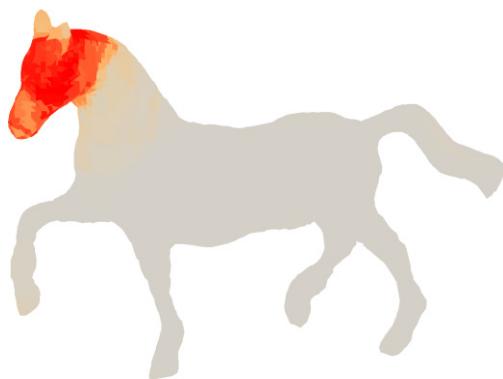
$P(\text{neck} \mid \mathbf{x})$



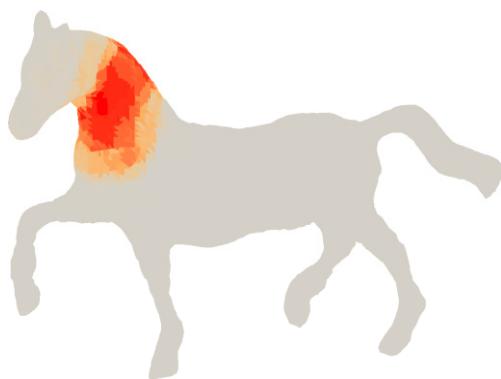
$P(\text{ear} \mid \mathbf{x})$



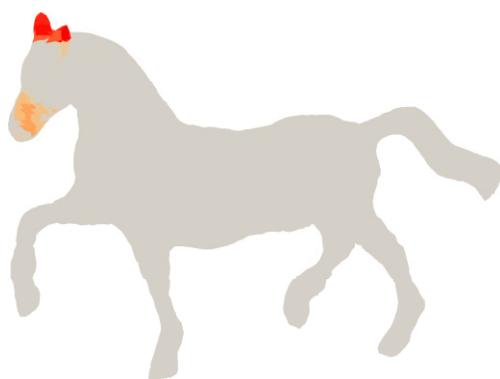
Unary term



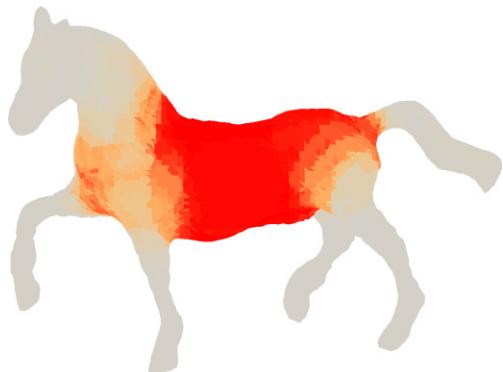
$$P(\text{head} \mid \mathbf{x})$$



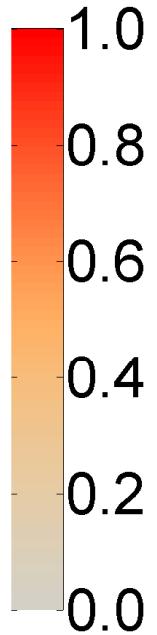
$$P(\text{neck} \mid \mathbf{x})$$



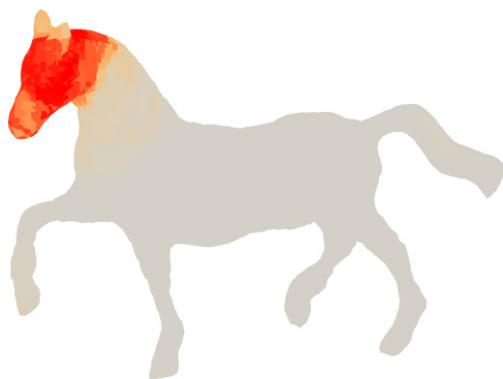
$$P(\text{ear} \mid \mathbf{x})$$



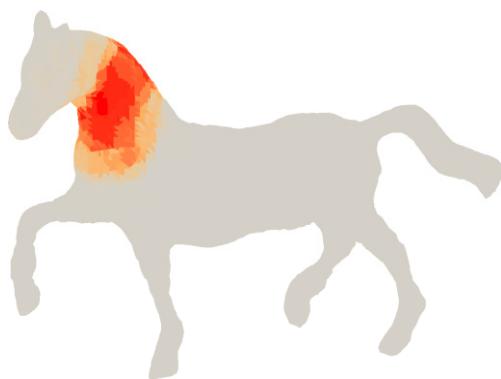
$$P(\text{torso} \mid \mathbf{x})$$



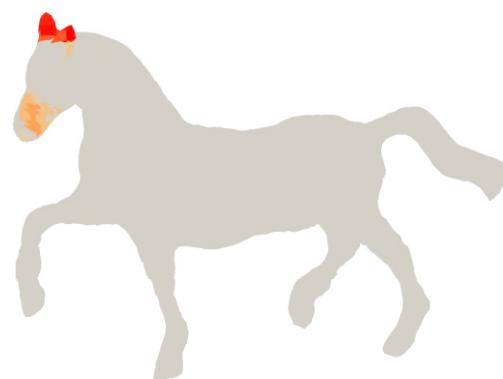
Unary term



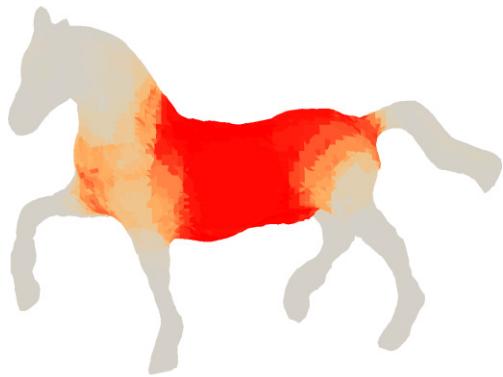
$$P(\text{head} \mid \mathbf{x})$$



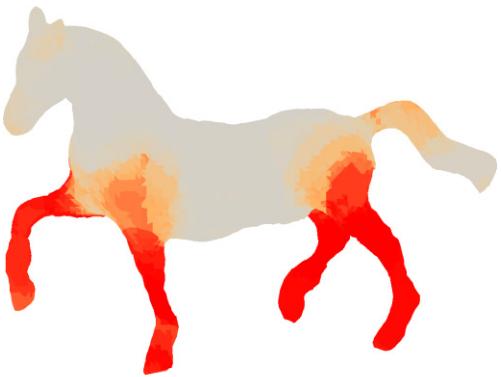
$$P(\text{neck} \mid \mathbf{x})$$



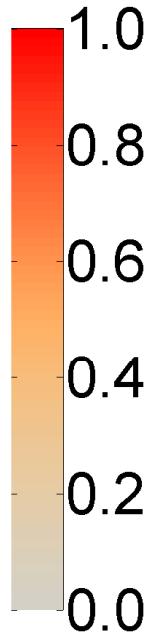
$$P(\text{ear} \mid \mathbf{x})$$



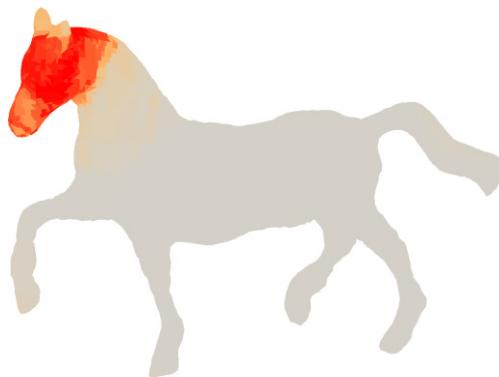
$$P(\text{torso} \mid \mathbf{x})$$



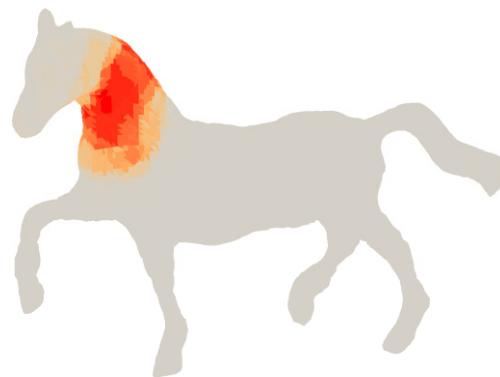
$$P(\text{leg} \mid \mathbf{x})$$



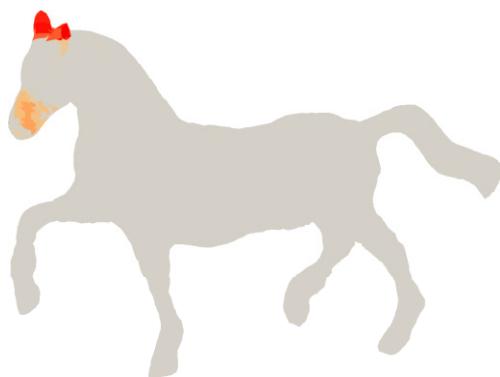
Unary term



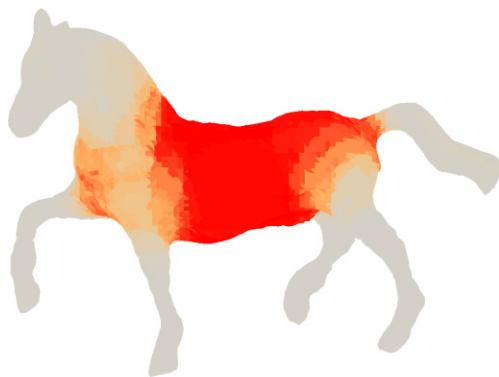
$$P(\text{head} \mid \mathbf{x})$$



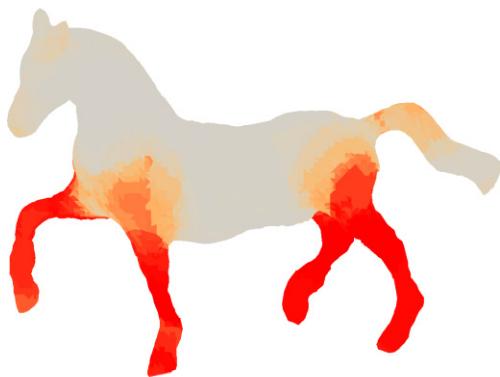
$$P(\text{neck} \mid \mathbf{x})$$



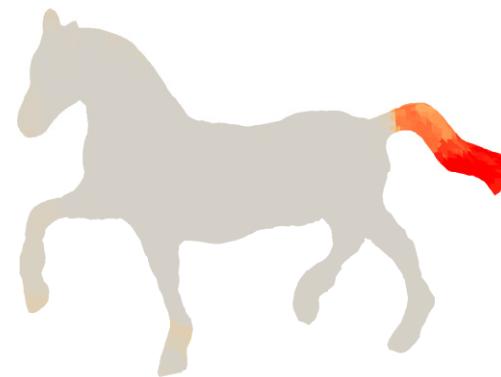
$$P(\text{ear} \mid \mathbf{x})$$



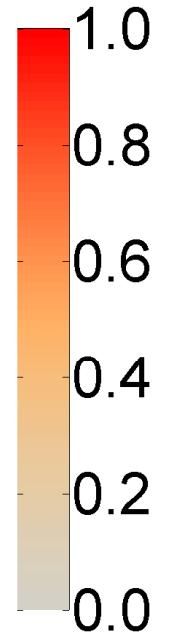
$$P(\text{torso} \mid \mathbf{x})$$



$$P(\text{leg} \mid \mathbf{x})$$

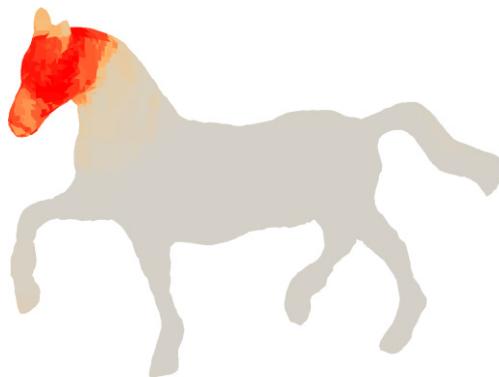


$$P(\text{tail} \mid \mathbf{x})$$

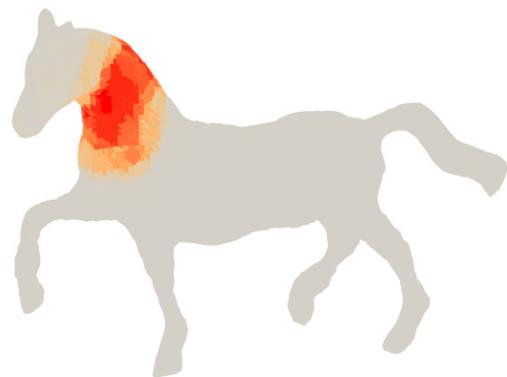


Unary term

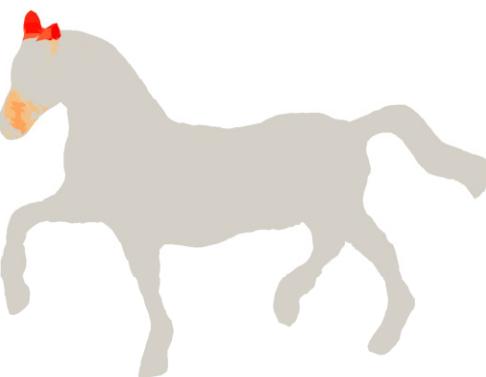
$$E_1(c; \mathbf{x}) = -\log P(c | \mathbf{x})$$



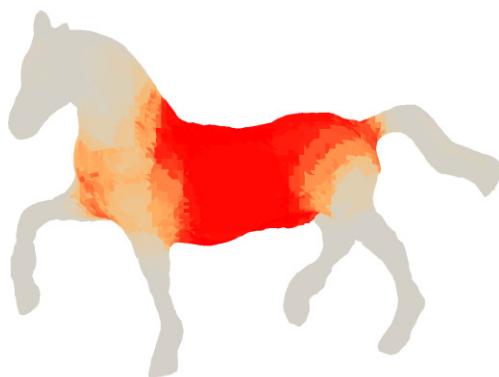
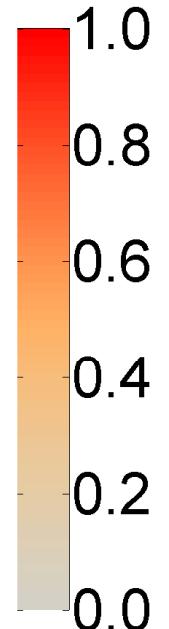
$P(\text{head} | \mathbf{x})$



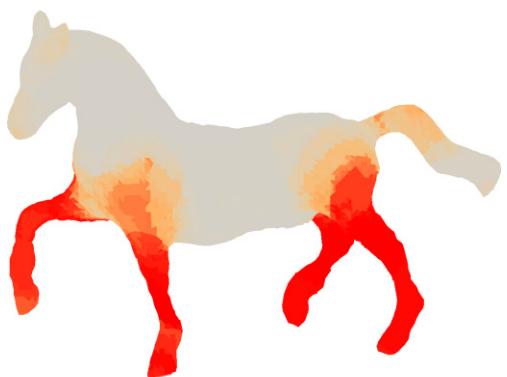
$P(\text{neck} | \mathbf{x})$



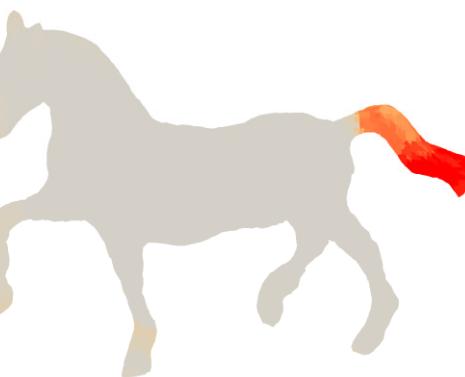
$P(\text{ear} | \mathbf{x})$



$P(\text{torso} | \mathbf{x})$

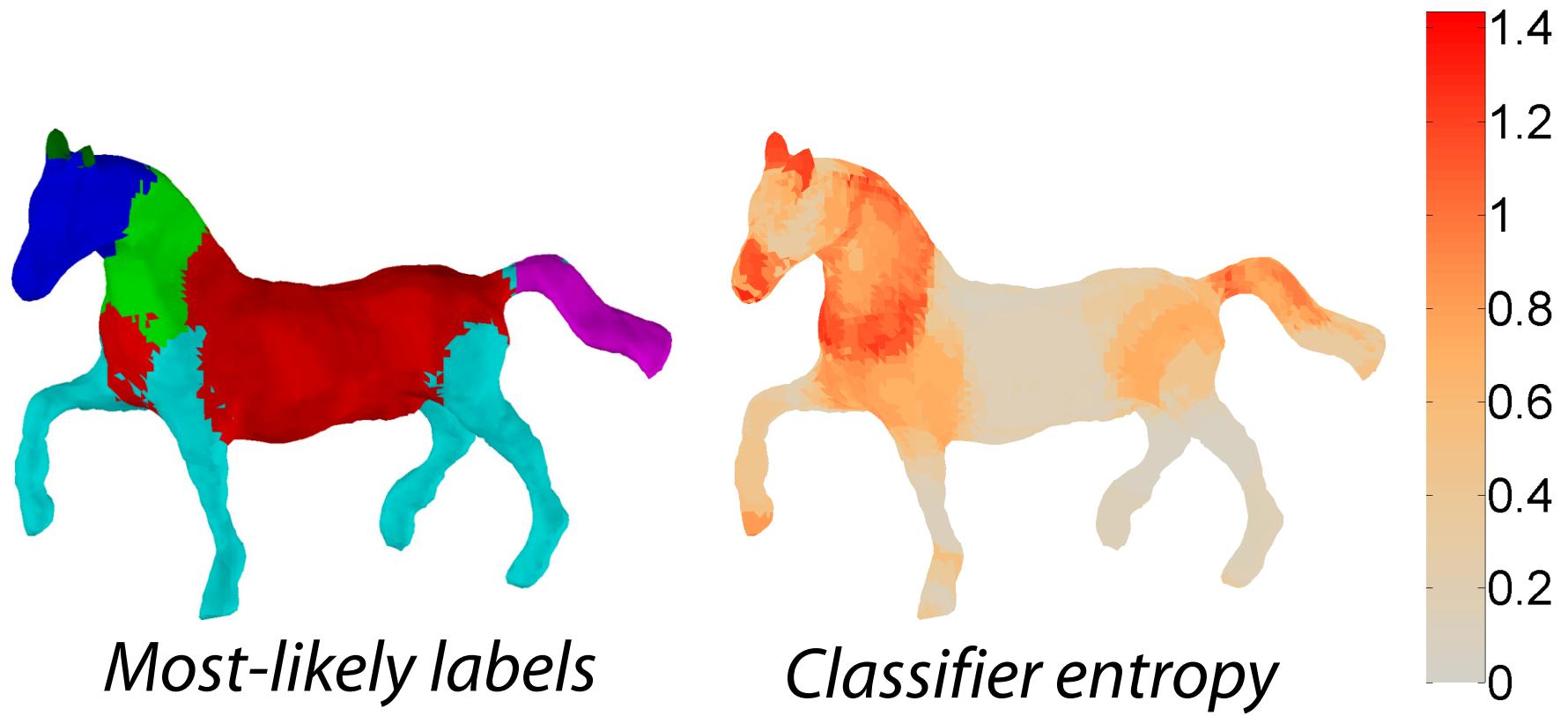


$P(\text{leg} | \mathbf{x})$

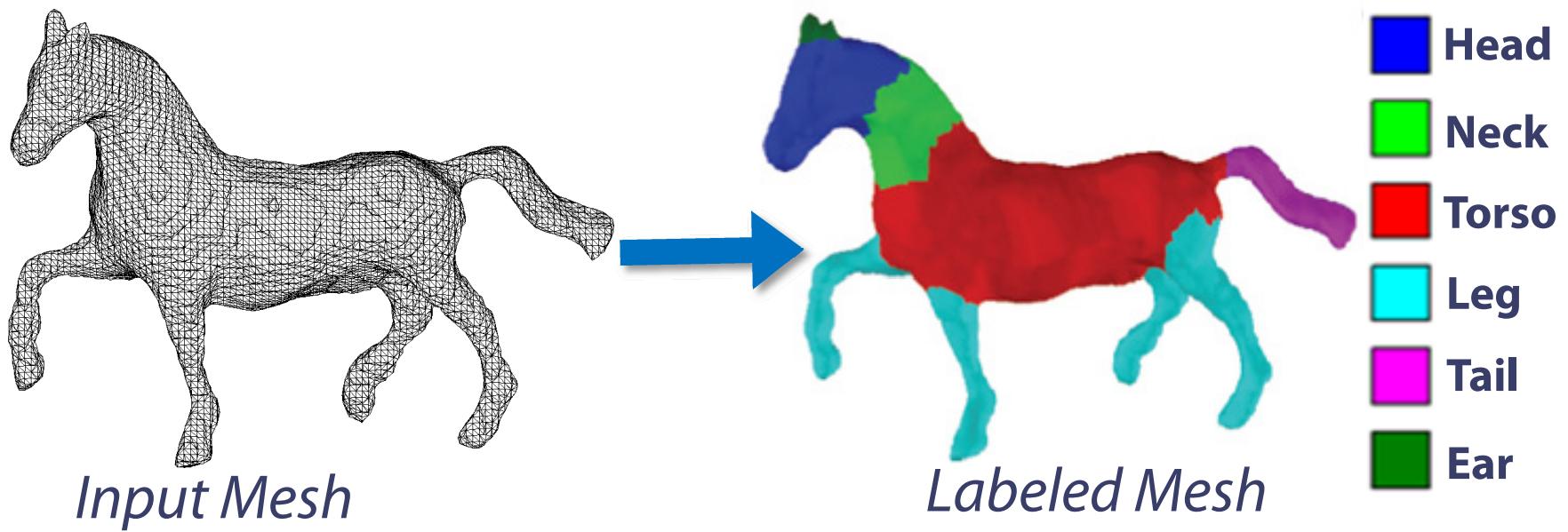


$P(\text{tail} | \mathbf{x})$

Unary Term



Our approach



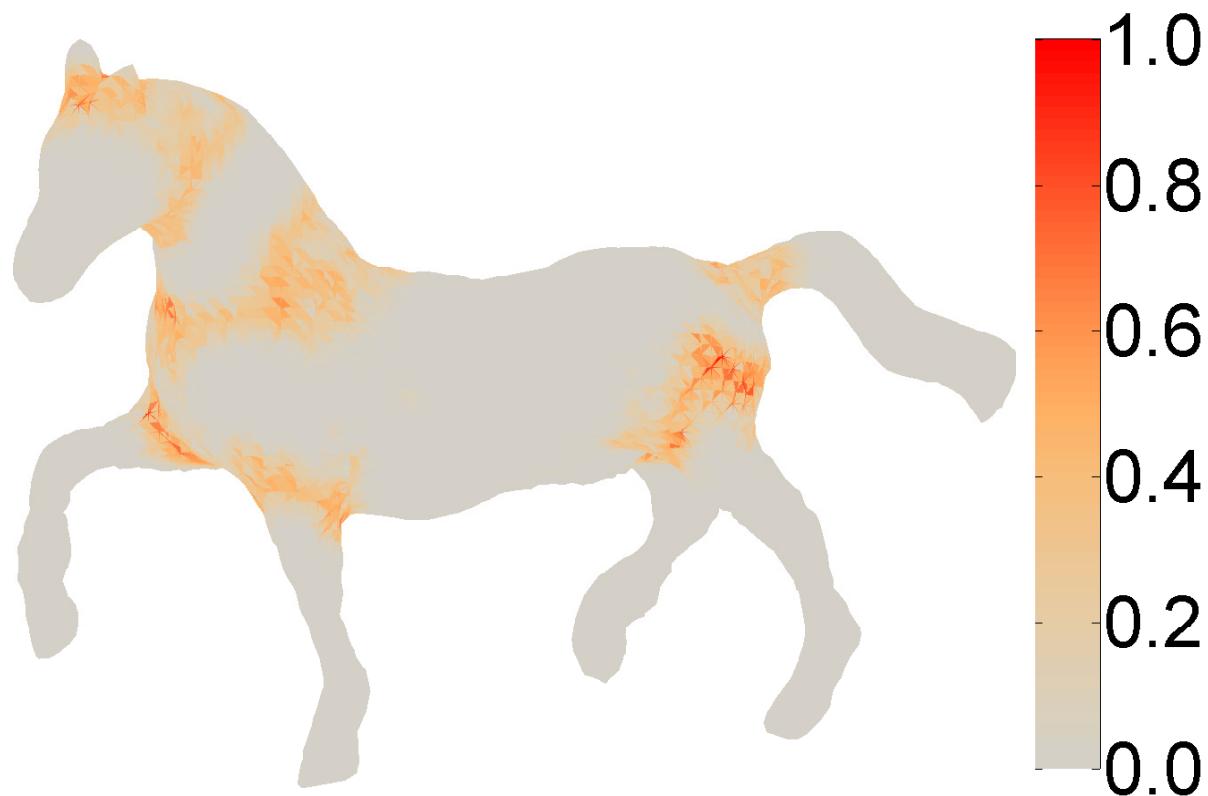
$$c^* = \arg \min_c \left\{ \sum_i \alpha_i E_1(c_i; \mathbf{x}_i) + \sum_{i,j} l_{ij} E_2(c_i, c_j; \mathbf{y}_{ij}) \right\}$$

Pairwise Term

Pairwise Term

$$E_2(c, c'; \mathbf{y}, \theta_2) = G(\mathbf{y}) L(c, c')$$

Geometry-dependent term



Pairwise Term

$$E_2(c, c'; \mathbf{y}, \theta_2) = G(\mathbf{y}) L(c, c')$$

Label compatibility term

Pairwise Term

$$E_2(c, c'; \mathbf{y}, \theta_2) = G(\mathbf{y}) L(c, c')$$

Label compatibility term

$$L(c, c') = \begin{bmatrix} \text{Head} & \text{Neck} & \text{Ear} & \text{Torso} & \text{Leg} & \text{Tail} \\ 0 & .45 & .07 & 1 & \infty & \infty \\ .45 & 0 & \infty & 1 & \infty & \infty \\ .07 & \infty & 0 & \infty & \infty & \infty \\ 1 & 1 & \infty & 0 & 1 & .56 \\ \infty & \infty & \infty & 1 & 0 & \infty \\ \infty & \infty & \infty & .56 & \infty & 0 \end{bmatrix} \begin{array}{l} \text{Head} \\ \text{Neck} \\ \text{Ear} \\ \text{Torso} \\ \text{Leg} \\ \text{Tail} \end{array}$$

Pairwise Term

$$E_2(c, c'; \mathbf{y}, \theta_2) = G(\mathbf{y}) L(c, c')$$

Label compatibility term

$$L(c, c') = \begin{bmatrix} \text{Head} & \text{Neck} & \text{Ear} & \text{Torso} & \text{Leg} & \text{Tail} \\ \text{Head} & 0 & .45 & .07 & 1 & \infty & \infty \\ \text{Neck} & .45 & 0 & \infty & 1 & \infty & \infty \\ \text{Ear} & .07 & \infty & 0 & \infty & \infty & \infty \\ \text{Torso} & 1 & 1 & \infty & 0 & 1 & .56 \\ \text{Leg} & \infty & \infty & \infty & 1 & 0 & \infty \\ \text{Tail} & \infty & \infty & \infty & .56 & \infty & 0 \end{bmatrix}$$

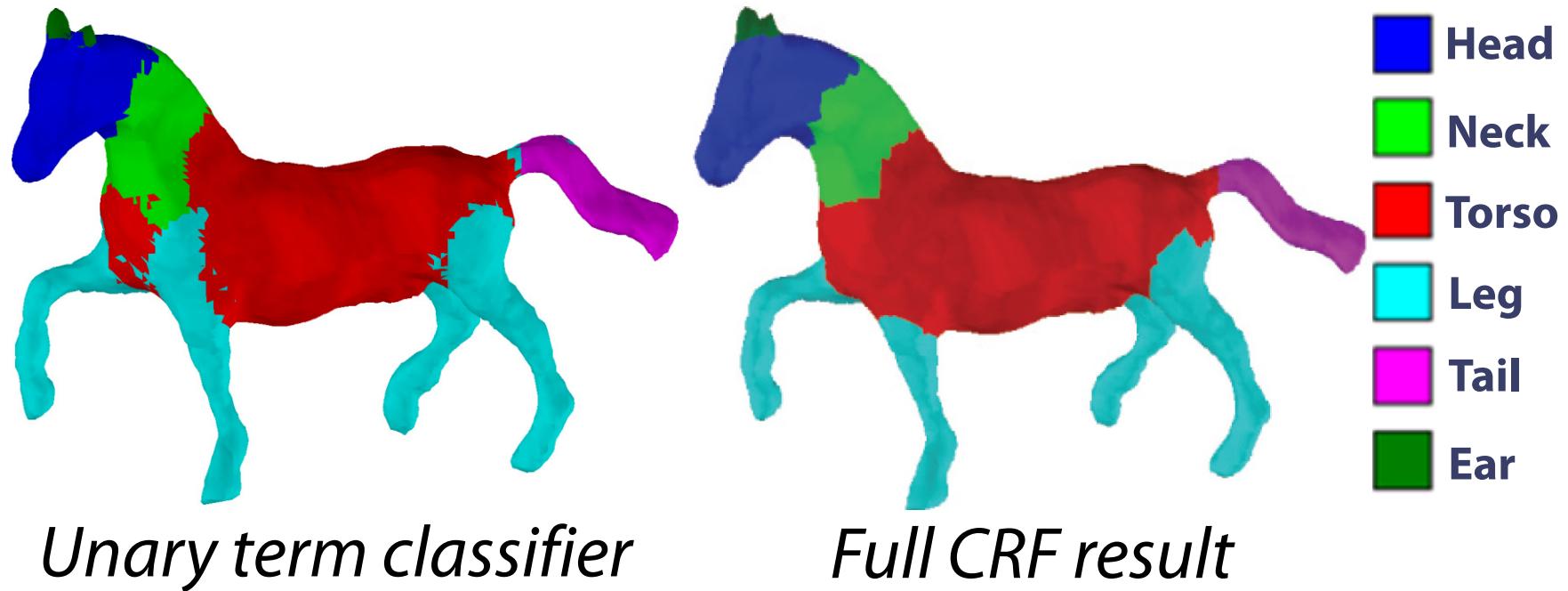
Pairwise Term

$$E_2(c, c'; \mathbf{y}, \theta_2) = G(\mathbf{y}) L(c, c')$$

Label compatibility term

$$L(c, c') = \begin{bmatrix} \text{Head} & \text{Neck} & \text{Ear} & \text{Torso} & \text{Leg} & \text{Tail} \\ 0 & .45 & .07 & 1 & \infty & \infty \\ .45 & 0 & \infty & 1 & \infty & \infty \\ .07 & \infty & 0 & \infty & \infty & \infty \\ 1 & 1 & \infty & 0 & 1 & .56 \\ \infty & \infty & \infty & 1 & 0 & \infty \\ \infty & \infty & \infty & .56 & \infty & 0 \end{bmatrix} \begin{array}{l} \text{Head} \\ \text{Neck} \\ \text{Ear} \\ \text{Torso} \\ \text{Leg} \\ \text{Tail} \end{array}$$

Full CRF result



Learning

Learning

Learn unary classifier and $G(y)$ with Joint Boosting
[Torralba et al. 2007]

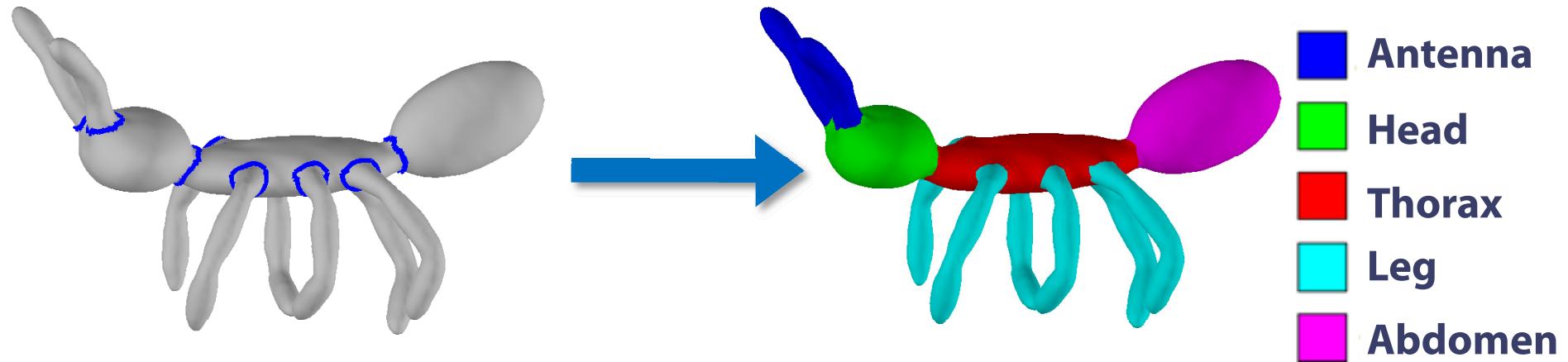
Learning

Learn unary classifier and $G(y)$ with Joint Boosting
[Torralba et al. 2007]

Hold-out validation for the rest of parameters

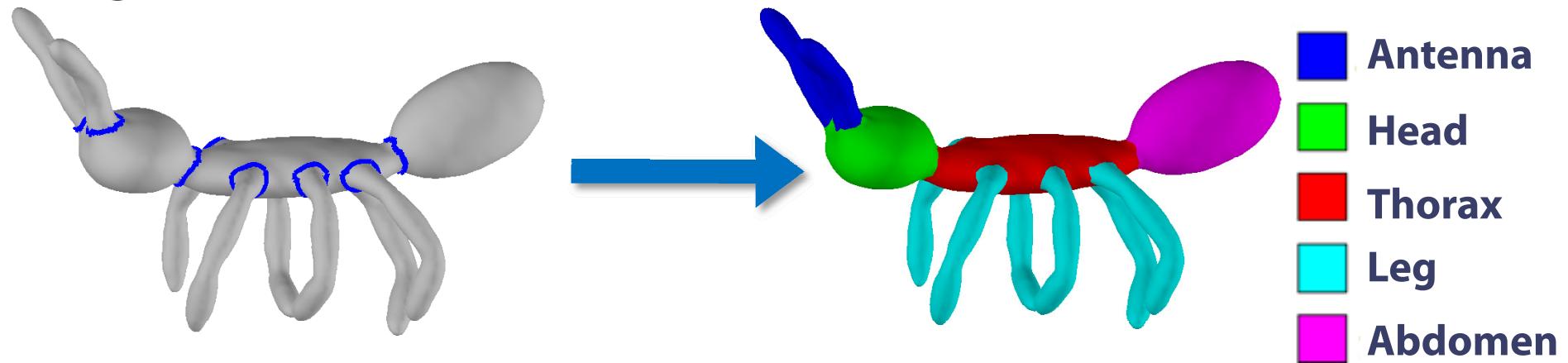
Dataset used in experiments

We label 380 meshes from the Princeton Segmentation Benchmark [**Chen et al. 2009**]



Dataset used in experiments

We label 380 meshes from the Princeton Segmentation Benchmark [**Chen et al. 2009**]



Each of the 19 categories is treated separately

Quantitative Evaluation

Labeling

- **6%** error by surface area

Quantitative Evaluation

Labeling

- **6%** error by surface area
- No previous automatic method

Quantitative Evaluation

Labeling

- **6%** error by surface area
- No previous automatic method

Segmentation

- Our result: **9.5%** Rand Index error

Quantitative Evaluation

Labeling

- **6%** error by surface area
- No previous automatic method

Segmentation

- Our result: **9.5%** Rand Index error
- State-of-the art: **16%** [Golovinskiy and Funkhouser 08]

Quantitative Evaluation

Labeling

- **6%** error by surface area
- No previous automatic method

Segmentation

- Our result: **9.5%** Rand Index error
- State-of-the art: **16%** [Golovinskiy and Funkhouser 08]
- With 6 training meshes: **12%**

Quantitative Evaluation

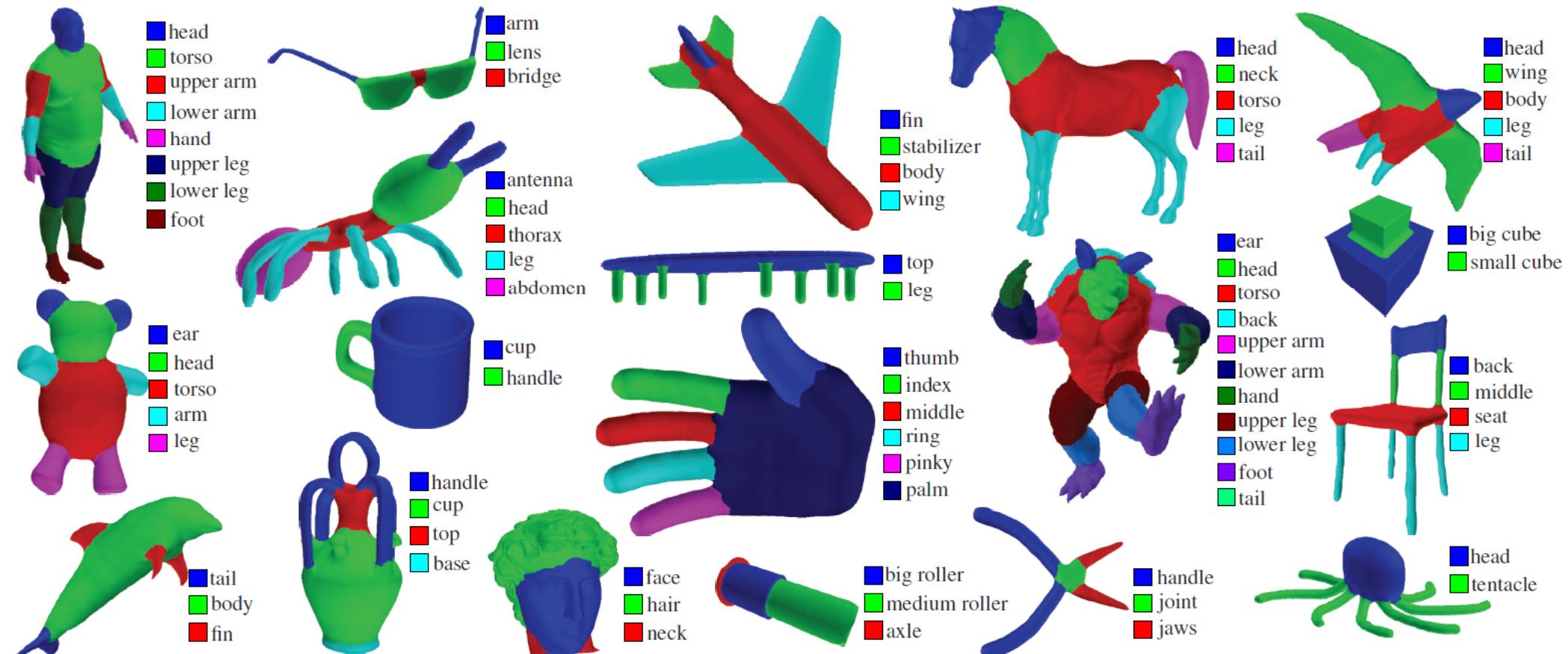
Labeling

- **6%** error by surface area
- No previous automatic method

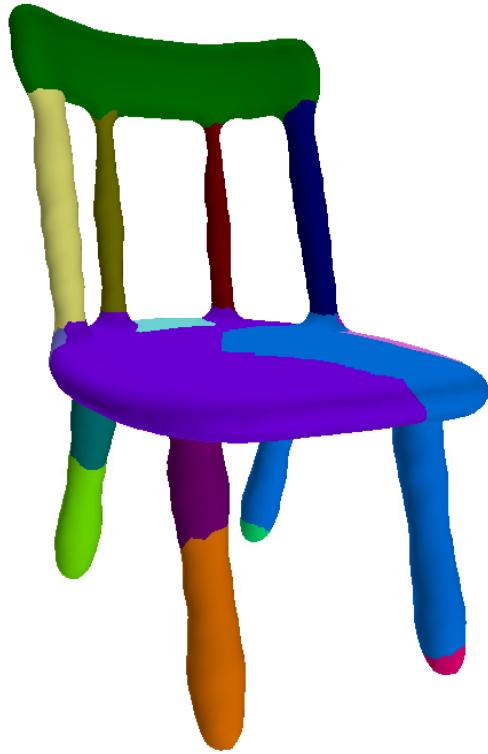
Segmentation

- Our result: **9.5%** Rand Index error
- State-of-the art: **16%** [Golovinskiy and Funkhouser 08]
- With 6 training meshes: **12%**
- With 3 training meshes: **15%**

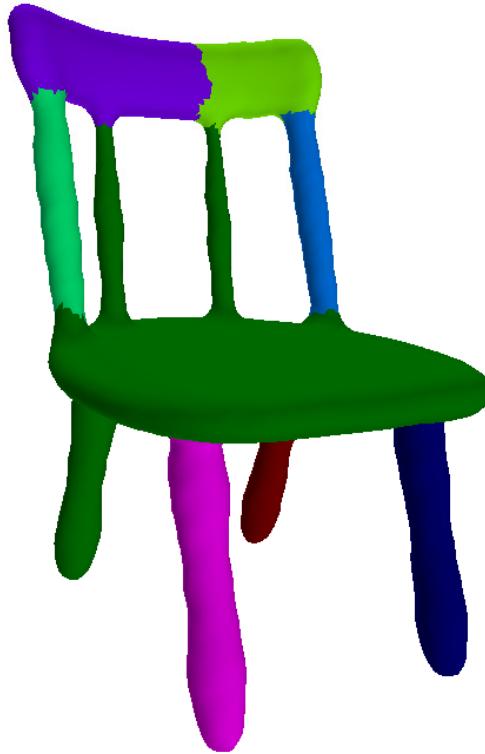
Labeling results



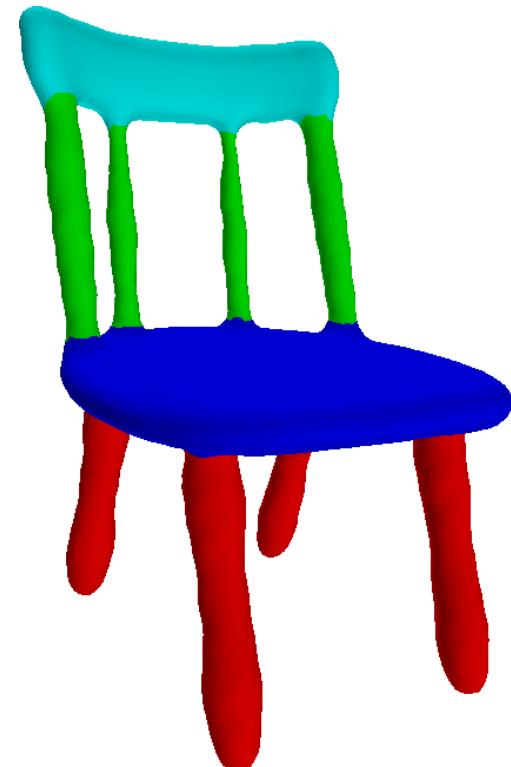
Segmentation Comparisons



Shape Diameter
[Shapira et al. 10]



Randomized Cuts
[Golovinskiy and
Funkhouser 08]



Our approach

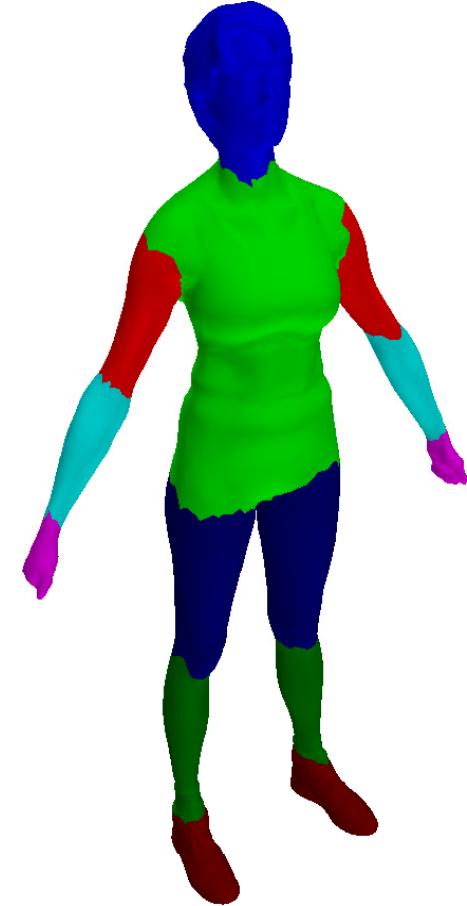
Segmentation Comparisons



Shape Diameter
[Shapira et al. 10]

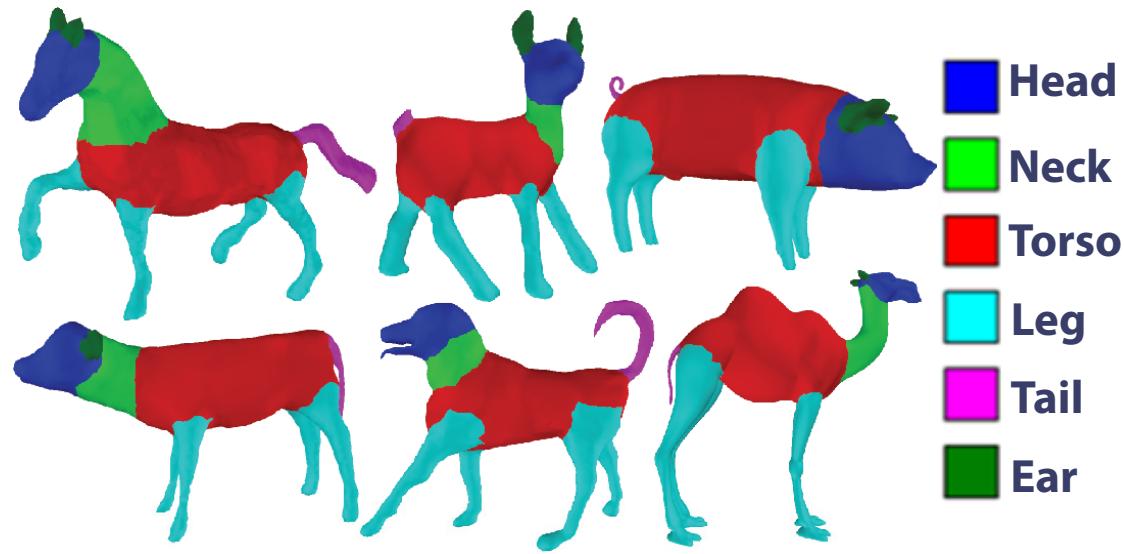


Randomized Cuts
[Golovinskiy and
Funkhouser 08]



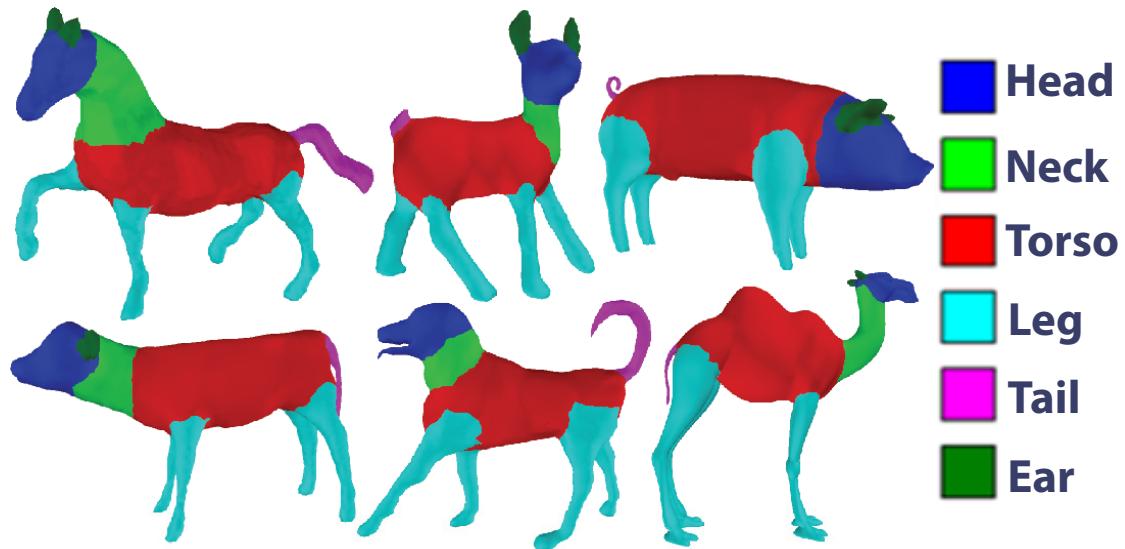
Our approach

Learning different segmentation styles

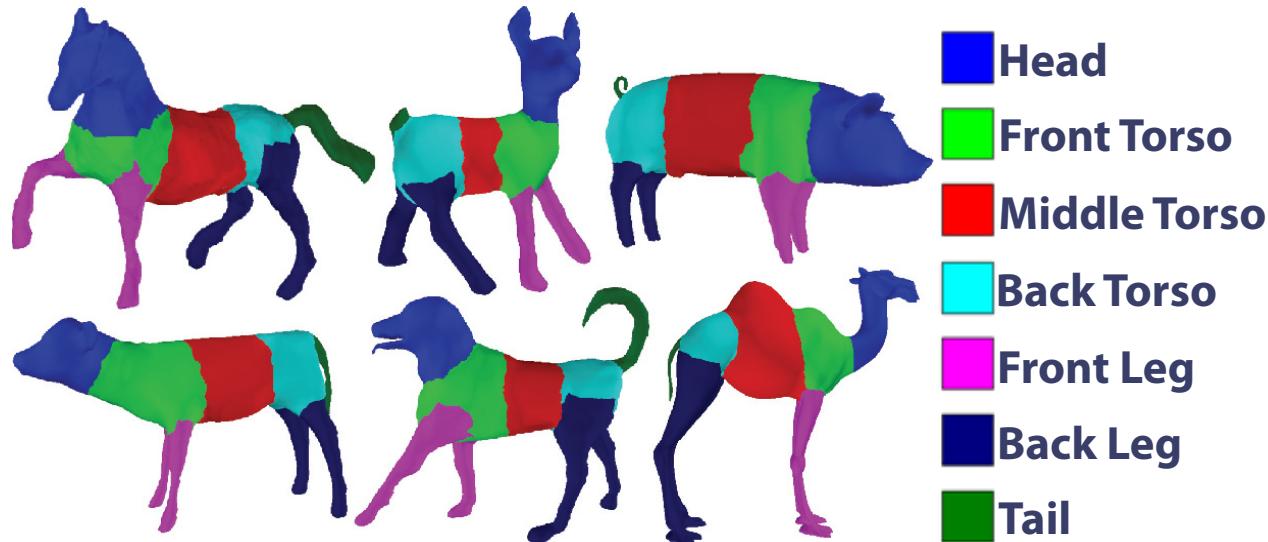


Training Meshes

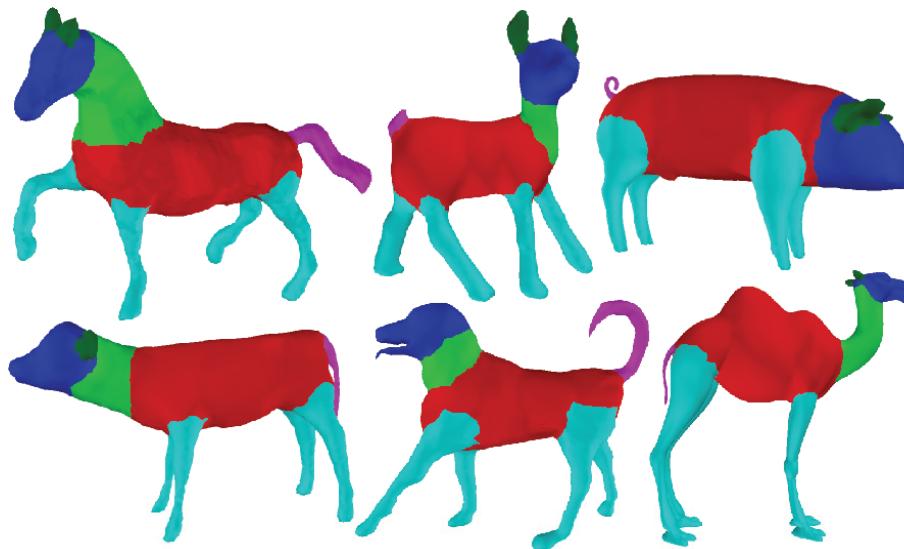
Learning different segmentation styles



Training Meshes

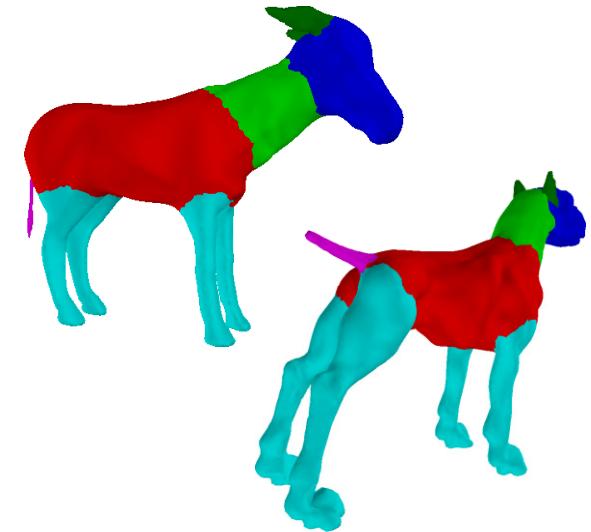


Learning different segmentation styles

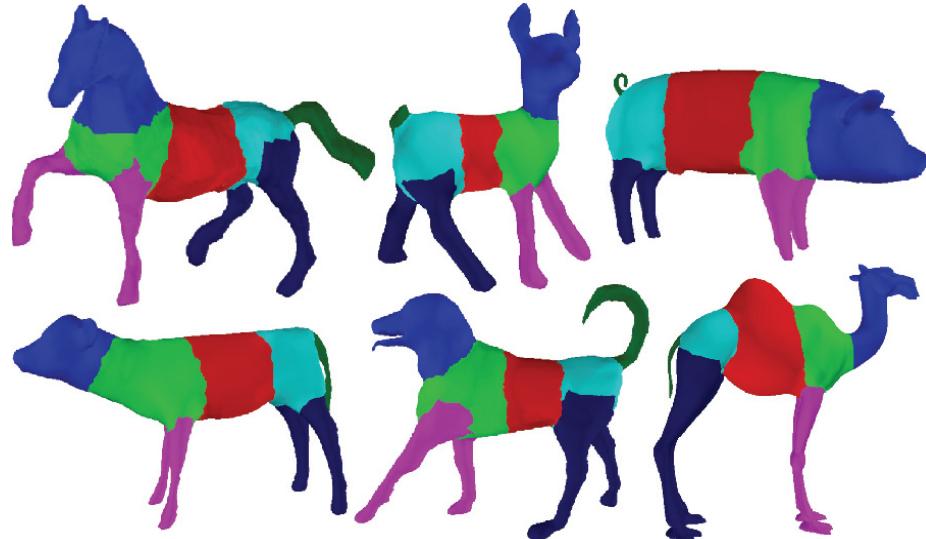


Training Meshes

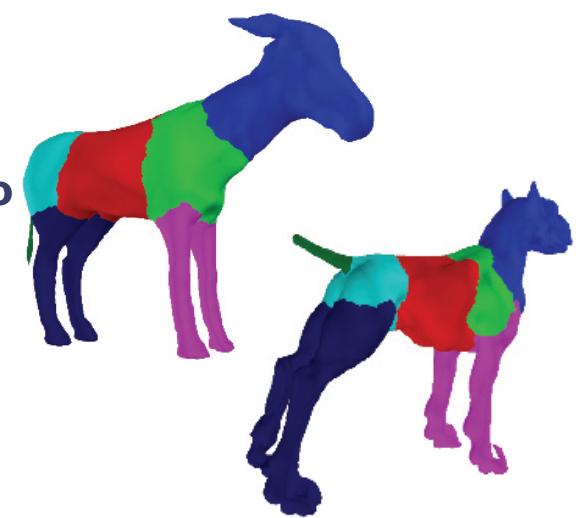
- █ Head
- █ Neck
- █ Torso
- █ Leg
- █ Tail
- █ Ear



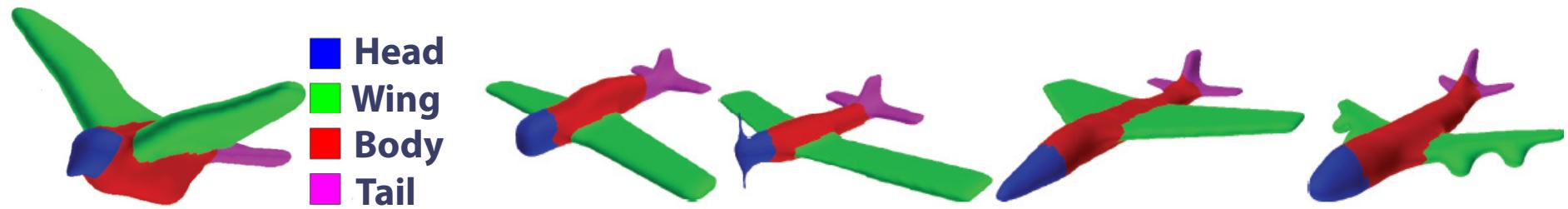
Test Meshes



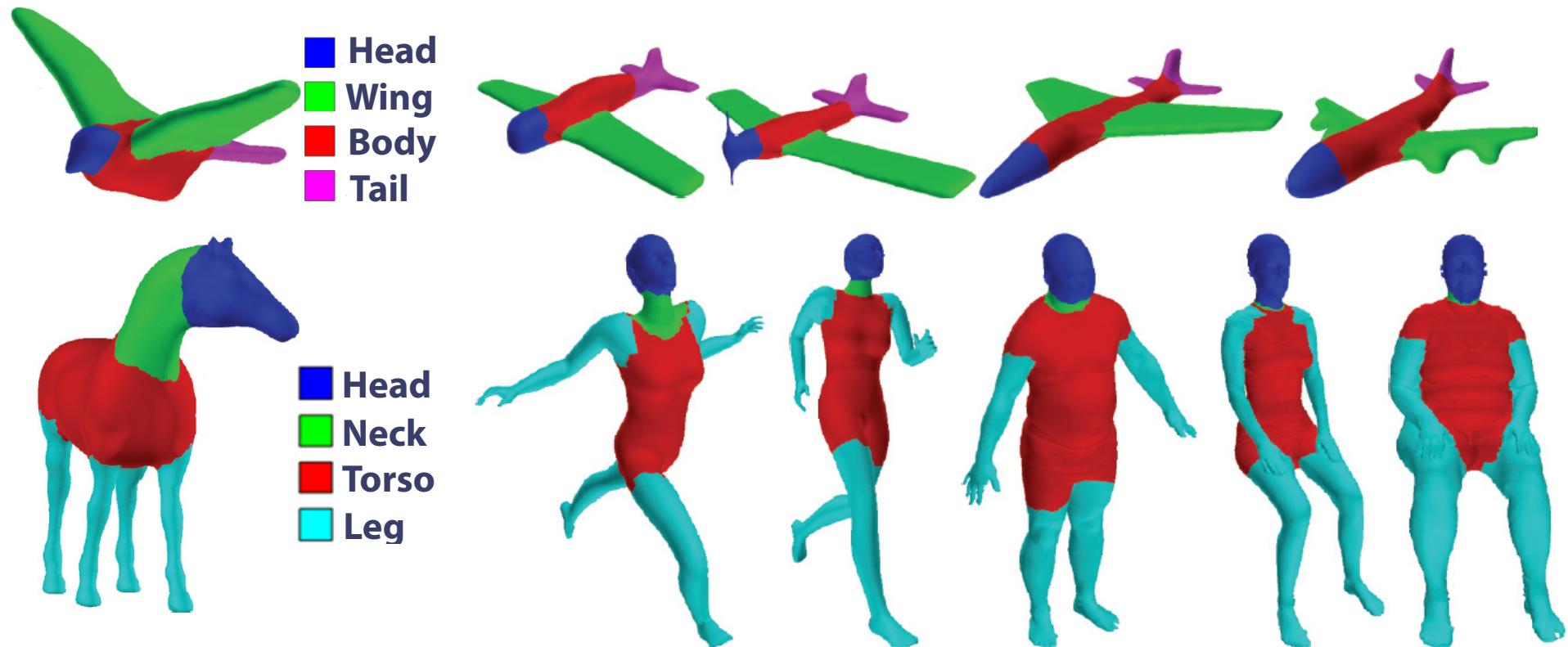
- █ Head
- █ Front Torso
- █ Middle Torso
- █ Back Torso
- █ Front Leg
- █ Back Leg
- █ Tail



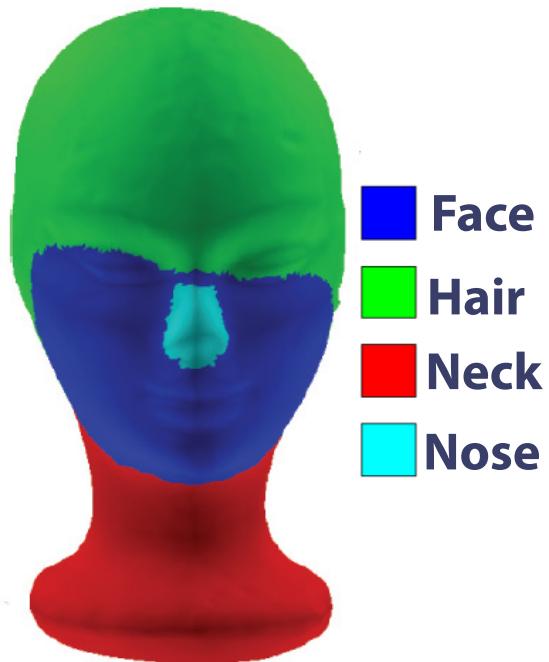
Generalization to different categories



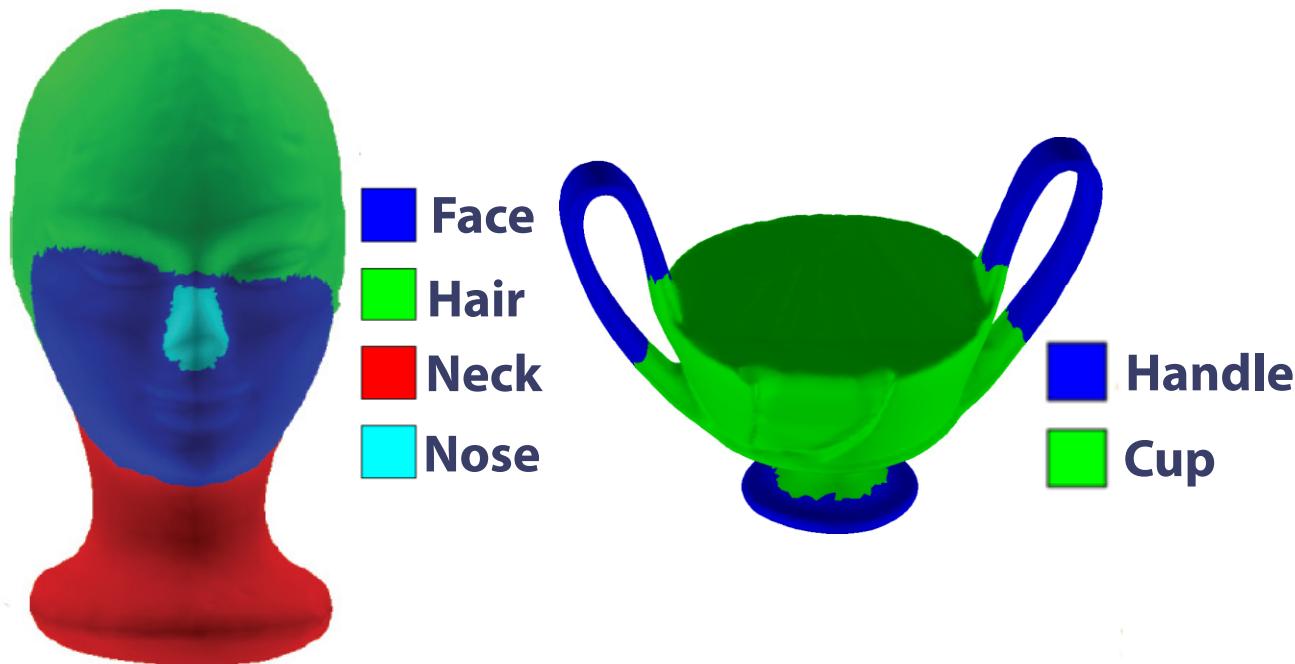
Generalization to different categories



Failure cases



Failure cases

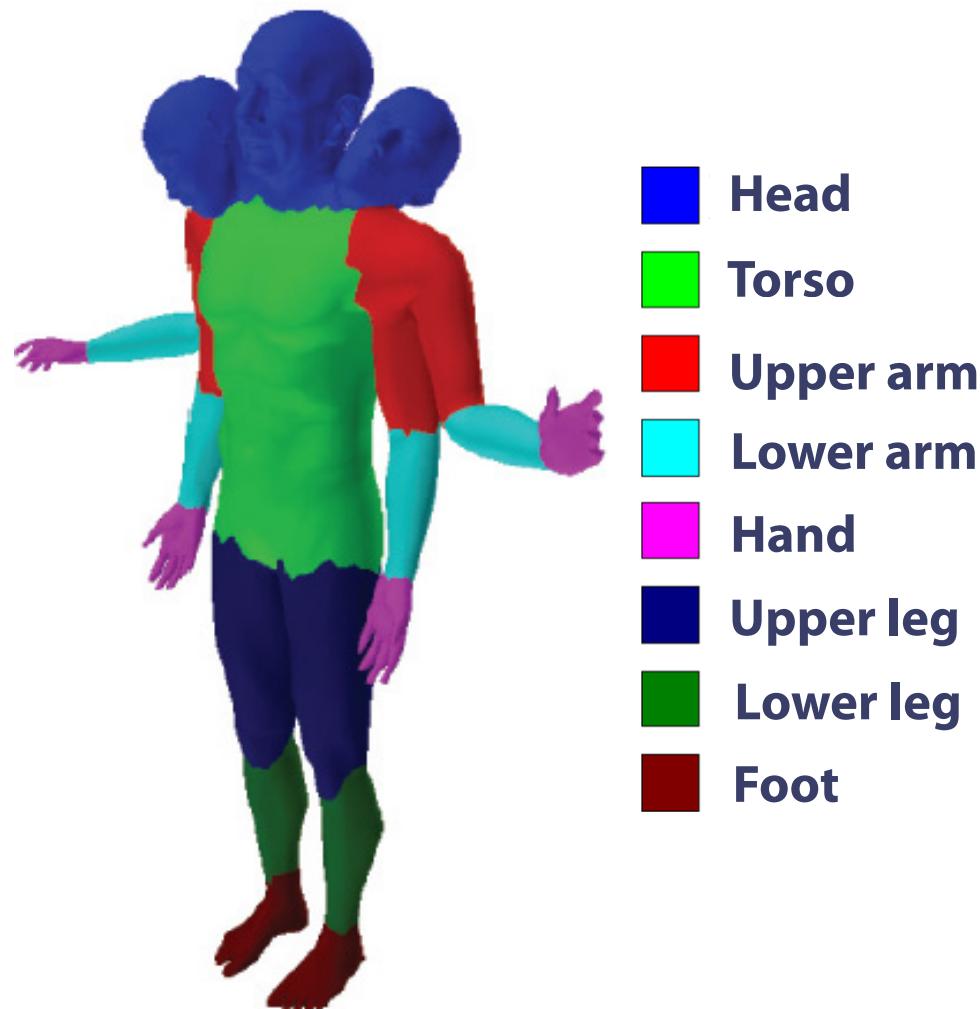


Failure cases



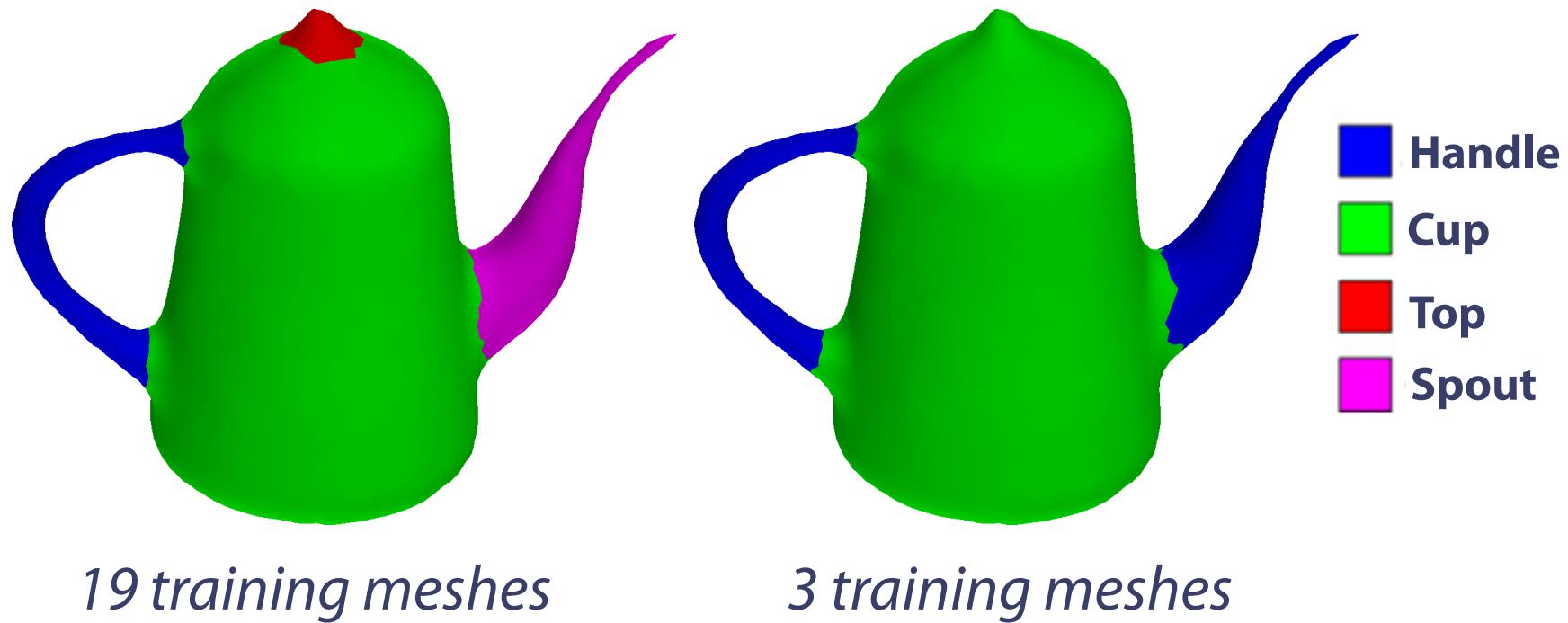
Limitations

Adjacent segments with the same label are merged



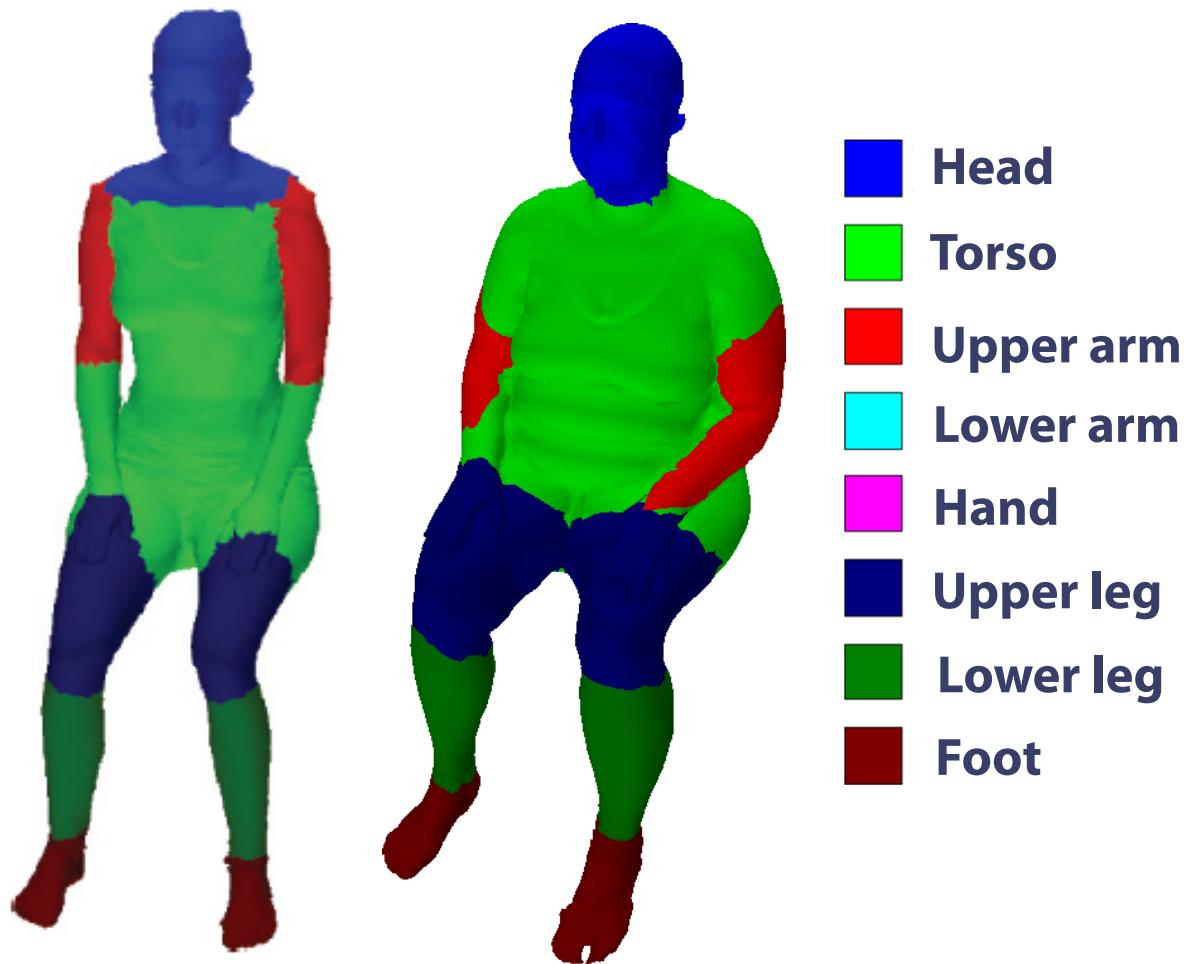
Limitations

Results depend on having sufficient training data

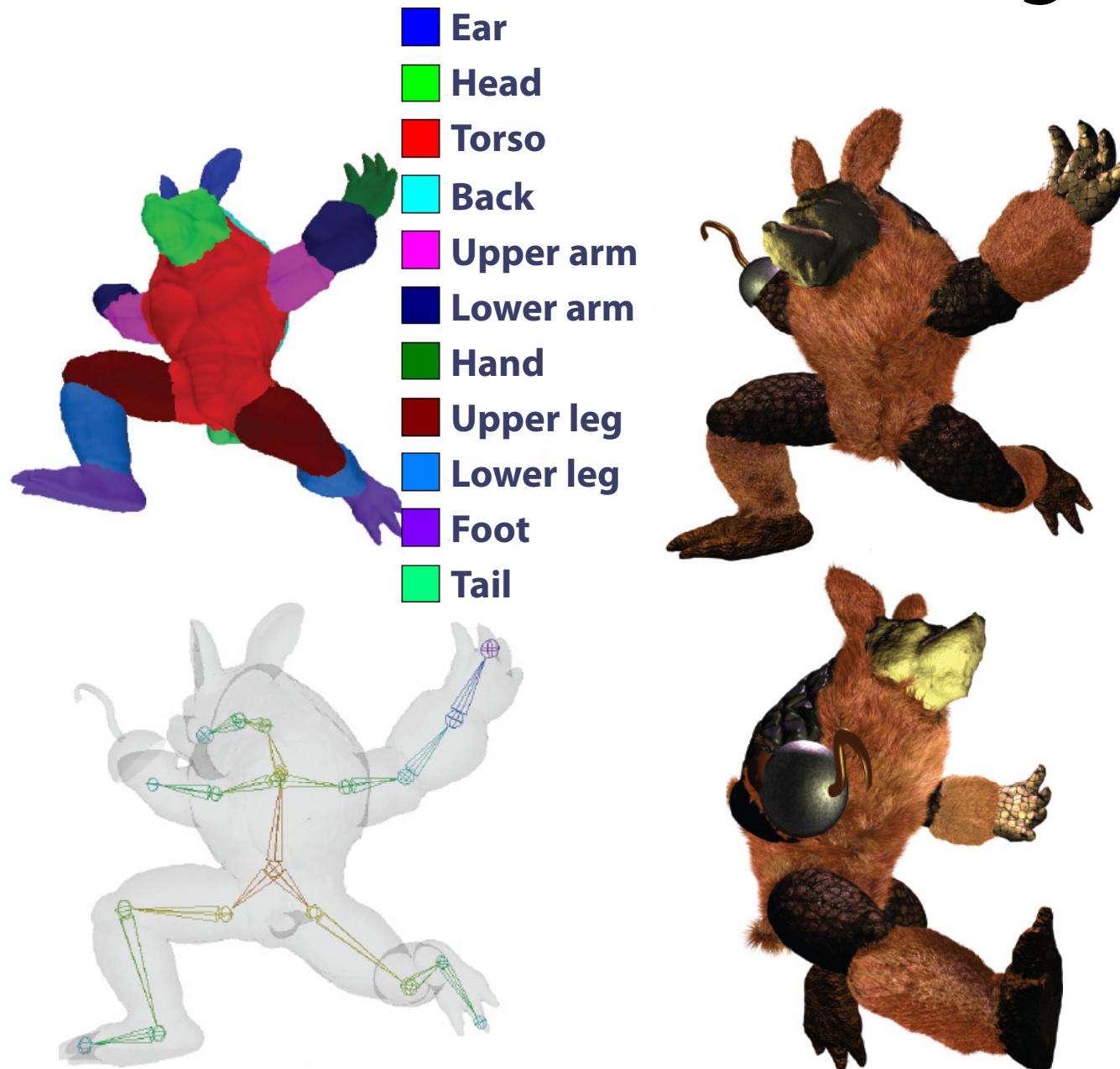


Limitations

Many features are sensitive to topology



Applications: Character Texturing, Rigging



Summary

- Use prior knowledge for 3D mesh segmentation and labeling

Summary

- Use prior knowledge for 3D mesh segmentation and labeling
- Based on a Conditional Random Field model

Summary

- Use prior knowledge for 3D mesh segmentation and labeling
- Based on a Conditional Random Field model
- Parameters are learned from examples

Summary

- Use prior knowledge for 3D mesh segmentation and labeling
- Based on a Conditional Random Field model
- Parameters are learned from examples
- Applicable to a broad range of meshes

Summary

- Use prior knowledge for 3D mesh segmentation and labeling
- Based on a Conditional Random Field model
- Parameters are learned from examples
- Applicable to a broad range of meshes
- Significant improvements over the state-of-the-art

Thank you!

Acknowledgements: Xiaobai Chen, Aleksey Golovinskiy, Thomas Funkhouser, Szymon Rusinkiewicz , Olga Veksler, Daniela Giorgi, AIM@SHAPE, David Fleet, Olga Vesselova, John Hancock

Our project web page:

<http://www.dgp.toronto.edu/~kalo/papers/LabelMeshes/>

